Probabilistic Circuits

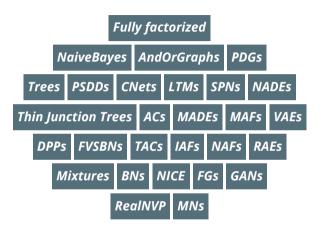
Inference
Representations
Learning
Theory

Antonio Vergari University of California, Los Angeles

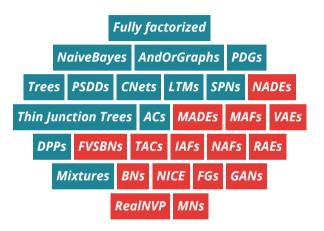
Robert Peharz

YooJung ChoiUniversity of California. Los Angeles

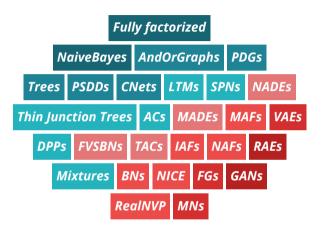
Guy Van den Broeck University of California, Los Angeles



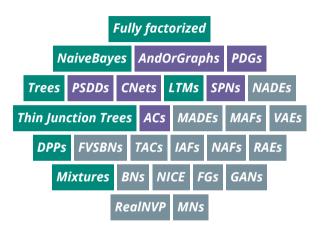
The Alphabet Soup of probabilistic models



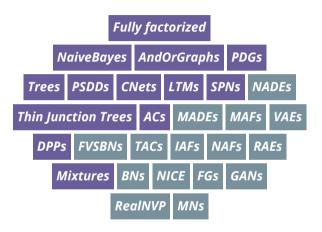
Intractable and tractable models



tractability is a spectrum



Expressive models without compromises



a unifying framework for tractable models

or expressiveness vs tractability

or expressiveness vs tractability

Probabilistic circuits

a unified framework for tractable probabilistic modeling

or expressiveness vs tractability

Probabilistic circuits

a unified framework for tractable probabilistic modeling

Learning circuits

learning their structure and parameters from data

or expressiveness vs tractability

Probabilistic circuits

a unified framework for tractable probabilistic modeling

Learning circuits

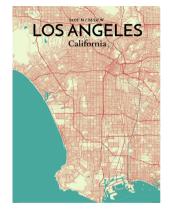
learning their structure and parameters from data

Advanced representations

tracing the boundaries of tractability and connections to other formalisms

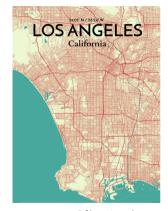
or the inherent trade-off of tractability vs. expressiveness

q₁: What is the probability that today is a Monday and there is a traffic jam on Westwood Blvd.?



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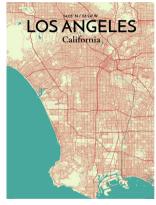
- **q**₁: What is the probability that today is a Monday and there is a traffic jam on Westwood Blvd.?
- **q**₂: Which day is most likely to have a traffic jam on my route to campus?



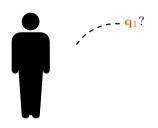
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- **q**₁: What is the probability that today is a Monday and there is a traffic jam on Westwood Blvd.?
- **q**₂: Which day is most likely to have a traffic jam on my route to campus?

How to answer several of these *probabilistic queries?*

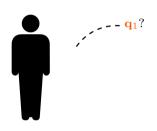


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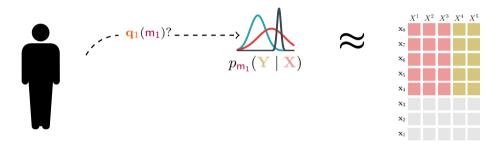


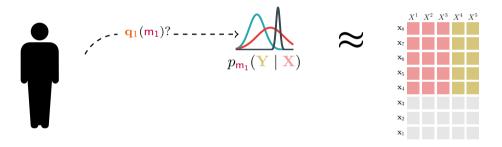
answering queries...



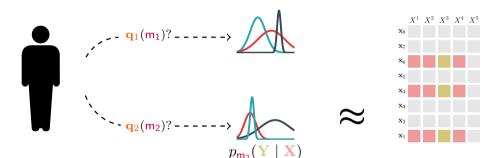
	X^1	X^2	X^3	X^4	X^5
\mathbf{x}_8					
\mathbf{x}_7					
\mathbf{x}_6					
\mathbf{x}_5					
\mathbf{x}_4					
\mathbf{x}_3					
\mathbf{x}_2					
\mathbf{x}_1					

answering queries...

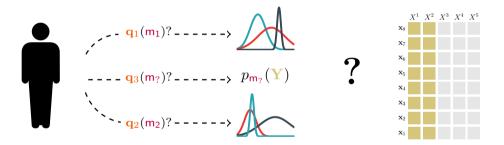


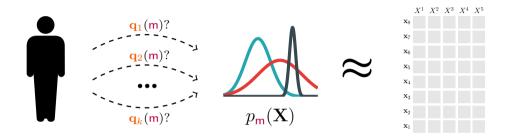


"What is the most likely time to see a traffic jam at Sunset Blvd.?"

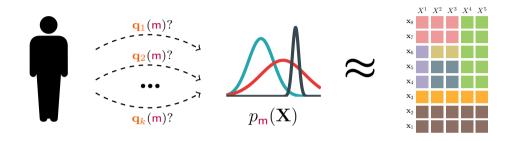


"What is the probability of a traffic jam on Westwood Blvd. on Monday?"



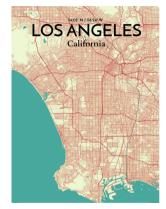


...by fitting generative models!



...e.g. exploratory data analysis

q₁: What is the probability that today is a Monday and there is a traffic jam on Westwood Blvd.?

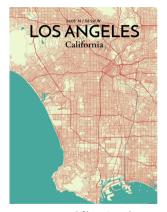


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q₁: What is the probability that today is a Monday and there is a traffic jam on Westwood Blvd.?

$$\mathbf{X} = \{\mathsf{Day}, \mathsf{Time}, \mathsf{Jam}_{\mathsf{Str1}}, \mathsf{Jam}_{\mathsf{Str2}}, \dots, \mathsf{Jam}_{\mathsf{StrN}}\}$$

$$\mathbf{q}_1(\mathbf{m}) = p_{\mathbf{m}}(\mathsf{Day} = \mathsf{Mon}, \mathsf{Jam}_{\mathsf{Wwood}} = 1)$$



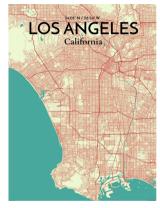
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$$\mathbf{q_1}(\mathbf{m}) = p_{\mathbf{m}}(\mathsf{Day} = \mathsf{Mon}, \mathsf{Jam}_{\mathsf{Wwood}} = 1)$$

→ marginals

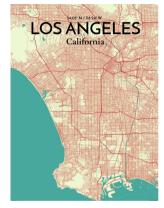


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q₂: Which day is most likely to have a traffic jam on my route to campus?

$$\mathbf{X} = \{\mathsf{Day}, \mathsf{Time}, \mathsf{Jam}_{\mathsf{Str1}}, \mathsf{Jam}_{\mathsf{Str2}}, \dots, \mathsf{Jam}_{\mathsf{StrN}}\}$$

$$\mathbf{q}_2(\mathbf{m}) = \operatorname{argmax}_{\mathsf{d}} p_{\mathbf{m}}(\mathsf{Day} = \mathsf{d} \wedge \bigvee_{i \in \mathsf{route}} \mathsf{Jam}_{\mathsf{St}ri})$$

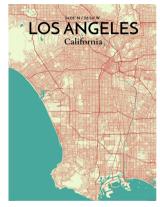


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A class of queries \mathcal{Q} is tractable on a family of probabilistic models \mathcal{M} iff for any query $\mathbf{q} \in \mathcal{Q}$ and model $\mathbf{m} \in \mathcal{M}$ exactly computing $\mathbf{q}(\mathbf{m})$ runs in time $O(\mathsf{poly}(|\mathbf{m}|))$.

A class of queries $\mathcal Q$ is tractable on a family of probabilistic models $\mathcal M$ iff for any query $\mathbf q \in \mathcal Q$ and model $\mathbf m \in \mathcal M$ exactly computing $\mathbf q(\mathbf m)$ runs in time $O(\mathsf{poly}(|\mathbf m|))$.

⇒ often poly will in fact be **linear**!

A class of queries $\mathcal Q$ is tractable on a family of probabilistic models $\mathcal M$ iff for any query $\mathbf q \in \mathcal Q$ and model $\mathbf m \in \mathcal M$ exactly computing $\mathbf q(\mathbf m)$ runs in time $O(\mathsf{poly}(|\mathbf m|))$.

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\Longrightarrow often poly will in fact be linear! \Longrightarrow Note: if \mathcal M is compact in the number of random variables \mathbf X, that is, |\mathbf m|\in O(\operatorname{poly}(|\mathbf X|)), then query time is O(\operatorname{poly}(|\mathbf X|)).
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A class of queries $\mathcal Q$ is tractable on a family of probabilistic models $\mathcal M$ iff for any query $\mathbf q \in \mathcal Q$ and model $\mathbf m \in \mathcal M$ exactly computing $\mathbf q(\mathbf m)$ runs in time $O(\mathsf{poly}(|\mathbf m|))$.

```
\Rightarrow often poly will in fact be linear! \Rightarrow Note: if \mathcal{M} is compact in the number of random variables \mathbf{X}, that is, |\mathbf{m}| \in O(\mathsf{poly}(|\mathbf{X}|)), then query time is O(\mathsf{poly}(|\mathbf{X}|)). \Rightarrow Why exactness? Highest guarantee possible!
```

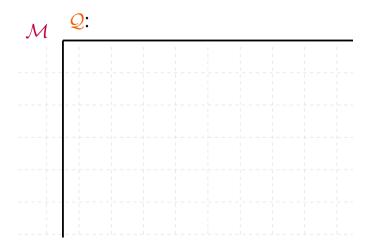
Stay tuned for

Nexa

- 1. What are classes of queries?
- 2. Are my favorite models tractable?
- 3. Are tractable models expressive?

Afters

We introduce **probabilistic circuits** as a unified framework for tractable probabilistic modeling



tractable bands

Complete evidence (EVI)

q₃: What is the probability that today is a Monday at 12.00 and there is a traffic jam only on Westwood Blvd.?



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Complete evidence (EVI)

q₃: What is the probability that today is a Monday at 12.00 and there is a traffic jam only on Westwood Blvd.?

$$\mathbf{X} = \{\mathsf{Day}, \mathsf{Time}, \mathsf{Jam}_{\mathsf{Wwood}} \,, \mathsf{Jam}_{\mathsf{Str2}}, \dots, \mathsf{Jam}_{\mathsf{StrN}}\}$$

$$\mathbf{q_3}(\mathbf{m}) = p_{\mathbf{m}}(\mathbf{X} = \{\mathsf{Mon}, 12.00, 1, 0, \dots, 0\})$$



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Complete evidence (EVI)

q₃: What is the probability that today is a Monday at 12.00 and there is a traffic jam only on Westwood Blvd.?

$$\mathbf{X} = \{\mathsf{Day}, \mathsf{Time}, \mathsf{Jam}_{\mathsf{Wwood}} \,, \mathsf{Jam}_{\mathsf{Str2}}, \dots, \mathsf{Jam}_{\mathsf{StrN}}\}$$

$$\mathbf{q_3}(\mathbf{m}) = p_{\mathbf{m}}(\mathbf{X} = \{\mathsf{Mon}, 12.00, 1, 0, \dots, 0\})$$

...fundamental in *maximum likelihood learning*

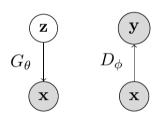
$$\theta_{\mathbf{m}}^{\mathsf{MLE}} = \operatorname{argmax}_{\theta} \prod_{\mathbf{x} \in \mathcal{D}} p_{\mathbf{m}}(\mathbf{x}; \theta)$$



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Generative Adversarial Networks

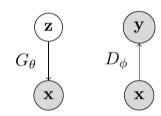
 $\min_{\theta} \max_{\phi} \mathbb{E}_{\mathbf{x} \sim p_{\mathsf{data}}(\mathbf{x})} \left[\log D_{\phi}(\mathbf{x}) \right] + \mathbb{E}_{\mathbf{z} \sim p(\mathbf{z})} \left[\log (1 - D_{\phi}(G_{\theta}(\mathbf{z}))) \right]$

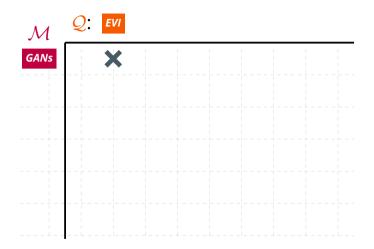


Generative Adversarial Networks

$$\min_{\theta} \max_{\phi} \mathbb{E}_{\mathbf{x} \sim p_{\mathsf{data}}(\mathbf{x})} \left[\log D_{\phi}(\mathbf{x}) \right] + \mathbb{E}_{\mathbf{z} \sim p(\mathbf{z})} \left[\log (1 - D_{\phi}(G_{\theta}(\mathbf{z}))) \right]$$

- no explicit likelihood!
 - ⇒ adversarial training instead of MLE
 - → no tractable EVI
- good sample quality
 - ⇒ but lots of samples needed for MC
- unstable training ⇒ mode collapse



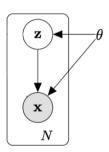


tractable bands

Variational Autoencoders

$$p_{\theta}(\mathbf{x}) = \int p_{\theta}(\mathbf{x} \mid \mathbf{z}) p(\mathbf{z}) d\mathbf{z}$$

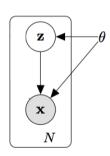
an explicit likelihood model!

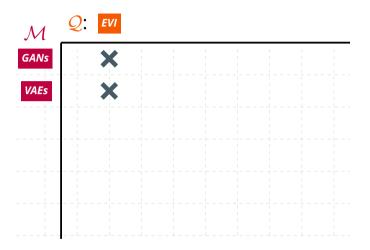


Variational Autoencoders

$$\log p_{\theta}(\mathbf{x}) \ge \mathbb{E}_{\mathbf{z} \sim q_{\phi}(\mathbf{z} \mid \mathbf{x})} \left[\log p_{\theta}(\mathbf{x} \mid \mathbf{z}) \right] - \mathbb{KL} (q_{\phi}(\mathbf{z} \mid \mathbf{x}) || p(\mathbf{z}))$$

- an explicit likelihood model!
- lacksquare ... but computing $\log p_{ heta}(\mathbf{x})$ is intractable
 - ⇒ an infinite and uncountable mixture
 ⇒ no tractable FVI
- we need to optimize the ELBO...
 - → which is "tricky" [Alemi et al. 2017; Dai
 et al. 2019; Ghosh et al. 2019]



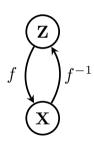


tractable bands

$$p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Z}}(f^{-1}(\mathbf{x})) \left| \det \left(\frac{\delta f^{-1}}{\delta \mathbf{x}} \right) \right|$$

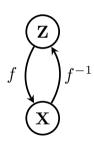
- an explicit likelihood!
- ...plus structured Jacobians

 tractable FVI queries
- many neural variants
 - RealNVP [Dinh et al. 2016], MAF [Papamakarios et al. 2017]
 - MADE [Germain et al. 2015], PixelRNN [Oord et al. 2016]



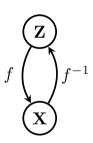
$$p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Z}}(f^{-1}(\mathbf{x})) \left| \det \left(\frac{\delta f^{-1}}{\delta \mathbf{x}} \right) \right|$$

- an explicit likelihood!
- ____ ...plus structured Jacobians
 - → tractable EVI queries!
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 - RealNVP [Dinh et al. 2016], MAF [Papamakarios et al. 2017]
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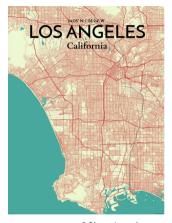


$$p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Z}}(f^{-1}(\mathbf{x})) \left| \det \left(\frac{\delta f^{-1}}{\delta \mathbf{x}} \right) \right|$$

- an explicit likelihood!
- ...plus structured Jacobians⇒ tractable EVI queries!
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 - RealNVP [Dinh et al. 2016],
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q₁: What is the probability that today is a Monday at 42.00 and there is a traffic jam only on Westwood Blvd.?



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q₁: What is the probability that today is a Monday et 42.00 and there is a traffic jam enly on Westwood Blvd.?

$$\mathbf{q_1}(\mathbf{m}) = p_{\mathbf{m}}(\mathsf{Day} = \mathsf{Mon}, \mathsf{Jam}_{\mathsf{Wwood}} \, = 1)$$



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q₁: What is the probability that today is a Monday et 42.00 and there is a traffic jam only on Westwood Blvd.?

$$\mathbf{q_1}(\mathbf{m}) = p_{\mathbf{m}}(\mathsf{Day} = \mathsf{Mon}, \mathsf{Jam}_{\mathsf{Wwood}} = 1)$$

General:
$$p_{\mathbf{m}}(\mathbf{e}) = \int p_{\mathbf{m}}(\mathbf{e}, \mathbf{H}) d\mathbf{H}$$

where
$$\mathbf{E} \subset \mathbf{X}$$
, $\mathbf{H} = \mathbf{X} \setminus \mathbf{E}$



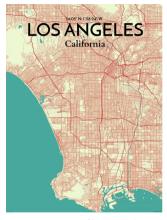
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q₁: What is the probability that today is a Monday et 12:00 and there is a traffic jam only on Westwood Blvd.?

$$\mathbf{q}_1(\mathbf{m}) = p_{\mathbf{m}}(\mathsf{Day} = \mathsf{Mon}, \mathsf{Jam}_{\mathsf{Wwood}} = 1)$$

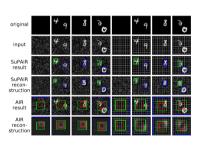
tractable MAR \Longrightarrow tractable **conditional queries** (CON):

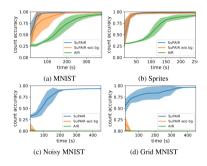
$$p_{\mathbf{m}}(\mathbf{q} \mid \mathbf{e}) = \frac{p_{\mathbf{m}}(\mathbf{q}, \mathbf{e})}{p_{\mathbf{m}}(\mathbf{e})}$$



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Tractable MAR: scene understanding





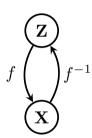
Fast and exact marginalization over unseen or "do not care" parts in the scene

Stelzner et al., "Faster Attend-Infer-Repeat with Tractable Probabilistic Models", 2019
Kossen et al., "Structured Object-Aware Physics Prediction for Video Modeling and Planning", 2019

$$p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Z}}(f^{-1}(\mathbf{x})) \left| \det \left(\frac{\delta f^{-1}}{\delta \mathbf{x}} \right) \right|$$

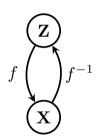
- an explicit likelihood!
- ...plus structured Jacobians

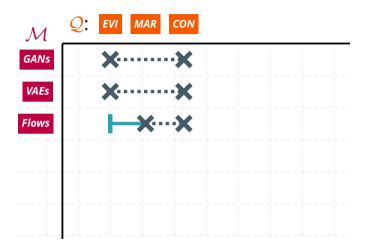
⇒ tractable EVI queries!



$$p_{\mathbf{X}}(\mathbf{x}) = p_{\mathbf{Z}}(f^{-1}(\mathbf{x})) \left| \det \left(\frac{\delta f^{-1}}{\delta \mathbf{x}} \right) \right|$$

- an explicit likelihood!
- ...plus structured Jacobians⇒ tractable EVI queries!
- MAR is generally intractable: we cannot easily integrate over f \implies unless f is "simple", e.g. bijection





tractable bands

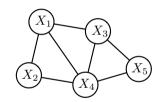
Probabilistic Graphical Models (PGMs)

Declarative semantics: a clean separation of modeling assumptions from inference

Nodes: random variables

Edges: dependencies





Inference:

- conditioning [Darwiche 2001; Sang et al. 2005]
- elimination [Zhang et al. 1994; Dechter 1998]
- message passing [Yedidia et al. 2001; Dechter et al. 2002; Choi et al. 2010; Sontag et al. 2011]

Complexity of MAR on PGMs

Exact complexity: Computing MAR and CON is #P-hard



Approximation complexity: Computing MAR and CON approximately within a relative error of $2^{n^{1-\epsilon}}$ for any fixed ϵ is *NP-hard*

⇒ [Dagum et al. 1993; Roth 1996]

Why? Treewidth!

Treewidth:

Informally, how tree-like is the graphical model **m**? Formally, the minimum width of any tree-decomposition of **m**.

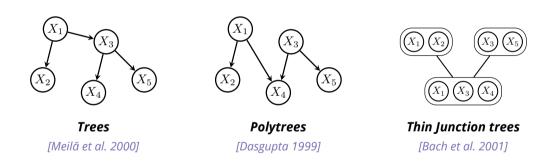
Fixed-parameter tractable: MAR and CON on a graphical model ${\bf m}$ with treewidth w take time $O(|{\bf X}|\cdot 2^w)$, which is linear for fixed width w

[Dechter 1998; Koller et al. 2009].



what about bounding the treewidth by design?

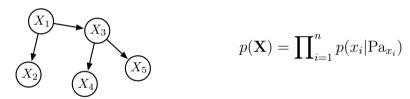
Low-treewidth PGMs



If treewidth is bounded (e.g. $\approxeq 20$), exact MAR and CON inference is possible in practice

Tree distributions

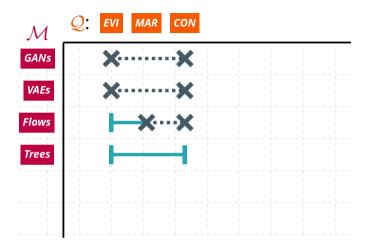
A **tree-structured BN** [Meilă et al. 2000] where each $X_i \in \mathbf{X}$ has at most one parent Pa_{X_i} .



Exact querying: EVI, MAR, CON tasks *linear* for trees: $O(|\mathbf{X}|)$

Exact learning from d examples takes $O(|\mathbf{X}|^2 \cdot d)$ with the classical Chow-Liu algorithm¹

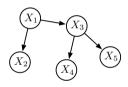
¹Chow et al., "Approximating discrete probability distributions with dependence trees", 1968



tractable bands

What do we lose?

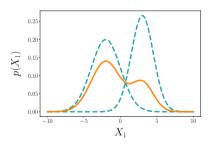
Expressiveness: Ability to represent rich and complex classes of distributions



Bounded-treewidth PGMs lose the ability to represent all possible distributions ...

Mixtures

Mixtures as a convex combination of k (simpler) probabilistic models

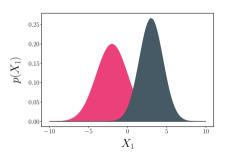


$$p(X) = w_1 \cdot p_1(X) + w_2 \cdot p_2(X)$$

EVI, MAR, CON queries scale linearly in \boldsymbol{k}

Mixtures

Mixtures as a convex combination of k (simpler) probabilistic models



$$p(X) = p(Z = 1) \cdot p_1(X|Z = 1)$$

$$+ p(Z = 2) \cdot p_2(X|Z = 2)$$

Mixtures are marginalizing a *categorical latent variable* Z with k values

Expressiveness and efficiency

Expressiveness: Ability to represent rich and effective classes of functions



mixture of Gaussians can approximate any distribution!

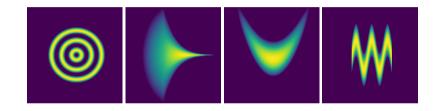
Expressiveness and efficiency

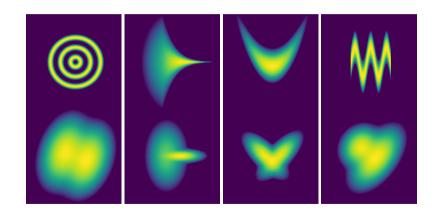
Expressiveness: Ability to represent rich and effective classes of functions

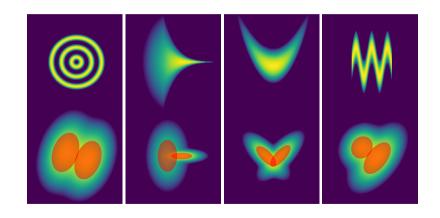
⇒ mixture of Gaussians can approximate any distribution!

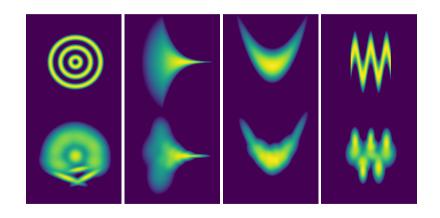
Expressive efficiency (succinctness) Ability to represent rich and effective classes of functions **compactly**

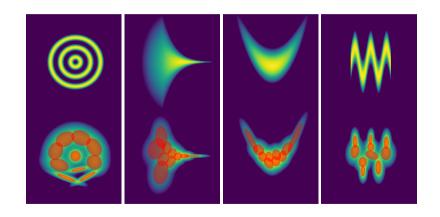
but how many components does a Gaussian mixture need?

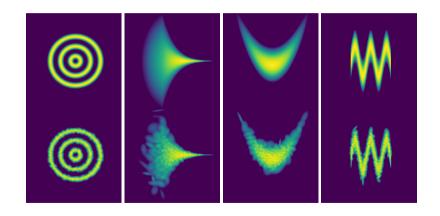


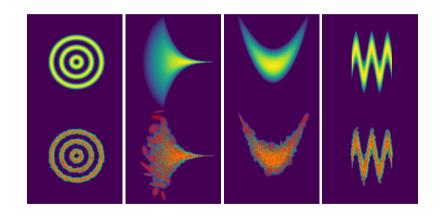


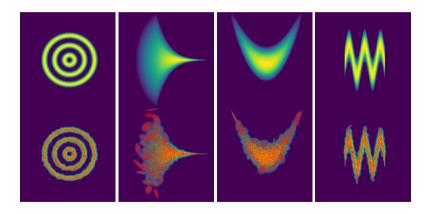




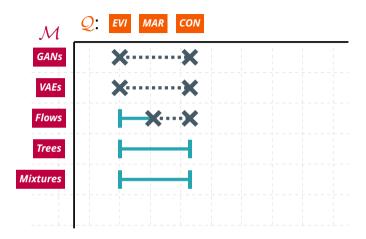












tractable bands

aka Most Probable Explanation (MPE)

q₅: Which combination of roads is most likely to be jammed on Monday at 9am?



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aka Most Probable Explanation (MPE)

q₅: Which combination of roads is most likely to be jammed on Monday at 9am?

$$\mathbf{q}_{5}(\mathbf{m}) = \operatorname{argmax}_{\mathbf{j}} p_{\mathbf{m}}(\mathbf{j}_{1}, \mathbf{j}_{2}, \dots \mid \mathsf{Day} = \mathsf{M}, \mathsf{Time} = 9)$$



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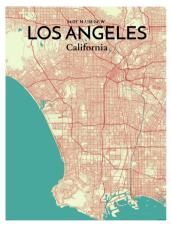
aka Most Probable Explanation (MPE)

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General: $\operatorname{argmax}_{\mathbf{q}} p_{\mathbf{m}}(\mathbf{q} \mid \mathbf{e})$

where
$$\mathbf{Q} \cup \mathbf{E} = \mathbf{X}$$



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aka Most Probable Explanation (MPE)

q₅: Which combination of roads is most likely to be jammed on Monday at 9am?

...intractable for latent variable models!

$$\begin{split} \max_{\mathbf{q}} p_{\mathbf{m}}(\mathbf{q} \mid \mathbf{e}) &= \max_{\mathbf{q}} \sum_{\mathbf{z}} p_{\mathbf{m}}(\mathbf{q}, \mathbf{z} \mid \mathbf{e}) \\ &\neq \sum_{\mathbf{z}} \max_{\mathbf{q}} p_{\mathbf{m}}(\mathbf{q}, \mathbf{z} \mid \mathbf{e}) \end{split}$$



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MAP inference: image inpainting



Original

Covered

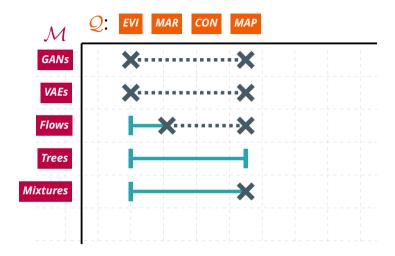
BACK-ORIG

 $_{\mathrm{SUM}}$

BACK-MPE

Predicting *arbitrary patches* given a *single* model without the need of retraining.

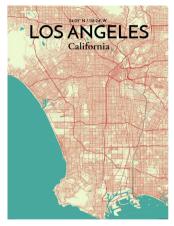
Poon and Domingos, "Sum-Product Networks: a New Deep Architecture", 2011 Sguerra and Cozman, "Image classification using sum-product networks for autonomous flight of micro aerial vehicles". 2016



tractable bands

aka Bayesian Network MAP

q₆: Which combination of roads is most likely to be jammed on Monday at 9am?

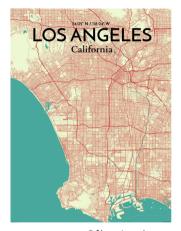


© fineartamerica.com

aka Bayesian Network MAP

q₆: Which combination of roads is most likely to be jammed on Monday at 9am?

$$\mathbf{q}_{6}(\mathbf{m}) = \operatorname{argmax}_{\mathbf{j}} p_{\mathbf{m}}(\mathbf{j}_{1}, \mathbf{j}_{2}, \dots \mid \mathsf{Time} = 9)$$



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aka Bayesian Network MAP

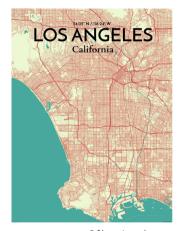
q₆: Which combination of roads is most likely to be jammed on Monday at 9am?

$$\mathbf{q}_6(\mathbf{m}) = \operatorname{argmax}_{\mathbf{j}} \ p_{\mathbf{m}}(\mathbf{j}_1, \mathbf{j}_2, \dots \mid \mathsf{Time} = 9)$$

General:
$$\operatorname{argmax}_{\mathbf{q}} \ p_{\mathbf{m}}(\mathbf{q} \mid \mathbf{e})$$

$$= \operatorname{argmax}_{\mathbf{q}} \ \sum_{\mathbf{h}} p_{\mathbf{m}}(\mathbf{q}, \mathbf{h} \mid \mathbf{e})$$

where
$$\mathbf{Q} \cup \mathbf{H} \cup \mathbf{E} = \mathbf{X}$$



© fineartamerica.com

aka Bayesian Network MAP

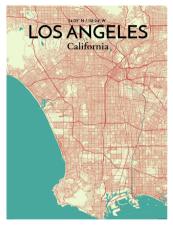
q₆: Which combination of roads is most likely to be jammed on Monday at 9am?

$$\mathbf{q}_6(\mathbf{m}) = \operatorname{argmax}_{\mathbf{j}} \ p_{\mathbf{m}}(\mathbf{j}_1, \mathbf{j}_2, \dots \mid \mathsf{Time} = 9)$$

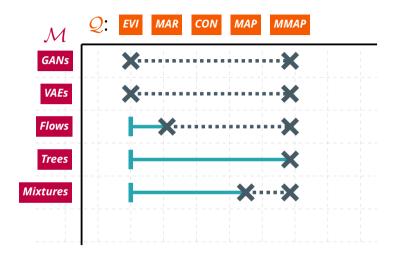
 \Rightarrow NP^{PP}-complete [Park et al. 2006]

⇒ NP-hard for trees [de Campos 2011]

→ NP-hard even for Naive Bayes [ibid.]

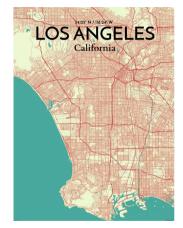


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tractable bands

q₂: Which day is most likely to have a traffic jam on my route to campus?

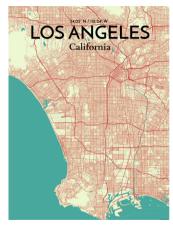


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q₂: Which day is most likely to have a traffic jam on my route to campus?

$$\mathbf{q}_2(\mathbf{m}) = \operatorname{argmax}_{\mathsf{d}} p_{\mathbf{m}}(\mathsf{Day} = \mathsf{d} \wedge \bigvee_{i \in \mathsf{route}} \mathsf{Jam}_{\mathsf{Str}\,i})$$

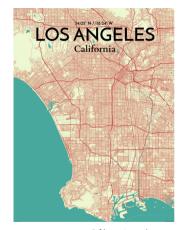
marginals + MAP + logical events



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q₂: Which day is most likely to have a traffic jam on my route to campus?

q₇: What is the probability of seeing more traffic jams in Westwood than Hollywood?

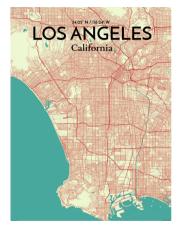


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q₂: Which day is most likely to have a traffic jam on my route to campus?

q₇: What is the probability of seeing more traffic jams in Westwood than Hollywood?

counts + group comparison



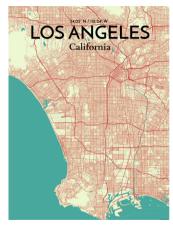
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q₂: Which day is most likely to have a traffic jam on my route to campus?

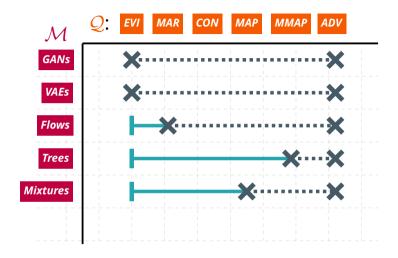
q₇: What is the probability of seeing more traffic jams in Westwood than Hollywood?

and more:

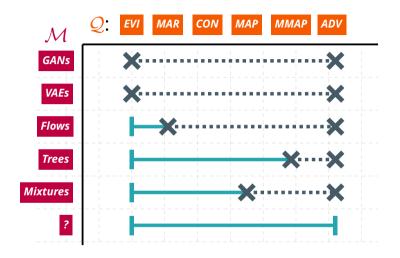
- expected classification agreement [Oztok et al. 2016; Choi et al. 2017, 2018]
- expected predictions [Khosravi et al. 2019c]



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tractable bands



tractable bands

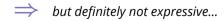
Fully factorized models

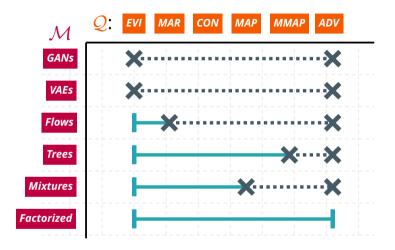
A completely disconnected graph. Example: Product of Bernoullis (PoBs)

$$\begin{array}{ccc}
\widehat{X_1} & \widehat{X_3} & & & \\
\widehat{X_2} & \widehat{X_4} & & & \\
\widehat{X_5} & & & & \\
\end{array}$$

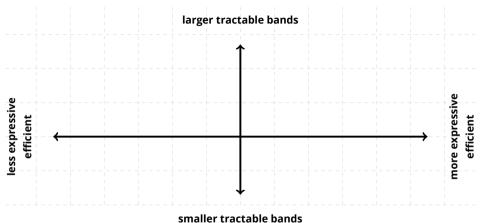
$$p(\mathbf{x}) = \prod_{i=1}^n p(x_i)$$

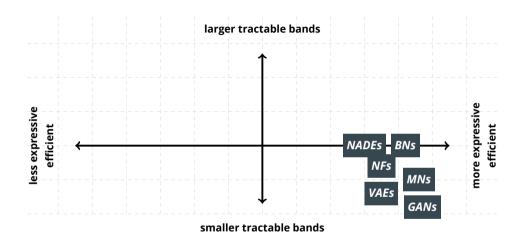
Complete evidence, marginals and MAP, MMAP inference is *linear*!



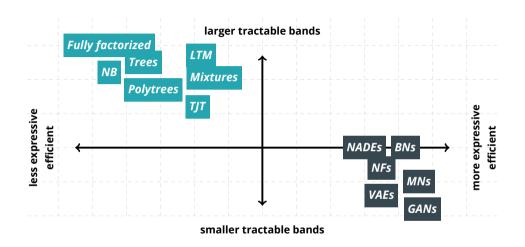


tractable bands

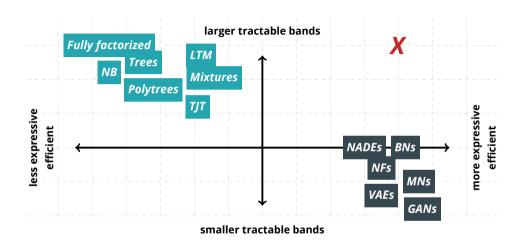




Expressive models are not very tractable...



and tractable ones are not very expressive...



probabilistic circuits are at the "sweet spot"

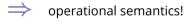
Probabilistic Circuits

Probabilistic circuits

A probabilistic circuit $\mathcal C$ over variables $\mathbf X$ is a computational graph encoding a (possibly unnormalized) probability distribution $p(\mathbf X)$

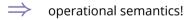
Probabilistic circuits

A probabilistic circuit $\mathcal C$ over variables $\mathbf X$ is a computational graph encoding a (possibly unnormalized) probability distribution $p(\mathbf X)$



Probabilistic circuits

A probabilistic circuit ${\cal C}$ over variables ${\bf X}$ is a computational graph encoding a (possibly unnormalized) probability distribution $p({\bf X})$



by constraining the graph we can guarantee tractable inference...

Stay tuned for...

Next

- 1. What are the building blocks of probabilistic circuits?
 - → How to build a tractable computational graph?
- 2. For which queries are probabilistic circuits tractable?
 - ⇒ tractable classes induced by structural properties



How can probabilistic circuits be learned?



Base case: a single node encoding a distribution

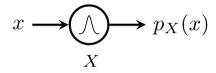


⇒ e.g., Gaussian PDF continuous random variable



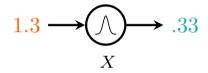
Base case: a single node encoding a distribution

 \Rightarrow e.g., indicators for X or $\neg X$ for Boolean random variable



Simple distributions are tractable "black boxes" for:

- lacksquare EVI: output $p(\mathbf{x})$ (density or mass)
- lacksquare MAR: output 1 (normalized) or Z (unnormalized)
- MAP: output the mode



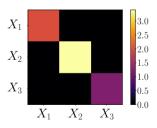
Simple distributions are tractable "black boxes" for:

- **EVI**: output $p(\mathbf{x})$ (density or mass)
- lacksquare MAR: output 1 (normalized) or Z (unnormalized)
- MAP: output the mode

Factorizations

Divide and conquer complexity

$$p(X_1, X_2, X_3) = p(X_1) \cdot p(X_2) \cdot p(X_3)$$

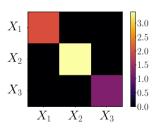


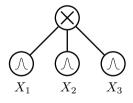
e.g. modeling a multivariate Gaussian with diagonal covariance matrix...

Factorizations are product nodes

Divide and conquer complexity

$$p(X_1, X_2, X_3) = p(X_1) \cdot p(X_2) \cdot p(X_3)$$



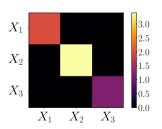


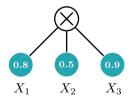
...with a product node over some univariate Gaussian distribution

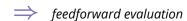
Factorizations are product nodes

Divide and conquer complexity

$$p(x_1, x_2, x_3) = p(x_1) \cdot p(x_2) \cdot p(x_3)$$



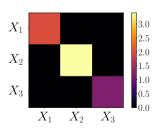


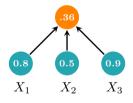


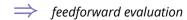
Factorizations are product nodes

Divide and conquer complexity

$$p(x_1, x_2, x_3) = p(x_1) \cdot p(x_2) \cdot p(x_3)$$

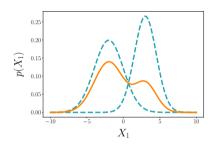






Mixtures

Enhance expressiveness

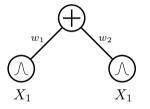


$$p(X) = w_1 \cdot p_1(X) + w_2 \cdot p_2(X)$$

⇒ e.g. modeling a mixture of Gaussians...

Mixtures are sum nodes

Enhance expressiveness



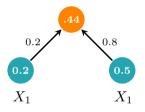
$$p(x) = 0.2 \cdot p_1(x) + 0.8 \cdot p_2(x)$$



⇒ ...as a weighted sum node over Gaussian input distributions

Mixtures are sum nodes

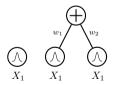
Enhance expressiveness

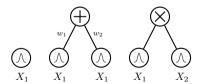


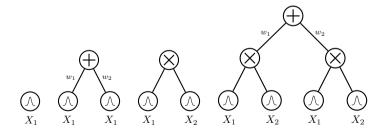
$$p(x) = 0.2 \cdot p_1(x) + 0.8 \cdot p_2(x)$$

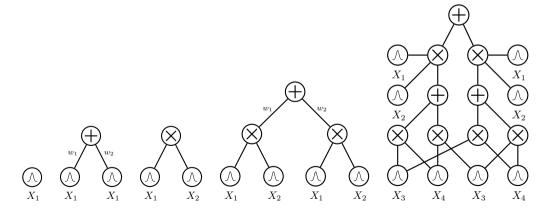
by **stacking** them we increase expressive efficiency











Building PCs in Python with SPFlow



Gaussian(mean=0.0, stdev=0.1, scope=1) *
Categorical(p=[0.4, 0.6], scope=2))

import spn.structure.leaves.parametric.Parametric as param

+ 0.6 * (Categorical(p=[0.2, 0.8], scope=0) *

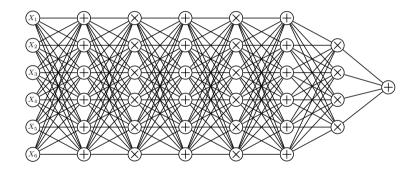
Molina et al., "SPFlow: An easy and extensible library for deep probabilistic learning using sum-product networks", 2019

Probabilistic circuits are not PGMs!

They are *probabilistic* and *graphical*, however ...

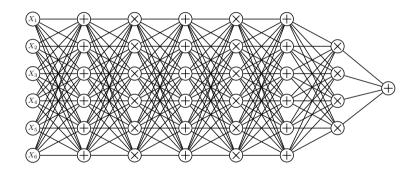
	PGMs	Circuits
Nodes:	random variables	unit of computations
Edges:	dependencies	order of execution
Inference:	conditioning	feedforward pass
	elimination	backward pass
	message passing	
	⇒ they are compute	a tional graphs , more like neural ne

Just sum, products and distributions?



just arbitrarily compose them like a neural network!

Just sum, products and distributions?



just arbitrarily compose them like a neural network



structural constraints needed for tractability

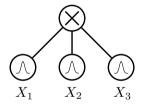
Which structural constraints

ensure tractability?

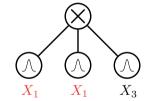
Decomposability

A product node is decomposable if its children depend on disjoint sets of variables

⇒ just like in factorization!



decomposable circuit



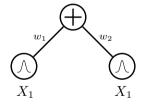
non-decomposable circuit

Smoothness

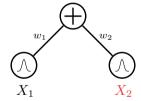
aka completeness

A sum node is smooth if its children depend of the same variable sets

→ otherwise not accounting for some variables



smooth circuit



non-smooth circuit



smoothness can be easily enforced [Shih et al. 2019]

Computing arbitrary integrations (or summations)

⇒ linear in circuit size!

E.g., suppose we want to compute Z:

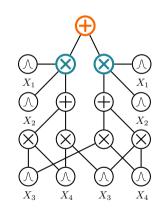
$$\int p(\mathbf{x})d\mathbf{x}$$

If
$$\mathbf{p}(\mathbf{x}) = \sum_i w_i \mathbf{p}_i(\mathbf{x})$$
, (smoothness):

$$\int \mathbf{p}(\mathbf{x}) d\mathbf{x} = \int \sum_{i} w_{i} \mathbf{p}_{i}(\mathbf{x}) d\mathbf{x} =$$

$$= \sum_{i} w_{i} \int \mathbf{p}_{i}(\mathbf{x}) d\mathbf{x}$$

⇒ integrals are "pushed down" to children



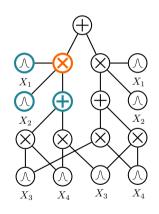
If
$$\mathbf{p}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \mathbf{p}(\mathbf{x})\mathbf{p}(\mathbf{y})\mathbf{p}(\mathbf{z})$$
, (decomposability):

$$\int \int \int \mathbf{p}(\mathbf{x}, \mathbf{y}, \mathbf{z}) d\mathbf{x} d\mathbf{y} d\mathbf{z} =$$

$$= \int \int \int \mathbf{p}(\mathbf{x}) \mathbf{p}(\mathbf{y}) \mathbf{p}(\mathbf{z}) d\mathbf{x} d\mathbf{y} d\mathbf{z} =$$

$$= \int \mathbf{p}(\mathbf{x}) d\mathbf{x} \int \mathbf{p}(\mathbf{y}) d\mathbf{y} \int \mathbf{p}(\mathbf{z}) d\mathbf{z}$$

integrals decompose into easier ones

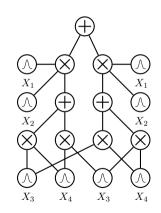


Forward pass evaluation for MAR

linear in circuit size!

E.g. to compute $p(x_2, x_4)$:

- leafs over X_1 and X_3 output $Z_i = \int p(x_i) dx_i$
 - \Rightarrow for normalized leaf distributions: 1.0
- leafs over X_2 and X_4 output \emph{EVI}
- feedforward evaluation (bottom-up)

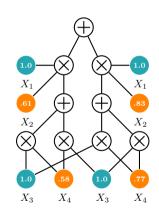


Forward pass evaluation for MAR

→ linear in circuit size!

E.g. to compute $p(x_2, x_4)$:

- leafs over X_1 and X_3 output ${m Z}_i = \int p(x_i) dx_i$
 - \Rightarrow for normalized leaf distributions: 1.0
- leafs over X_2 and X_4 output **EVI**
- feedforward evaluation (bottom-up

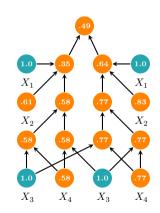


Forward pass evaluation for MAR

→ linear in circuit size!

E.g. to compute $p(x_2, x_4)$:

- leafs over X_1 and X_3 output $\mathbf{Z}_i = \int p(x_i) dx_i$
 - ⇒ for normalized leaf distributions: 1.0
- lacksquare leafs over X_2 and X_4 output lacksquare
- feedforward evaluation (bottom-up)

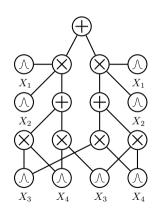


Analogously, for arbitrary conditional queries:

$$p(\mathbf{q} \mid \mathbf{e}) = \frac{p(\mathbf{q}, \mathbf{e})}{p(\mathbf{e})}$$

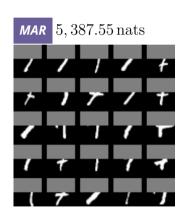
- 1. evaluate $p(\mathbf{q}, \mathbf{e})$ \implies one feedforward pass
- 2. evaluate $p(\mathbf{e})$ \implies another feedforward pass

⇒ ...still linear in circuit size!



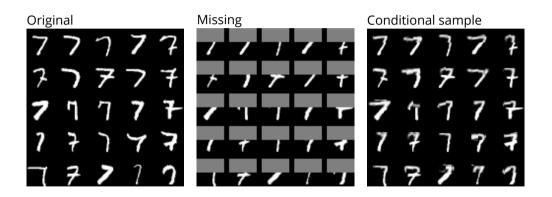
Tractable MAR on PCs (Einsum Networks)





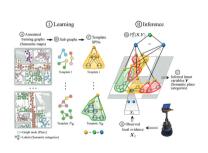
Peharz et al., "Einsum Networks: Fast and Scalable Learning of Tractable Probabilistic Circuits", 2020

Tractable CON on PCs (Einsum Networks)



Peharz et al., "Einsum Networks: Fast and Scalable Learning of Tractable Probabilistic Circuits", 2020

Tractable MAR: Robotics



Pixels for scenes and abstractions for maps decompose along circuit structures.

Fast and exact *marginalization* over unseen or "do not care" scene and map parts for *hierarchical planning robot executions*

Pronobis and Rao, "Learning Deep Generative Spatial Models for Mobile Robots", 2016 Pronobis et al., "Deep spatial affordance hierarchy: Spatial knowledge representation for planning in large-scale environments", 2017

Zheng et al., "Learning graph-structured sum-product networks for probabilistic semantic maps", 2018

We can also decompose bottom-up a MAP query:

$$\max_{\mathbf{q}} p(\mathbf{q} \mid \mathbf{e})$$

We *cannot* decompose bottom-up a MAP query:

$$\max_{\mathbf{q}} p(\mathbf{q} \mid \mathbf{e})$$

since for a sum node we are marginalizing out a latent variable

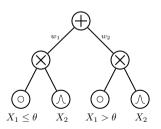
$$\max_{\mathbf{q}} \sum_{i} w_{i} p_{i}(\mathbf{q}, \mathbf{e}) = \max_{\mathbf{q}} \sum_{\mathbf{z}} p(\mathbf{q}, \mathbf{z}, \mathbf{e}) \neq \sum_{\mathbf{z}} \max_{\mathbf{q}} p(\mathbf{q}, \mathbf{z}, \mathbf{e})$$

→ MAP for latent variable models is intractable [Conaty et al. 2017]

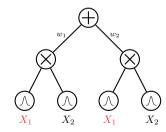
Determinism

aka selectivity

A sum node is deterministic if the output of only one children is non zero for any input e.g. if their distributions have disjoint support



deterministic circuit



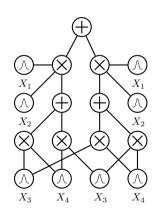
non-deterministic circuit

Computing maximization with arbitrary evidence e

linear in circuit size!

E.g., suppose we want to compute:

$$\max_{\mathbf{q}} p(\mathbf{q} \mid \mathbf{e})$$

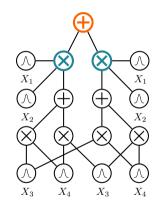


If
$$\mathbf{p}(\mathbf{q}, \mathbf{e}) = \sum_i w_i \mathbf{p}_i(\mathbf{q}, \mathbf{e}) = \max_i w_i \mathbf{p}_i(\mathbf{q}, \mathbf{e})$$
, (*deterministic* sum node):

$$\max_{\mathbf{q}} \mathbf{p}(\mathbf{q}, \mathbf{e}) = \max_{\mathbf{q}} \sum_{i} w_{i} \mathbf{p}_{i}(\mathbf{q}, \mathbf{e})$$
$$= \max_{\mathbf{q}} \max_{i} w_{i} \mathbf{p}_{i}(\mathbf{q}, \mathbf{e})$$
$$= \max_{i} \max_{\mathbf{q}} w_{i} \mathbf{p}_{i}(\mathbf{q}, \mathbf{e})$$

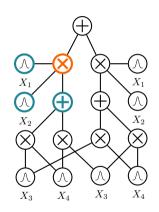


one non-zero child term, thus sum is max



If $\mathbf{p}(\mathbf{q}, \mathbf{e}) = \mathbf{p}(\mathbf{q}_{\mathbf{x}}, \mathbf{e}_{\mathbf{x}}, \mathbf{q}_{\mathbf{v}}, \mathbf{e}_{\mathbf{v}}) = \mathbf{p}(\mathbf{q}_{\mathbf{x}}, \mathbf{e}_{\mathbf{x}})\mathbf{p}(\mathbf{q}_{\mathbf{v}}, \mathbf{e}_{\mathbf{v}})$ (**decomposable** product node):

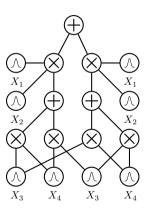
$$\begin{aligned} \max_{\mathbf{q}} \mathbf{p}(\mathbf{q} \mid \mathbf{e}) &= \max_{\mathbf{q}} \mathbf{p}(\mathbf{q}, \mathbf{e}) \\ &= \max_{\mathbf{q_x}, \mathbf{q_y}} \mathbf{p}(\mathbf{q_x}, \mathbf{e_x}, \mathbf{q_y}, \mathbf{e_y}) \\ &= \max_{\mathbf{q_x}} \mathbf{p}(\mathbf{q_x}, \mathbf{e_x}) \cdot \max_{\mathbf{q_y}} \mathbf{p}(\mathbf{q_y}, \mathbf{e_y}) \\ &\implies \textit{solving optimization independently} \end{aligned}$$



Evaluating the circuit twice:

bottom-up and top-down

⇒ still linear in circuit size!



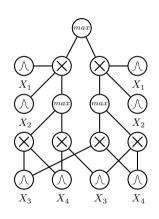
Evaluating the circuit twice:

bottom-up and top-down

still linear in circuit size!

E.g., for $\operatorname{argmax}_{x_1,x_2} p(x_1,x_3 \mid x_2,x_4)$:

- 1. turn sum into max nodes and distributions into max distributions



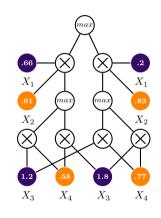
Evaluating the circuit twice:

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E.g., for $\operatorname{argmax}_{x_1,x_2} p(x_1,x_3 \mid x_2,x_4)$:

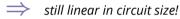
- 1. turn sum into max nodes and distributions into max distributions
- 2. evaluate $p(x_2, x_4)$ bottom-up



Determinism + decomposability = tractable MAP

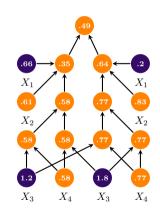
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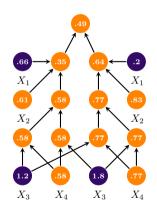
Evaluating the circuit twice:

bottom-up and top-down

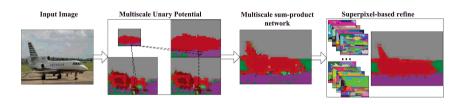
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E.g., for $\operatorname{argmax}_{x_1,x_2} p(x_1,x_3 \mid x_2,x_4)$:

- 1. turn sum into max nodes and distributions into max distributions
- 2. evaluate $p(x_2, x_4)$ bottom-up
- 3. retrieve max activations top-down
- 4. compute MAP states for X_1 and X_3 at leaves



MAP inference: image segmentation



Semantic segmentation is MAP over joint pixel and label space Even approximate MAP for non-deterministic circuits (SPNs) delivers good performances.

Rathke et al., "Locally adaptive probabilistic models for global segmentation of pathological oct scans", 2017

Yuan et al., "Modeling spatial layout for scene image understanding via a novel multiscale sum-product network", 2016

Friesen and Domingos, "Submodular Sum-product Networks for Scene Understanding", 2016

Determinism + decomposability = tractable MMAP

Analogously, we could also do a MMAP query?:

$$\max_{\mathbf{q}} \sum_{\mathbf{z}} p(\mathbf{q}, \mathbf{z} \mid \mathbf{e})$$

Determinism + decomposability = tractab

We *cannot* decompose a MMAP guery!

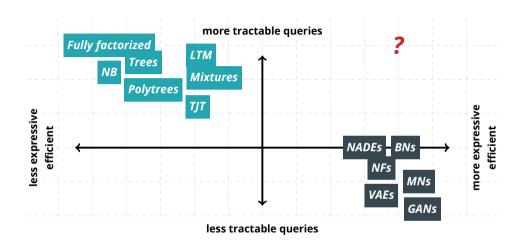
$$\max_{\mathbf{q}} \sum_{\mathbf{z}} p(\mathbf{q}, \mathbf{z} \mid \mathbf{e})$$

we still have latent variables to marginalize...

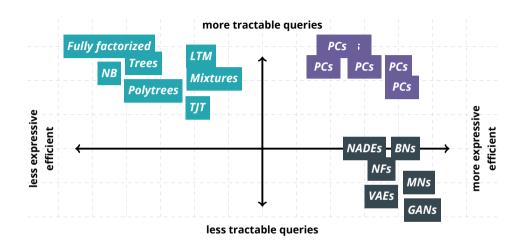
We need more structural properties!



more advanced queries in Part 4 later...



where are probabilistic circuits?



tractability vs expressive efficiency

Low-treewidh PGMs

Tree, polytrees and Thin Junction trees can be turned into

decomposable

smooth

deterministic

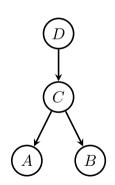
circuits

Therefore they support tractable

EVI

MAR/CON

MAP



Arithmetic Circuits (ACs)

ACs [Darwiche 2003] are

decomposable

smooth

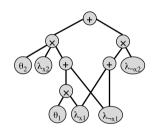
deterministic

They support tractable

EVI

MAR/CON

MAP



parameters are attached to the leaves

...but can be moved to the sum node edges [Rooshenas et al. 2014]

Sum-Product Networks (SPNs)

SPNs [Poon et al. 2011] are

decomposable

smooth

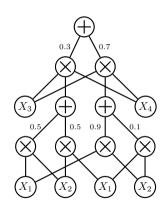
deterministic

They support tractable

EVI

MAR/CON

MAP





deterministic SPNs are also called selective [Peharz et al. 2014]

Cutset Networks (CNets)

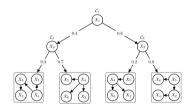
CNets

[Rahman et al. 2014] are

- decomposable
- smooth
- deterministic

They support tractable

- EVI
- MAR/CON
- MAP



Rahman et al., "Cutset Networks: A Simple, Tractable, and Scalable Approach for Improving the Accuracy of Chow-Liu Trees", 2014

Probabilistic Sentential Decision Diagrams

PSDDs [Kisa et al. 2014a] are

structured decomposable

smooth

deterministic

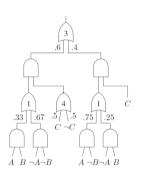
They support tractable

EVI

MAR/CON

MAP

Complex queries!



Kisa et al., "Probabilistic sentential decision diagrams", 2014

Choi et al., "Tractable learning for structured probability spaces: A case study in learning preference distributions", 2015

Shen et al., "Conditional PSDDs: Modeling and learning with modular knowledge", 2018

Probabilistic Decision Graphs

PDGs [laeger 2004] are

structured decomposable

smooth

deterministic

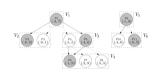
They support tractable

EVI

MAR/CON

MAP

Complex queries!



Jaeger, "Probabilistic decision graphs—combining verification and AI techniques for probabilistic inference", 2004

AndOrGraphs

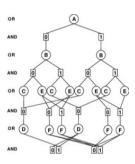
AndOrGarphs

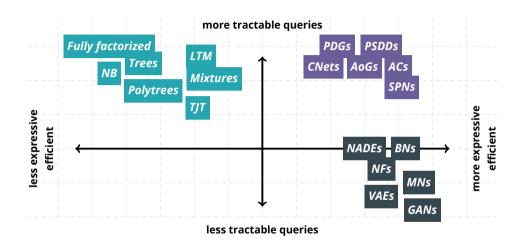
[Dechter et al. 2007] are

- structured decomposable
- smooth
- deterministic

They support tractable

- **EVI**
- MAR/CON
- MAP
- Complex queries!





tractability vs expressive efficiency

- In some sense: Yes, they can always be leaf distributions!
- More interesting: Can all tractable probabilistic models be written as compact PCs with structural constraints over "simple" leafs?
- Concretely: Can all binary distributions that are tractable for MAR be written as smooth decomposable PCs with univariate leafs?

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Almost! One possible exception are Determinantal Point Proceses (DPPs). Active area of research [Martens et al. 2014; Zhang et al. 2020]

How expressive are probabilistic circuits?

Measuring average test set log-likelihood on 20 density estimation benchmarks

Comparing against intractable models:

- Bayesian networks (BN) [Chickering 2002] with sophisticated context-specific CPDs
- MADEs [Germain et al. 2015]
- VAEs [Kingma et al. 2014] (IWAE ELBO [Burda et al. 2015])

Gens and Domingos, "Learning the Structure of Sum-Product Networks", 2013 Peharz et al., "Random sum-product networks: A simple but effective approach to probabilistic deep learning", 2019

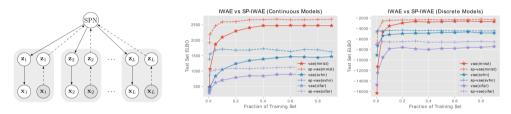
How expressive are probabilistic circuits?

density estimation benchmarks

dataset	best circuit	BN	MADE	VAE	dataset	best circuit	BN	MADE	VAE
nltcs	-5.99	-6.02	-6.04	-5.99	dna	-79.88	-80.65	-82.77	-94.56
msnbc	-6.04	-6.04	-6.06	-6.09	kosarek	-10.52	-10.83	-	-10.64
kdd	-2.12	-2.19	-2.07	-2.12	msweb	-9.62	-9.70	-9.59	-9.73
plants	-11.84	-12.65	-12.32	-12.34	book	-33.82	-36.41	-33.95	-33.19
audio	-39.39	-40.50	-38.95	-38.67	movie	-50.34	-54.37	-48.7	-47.43
jester	-51.29	-51.07	-52.23	-51.54	webkb	-149.20	-157.43	-149.59	-146.9
netflix	-55.71	-57.02	-55.16	-54.73	cr52	-81.87	-87.56	-82.80	-81.33
accidents	-26.89	-26.32	-26.42	-29.11	c20ng	-151.02	-158.95	-153.18	-146.9
retail	-10.72	-10.87	-10.81	-10.83	bbc	-229.21	-257.86	-242.40	-240.94
pumbs*	-22.15	-21.72	-22.3	-25.16	ad	-14.00	-18.35	-13.65	-18.81

Hybrid intractable + tractable EVI

VAEs as intractable input distributions, orchestrated by a circuit on top



decomposing a joint ELBO: better lower-bounds than a single VAE more expressive efficient and less data hungry

^{91/159}

A probabilistic circuit $\mathcal C$ over variables $\mathbf X$ is a **computational graph** encoding a (possibly unnormalized) probability distribution $p(\mathbf X)$ parameterized by Ω

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Learning a circuit $\mathcal C$ from data $\mathcal D$ can therefore involve learning the graph (structure) and/or its parameters

	Parameters	Structure
Generative	?	?
Discriminative	?	?

Stay tuned for ...

Next

- 1. How to learn circuit parameters?
 - ⇒ convex optimization, EM, SGD, Bayesian learning, ...
- 2. How to learn the structure of circuits?

⇒ local search, random structures, ensembles, ...



How circuits are related to other tractable models?

Probabilistic circuits are (peculiar) neural networks... just backprop with SGD!

Probabilistic circuits are (peculiar) neural networks... just backprop with SGD!

...end of Learning section!

Probabilistic circuits are (peculiar) neural networks... just backprop with SGD!

wait but...

SGD is slow to converge...can we do better?

How to learn normalized weights?

Can we exploit structural properties somehow?

As simple as tossing a coin



The simplest PC: a single input distribution p_{L} with parameters $oldsymbol{ heta}$

 \Rightarrow maximum likelihood (ML) estimation over data ${\cal D}$

As simple as tossing a coin



The simplest PC: a single input distribution p_{L} with parameters $oldsymbol{ heta}$

 \implies maximum likelihood (ML) estimation over data ${\cal D}$

E.g. Bernoulli with parameter θ

$$\hat{ heta}_{\mathsf{ML}} = rac{\sum_{x \in \mathcal{D}} \mathbb{1}[x=1] + lpha}{|\mathcal{D}| + 2lpha} \implies \textit{Laplace smoothing}$$

General case: still simple

Bernoulli, Gaussian, Dirichlet, Poisson, Gamma are exponential families of the form:

$$p_{\mathsf{L}}(\mathbf{x}) = \mathbf{h}(\mathbf{x}) \exp(\mathbf{T}(\mathbf{x})^T \boldsymbol{\theta} - A(\boldsymbol{\theta}))$$

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Where:

- lacksquare $A(m{ heta})$: log-normalizer
- h(x) base-measure
- T(x) sufficient statistics
- \blacksquare θ natural parameters

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- lacksquare $A(m{ heta})$: log-normalizer
- h(x) base-measure
- $T(\mathbf{x})$ sufficient statistics
- \blacksquare θ natural parameters
- lacksquare or ϕ expectation parameters 1:1 mapping with $heta\Longrightarrow heta= heta(\phi)$

General case: still simple

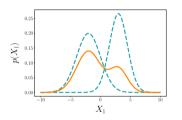
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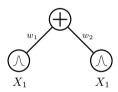
$$p_{\mathsf{L}}(\mathbf{x}) = \mathbf{h}(\mathbf{x}) \exp(\mathbf{T}(\mathbf{x})^T \boldsymbol{\theta} - A(\boldsymbol{\theta}))$$

Maximum likelihood estimation is still "counting":

$$\begin{split} \hat{\boldsymbol{\phi}}_{\mathsf{ML}} &= \mathbb{E}_{\mathcal{D}}[\boldsymbol{T}(\mathbf{x})] = \frac{1}{|\mathcal{D}|} \sum_{\mathbf{x} \in \mathcal{D}} \boldsymbol{T}(\mathbf{x}) \\ \hat{\boldsymbol{\theta}}_{\mathsf{ML}} &= \boldsymbol{\theta}(\hat{\boldsymbol{\phi}}_{\mathsf{ML}}) \end{split}$$

The simplest "real" PC: a sum node

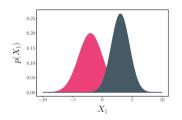


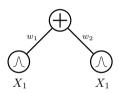


Recall that sum nodes represent *mixture models*:

$$p_{\mathsf{S}}(\mathbf{x}) = \sum_{k=1}^K w_k p_{\mathsf{L}_k}(\mathbf{x})$$

The simplest "real" PC: a sum node





Recall that sum nodes represent *latent variable models*:

$$p_{S}(\mathbf{x}) = \sum_{k=1}^{K} p(Z=k)p(\mathbf{x} \mid Z=k)$$

Learning latent variable models: the EM recipe

Expectation-maximization = maximum-likelihood under missing data.

Given: $p(\mathbf{X}, \mathbf{Z})$ where \mathbf{X} observed, \mathbf{Z} missing at random.

$$\boldsymbol{\theta}^{new} \leftarrow \arg \max_{\boldsymbol{\theta}} \mathbb{E}_{p(\mathbf{Z} \mid \mathbf{X}; \boldsymbol{\theta}^{old})} [\log p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta})]$$

Expectation-Maximization for mixtures

- \blacksquare ML if Z was observed:

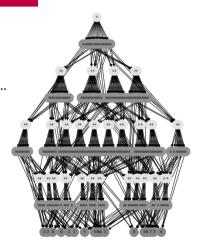
$$\hat{w}_k = \frac{\sum_{z \in \mathcal{D}} \mathbb{1}[z = k]}{|\mathcal{D}|} \qquad \hat{\phi}_k = \frac{\sum_{\mathbf{x}, z \in \mathcal{D}} \mathbb{1}[z = k] T(\mathbf{x})}{\sum_{z \in \mathcal{D}} \mathbb{1}[z = k]}$$

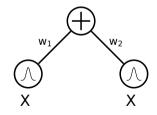
lacksquare Z is unobserved—but we have $p(Z=k\,|\,\mathbf{x}) \propto w_k\,\mathsf{L}_k(\mathbf{x}).$

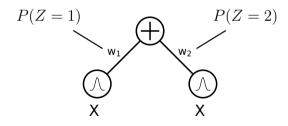
$$w_k^{new} = \frac{\sum_{\mathbf{x} \in \mathcal{D}} p(Z = k \mid \mathbf{x})}{|\mathcal{D}|} \qquad \phi_k^{new} = \frac{\sum_{\mathbf{x}, z \in \mathcal{D}} p(Z = k \mid \mathbf{x}) T(\mathbf{x})}{\sum_{z \in \mathcal{D}} p(Z = k \mid \mathbf{x})}$$

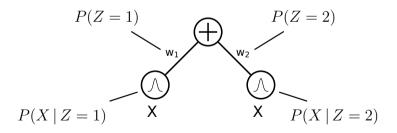
- EM for mixtures well understood.
- Mixtures are PCs with 1 sum node.
- The general case, PCs with many sum nodes, is similar ...

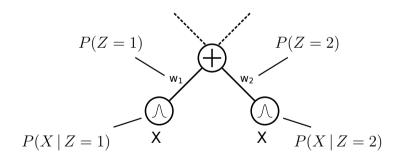
- EM for mixtures well understood.
- Mixtures are PCs with 1 sum node.
- The general case, PCs with many sum nodes, is similar ...
- ...but a bit more complicated.

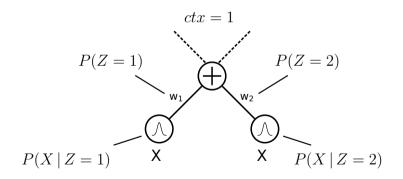


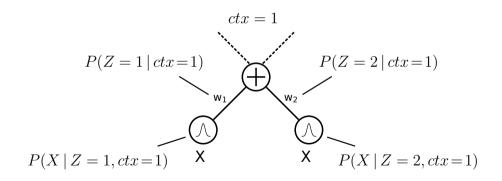




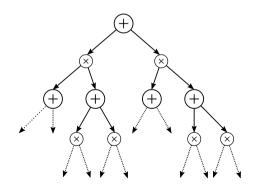








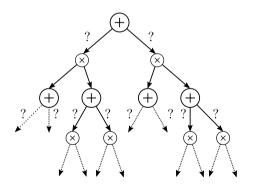
Tractable MAR (smooth, decomposable)



For learning, we need to know for each sum S:

- 1. Is S reached (ctx = ?)
- 2. Which child does it select ($Z_S = ?$)

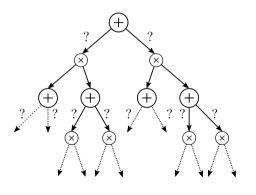
Tractable MAR (smooth, decomposable)



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Tractable MAR (smooth, decomposable)



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- 1. Is S reached (ctx = ?)
- 2. Which child does it select ($Z_S = ?$)

We can *infer* it: $p(ctx, Z_S \mid \mathbf{x})$

Tractable MAR (smooth, decomposable)

$$w_{i,j}^{new} \leftarrow \frac{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}]}{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1 \mid \mathbf{x}; \mathbf{w}^{old}]}$$

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We get **all** the required statistics with a single backprop pass:

$$p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}] = \frac{1}{p(\mathbf{x})} \frac{\partial p(\mathbf{x})}{\partial S_i(\mathbf{x})} \mathsf{N}_j(\mathbf{x}) w_{i,j}^{old}$$

Tractable MAR (smooth, decomposable)

$$w_{i,j}^{new} \leftarrow \frac{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}]}{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1 \mid \mathbf{x}; \mathbf{w}^{old}]}$$

We get **all** the required statistics with a single backprop pass:

$$p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}] = \frac{1}{p(\mathbf{x})} \frac{\partial p(\mathbf{x})}{\partial \mathsf{S}_i(\mathbf{x})} \mathsf{N}_j(\mathbf{x}) w_{i,j}^{old}$$



 \Rightarrow This also works with missing values in x!

Tractable MAR (smooth, decomposable)

$$w_{i,j}^{new} \leftarrow \frac{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}]}{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1 \mid \mathbf{x}; \mathbf{w}^{old}]}$$

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⇒ Similar updates for leaves, when in exponential family.

Tractable MAR (smooth, decomposable)

$$w_{i,j}^{new} \leftarrow \frac{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}]}{\sum_{\mathbf{x} \in \mathcal{D}} p[ctx_i = 1 \mid \mathbf{x}; \mathbf{w}^{old}]}$$

We get **all** the required statistics with a single backprop pass:

$$p[ctx_i = 1, Z_i = j \mid \mathbf{x}; \mathbf{w}^{old}] = \frac{1}{p(\mathbf{x})} \frac{\partial p(\mathbf{x})}{\partial S_i(\mathbf{x})} \mathsf{N}_j(\mathbf{x}) w_{i,j}^{old}$$

⇒ also derivable from a concave-convex procedure (CCCP) [Zhao et al. 2016b]

EM with Einsum Networks @PyTorch

Creating a PC as an EinsumNetwork [Peharz et al. 2020] for MNIST

EM with Einsum Networks @PyTorch

...and training its parameters with EM

```
for epoch_count in range(10):
    train_ll, valid_ll, test_ll = compute_loglikelihood()
    start_t = time.time()

    for idx in get_batches(train_x, 100):
        outputs = PC.forward(train_x[idx, :])
        log_likelihood = EinsumNetwork.log_likelihoods(outputs).sum()
        log_likelihood.backward()
        PC.em_process_batch()

    print_performance(epoch_count, train_ll, valid_ll, test_ll, time.time() - start_t)
```

EM with Einsum Networks @PyTorch

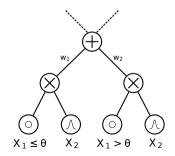
```
# train sample: 5175
# parameters: 1573486
[epoch 0]
            train II -140936.80
                                 valid II -140955.72
                                                        test LL -141033.80
                                                                             ... elapsed time 3.621 sec
[epoch 1]
            train LL
                     -15916.14
                                 valid LL -15693.25
                                                        test LL -15976.43
                                                                                elapsed time 3.438 sec
            train LL
                                 valid LL -10616.72
                                                        test LL -10943.56
                                                                                elapsed time 3.436 sec
[epoch 2]
                     -10865.67
[epoch 3]
            train LL
                     -10388.53
                                 valid LL -10158.84
                                                        test LL -10475.49
                                                                             ... elapsed time 3.473 sec
[epoch 4]
            train LL
                     -10264.11
                                 valid LL -10041.66
                                                        test LL -10352.59
                                                                                elapsed time 3.497 sec
                                 valid LL -10001.09
                                                       test LL -10319.35
                                                                             ... elapsed time 3.584 sec
[epoch 5]
            train LL
                     -10212.66
[epoch 6]
            train LL
                     -10192.21
                                 valid LL
                                             -9965.98
                                                        test LL -10314.84
                                                                             ... elapsed time 3.508 sec
[epoch 7]
            train LL
                     -10153.97
                                 valid LL
                                             -9920.09
                                                       test LL -10261.41
                                                                             ... elapsed time 3.446 sec
            train LL
                     -10112.95
                                 ll hilev
                                             -9882.48
                                                        test LL -10236.34
                                                                             ... elapsed time 3.579 sec
[epoch 8]
[epoch 9]
            train LL
                     -10093.31
                                  valid LL
                                             -9862.15
                                                        test LL
                                                               -10200.94
                                                                                elapsed time 3.483 sec
```

Tractable MAR/MAP (smooth, decomposable, deterministic)

Expectation Maximization Exact ML

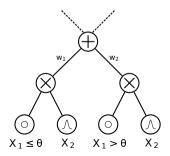
Tractable MAR/MAP (smooth, decomposable, deterministic)

Tractable MAR/MAP (smooth, decomposable, deterministic)



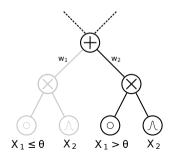
Tractable MAR/MAP (smooth, decomposable, deterministic)

Deterministic circuit \Rightarrow at most one non-zero sum child (for complete input).



Tractable MAR/MAP (smooth, decomposable, deterministic)

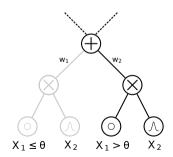
For example, the second child of this sum node...



Tractable MAR/MAP (smooth, decomposable, deterministic)

For example, the second child of this sum node...

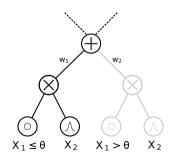
...but that rules out
$$Z=1!$$
 $\Rightarrow P(Z=2 \mid \mathbf{x})=1$



Tractable MAR/MAP (smooth, decomposable, deterministic)

Likewise, if the first child is non-zero:

$$\Rightarrow P(Z=1 \mid \mathbf{x}) = 1$$

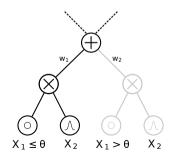


Tractable MAR/MAP (smooth, decomposable, deterministic)

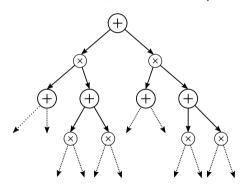
Likewise, if the first child is non-zero:

$$\Rightarrow P(Z=1 \mid \mathbf{x}) = 1$$

Thus, the latent variables are **actually observed** in deterministic circuits!



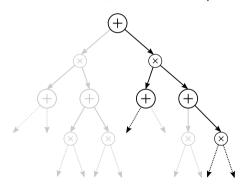
Tractable MAR/MAP (smooth, decomposable, deterministic)



For each sum node, we know

- 1. if it is reached (ctx = 1)
- 2. which child it selects

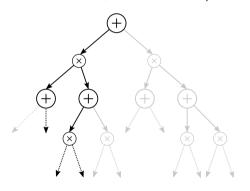
Tractable MAR/MAP (smooth, decomposable, deterministic)



For each sum node, we know

- 1. if it is reached (ctx = 1)
- 2. which child it selects

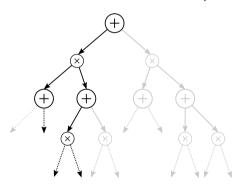
Tractable MAR/MAP (smooth, decomposable, deterministic)



For each sum node, we know

- 1. if it is reached (ctx = 1)
- 2. which child it selects

Tractable MAR/MAP (smooth, decomposable, deterministic)



For each sum node, we know

- 1. If it is reached (ctx = 1)
- 2. which child it selects

⇒ MLE by counting!

Tractable MAR/MAP (smooth, decomposable, deterministic)

Given a complete dataset \mathcal{D} , the maximum-likelihood sum-weights are:

$$w_{i,j}^{\mathsf{ML}} = \frac{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i \land j]\}}{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i]\}}$$

Exact ML

Tractable MAR/MAP (smooth, decomposable, deterministic)

Given a complete dataset \mathcal{D} , the maximum-likelihood sum-weights are:

$$w_{i,j}^{\mathsf{ML}} = \frac{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i \land j]\}}{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i]\}} \qquad \leftarrow ctx_i = 1, Z_i = j$$

Exact ML

Tractable MAR/MAP (smooth, decomposable, deterministic)

Given a complete dataset \mathcal{D} , the maximum-likelihood sum-weights are:

$$w_{i,j}^{\mathsf{ML}} = \frac{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i \land j]\}}{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i]\}} \qquad \begin{array}{l} \leftarrow ctx_i = 1, Z_i = j \\ \leftarrow ctx_i = 1 \end{array}$$

Exact ML

Tractable MAR/MAP (smooth, decomposable, deterministic)

Given a complete dataset \mathcal{D} , the maximum-likelihood sum-weights are:

$$w_{i,j}^{\mathsf{ML}} = \frac{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i \land j]\}}{\sum_{\mathbf{x} \in \mathcal{D}} \mathbb{1}\{\mathbf{x} \models [i]\}} \qquad \begin{array}{l} \leftarrow ctx_i = 1, Z_i = j \\ \leftarrow ctx_i = 1 \end{array}$$

 \Rightarrow global maximum with single pass over \mathcal{D} \Rightarrow regularization, e.g. Laplace-smoothing, to avoid division by zero \Rightarrow when missing data, fallback to EM

Training PCs in Julia with Juice.jl



Training maximum likelihood parameters of probabilistic circuits with determinism is incredibly fast.

```
julia> using ProbabilisticCircuits;
julia> data, structure = load(...);
julia> num_examples(data)
17412
julia> num_edges(structure)
270448
julia> @btime estimate_parameters(structure, data);
63.585 ms (1182350 allocations: 65.97 MiB)
```

Custom SIMD and CUDA kernels to parallelize over layers and training examples.

Bayesian parameter learning

Formulate a prior $p(\mathbf{w}, \boldsymbol{\theta})$ over sum-weights and leaf-parameters and perform posterior inference:

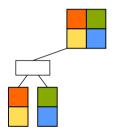
$$p(\mathbf{w}, \boldsymbol{\theta} | \mathcal{D}) \propto p(\mathbf{w}, \boldsymbol{\theta}) p(\mathcal{D} | \mathbf{w}, \boldsymbol{\theta})$$

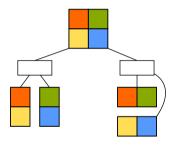
- Moment matching (oBMM) [Jaini et al. 2016; Rashwan et al. 2016]
- Collapsed variational inference algorithm [Zhao et al. 2016a]
- Gibbs sampling [Trapp et al. 2019; Vergari et al. 2019]

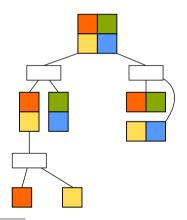
Learning probabilistic circuits

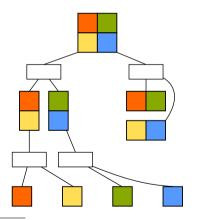
	Parameters	Structure	
Generative	deterministic closed-form MLE [Kisa et al. 2014b; Peharz et al. 2014] non-deterministic EM [Poon et al. 2011; Peharz 2015; Zhao et al. 2016b] SGD [Sharir et al. 2016; Peharz et al. 2019b] Bayesian [Jaini et al. 2016; Rashwan et al. 2016] [Zhao et al. 2016a; Trapp et al. 2019; Vergari et al. 2019]	?	
Discriminative	?	?	

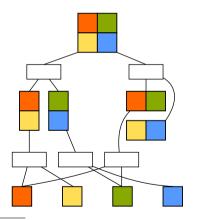


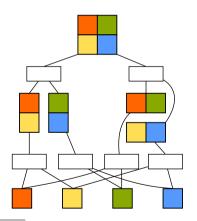


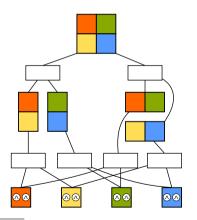


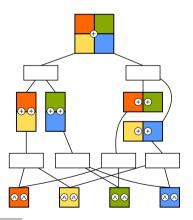


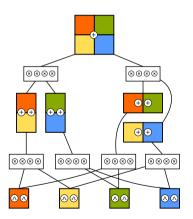


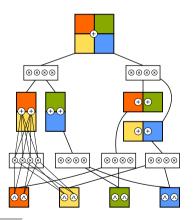






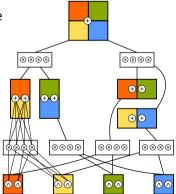






"Recursive Image Slicing"

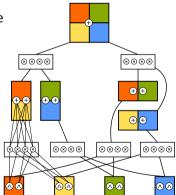
⇒ Smooth & Decomposable



"Recursive Image Slicing"

⇒ Smooth & Decomposable

⇒ Tractable MAR



"Recursive Data Slicing" — LearnSPN

Cluster



"Recursive Data Slicing" — LearnSPN

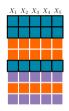
Cluster \rightarrow *sum node*





"Recursive Data Slicing" — LearnSPN

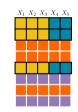
Try to find independent groups of random variables





"Recursive Data Slicing" — LearnSPN

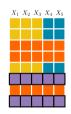
Try to find independent groups of random variables Success \rightarrow **product node**





"Recursive Data Slicing" — LearnSPN

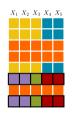
Try to find independent groups of random variables

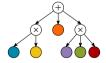




"Recursive Data Slicing" — LearnSPN

Try to find independent groups of random variables Success \rightarrow **product node**





"Recursive Data Slicing" — LearnSPN

Single variable





"Recursive Data Slicing" — LearnSPN

Single variable o *leaf*

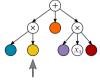




"Recursive Data Slicing" — LearnSPN

Try to find independent groups of random variables

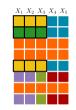


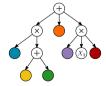


"Recursive Data Slicing" — LearnSPN

Try to find independent groups of random variables

Fail → cluster → **sum node**

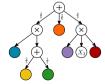




"Recursive Data Slicing" — LearnSPN

- ⇒ Continue until no further leaf can be expanded.
- ⇒ Clustering ratios also deliver (initial) parameters.

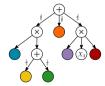




"Recursive Data Slicing" — LearnSPN

- ⇒ Continue until no further leaf can be expanded.
- \Rightarrow Clustering ratios also deliver (initial) parameters.
- ⇒ Smooth & Decomposable
- ⇒ Tractable MAR





LearnSPN

Variants

- ID-SPN [Rooshenas et al. 2014]
- LearnSPN-b/T/B [Vergari et al. 2015]
- for heterogeneous data [Molina et al. 2018]
- using k-means [Butz et al. 2018] or SVD splits [Adel et al. 2015]
- learning **DAGs** [Dennis et al. 2015; Jaini et al. 2018]
- **approximating** independence tests [Di Mauro et al. 2018]

"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]

A B C D E F

"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]



Select Variable

"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]

A B C D E F



"Recursive conditioning" — Cutset Networks

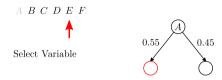
[Rahman et al. 2014]

A B C D E F

Split states



"Recursive conditioning" — Cutset Networks

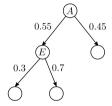


"Recursive conditioning" — Cutset Networks

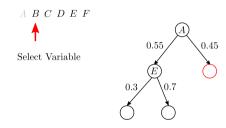
[Rahman et al. 2014]

A B C D E F

Split states



"Recursive conditioning" — Cutset Networks

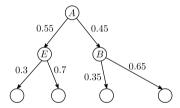


"Recursive conditioning" — Cutset Networks

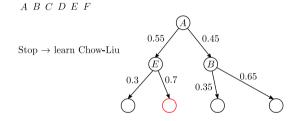
[Rahman et al. 2014]

A B C D E F

Split states



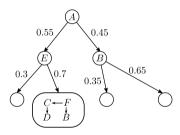
"Recursive conditioning" — Cutset Networks



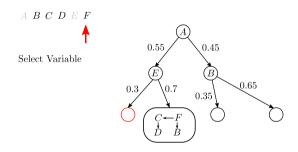
"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]

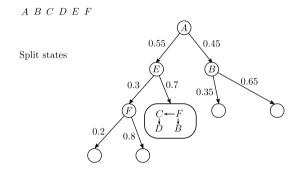
A B C D E F



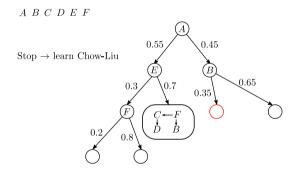
"Recursive conditioning" — Cutset Networks



"Recursive conditioning" — Cutset Networks



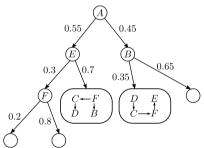
"Recursive conditioning" — Cutset Networks



"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]

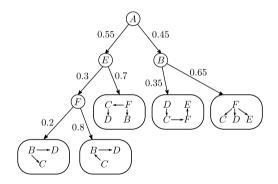
A B C D E F



"Recursive conditioning" — Cutset Networks

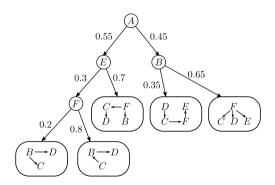
[Rahman et al. 2014]

...and so on.



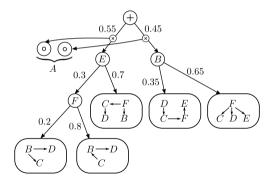
"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]



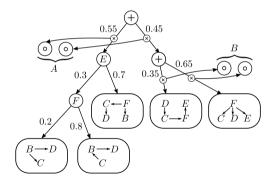
"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]



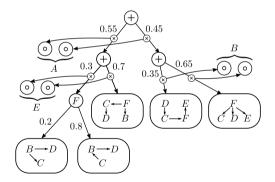
"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]



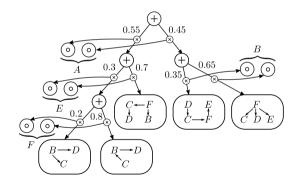
"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]



"Recursive conditioning" — Cutset Networks

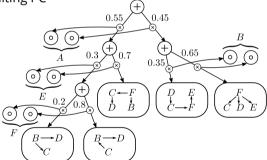
[Rahman et al. 2014]



"Recursive conditioning" — Cutset Networks

[Rahman et al. 2014]

Convert into PC... Resulting PC is deterministic.



Cutset networks (CNets)

Variants

- Variable selection based on entropy [Rahman et al. 2014]
- Can be extended to mixtures of CNets using EM [ibid.]
- Structure search over OR-graphs/CL-trees [Di Mauro et al. 2015b]
- Boosted CNets [Rahman et al. 2016]
- Randomized CNets, Bagging [Di Mauro et al. 2017]

Further Algorithms for Structure Learning

Variants

- Greedy discrete optimization
 [Lowd et al. 2008; Peharz et al. 2014; Liang et al. 2017a; Dang et al. 2020]
- Randomized structures [Di Mauro et al. 2017; Peharz et al. 2019b]
- Ensembles, Bagging [Di Mauro et al. 2015a,b], Boosting [Rahman et al. 2016]

Learning probabilistic circuits

Parameters Structure

Senerative

deterministic

closed-form MLE [Kisa et al. 2014b; Peharz et al. 2014] non-deterministic

EM [Poon et al. 2011; Peharz 2015; Zhao et al. 2016b] SGD [Sharir et al. 2016; Peharz et al. 2019b] Bayesian [Jaini et al. 2016; Rashwan et al. 2016]

[Zhao et al. 2016a; Trapp et al. 2019; Vergari et al. 2019]

greedy

top-down [Gens et al. 2013; Rooshenas et al. 2014] [Rahman et al. 2014; Vergari et al. 2015]

bottom-up [Peharz et al. 2013]

hill climbing [Lowd et al. 2008, 2013; Peharz et al. 2014] [Dennis et al. 2015; Liang et al. 2017a; Dang et al. 2020] random RAT-SPNs [Peharz et al. 2019b] XCNet [Di Mauro et al. 2017]

Discriminative

?

?

EVI inference: density estimation

dataset	single models	ensembles	dataset	single models	ensembles
nltcs	-5.99 [ID-SPN]	-5.99 [LearnPSDDs]	dna	-79.88 [SPGM]	-80.07 [SPN-btb]
msnbc	-6.04 [Prometheus]	-6.04 [LearnPSDDs]	kosarek	-10.59 [Prometheus]	-10.52 [LearnPSDDs]
kdd	-2.12 [Prometheus]	-2.12 [LearnPSDDs]	msweb	-9.73 [ID-SPN]	-9.62 [XCNets]
plants	-12.54 [ID-SPN]	-11.84 [XCNets]	book	-34.14 [ID-SPN]	-33.82 [SPN-btb]
audio	-39.77 [BNP-SPN]	-39.39 [XCNets]	movie	-51.49 [Prometheus]	-50.34 [XCNets]
jester	-52.42 [BNP-SPN]	-51.29 [LearnPSDDs]	webkb	-151.84 [ID-SPN]	-149.20 [XCNets]
netflix	-56.36 [ID-SPN]	-55.71 [LearnPSDDs]	cr52	-83.35 [ID-SPN]	-81.87 [XCNets]
accidents	-26.89 [SPGM]	-29.10 [XCNets]	c20ng	-151.47 [ID-SPN]	-151.02 [XCNets]
retail	-10.85 [ID-SPN]	-10.72 [LearnPSDDs]	bbc	-248.5 [Prometheus]	-229.21 [XCNets]
pumbs*	-22.15 [SPGM]	-22.67 [SPN-btb]	ad	-15.40 [CNetXD]	-14.00 [XCNets]

Learning probabilistic circuits

Parameters

Senerative

Discriminative

deterministic

closed-form MLE [Kisa et al. 2014b; Peharz et al. 2014]

EM [Poon et al. 2011; Peharz 2015; Zhao et al. 2016b] SGD [Sharir et al. 2016: Peharz et al. 2019b]

Bavesian [laini et al. 2016; Peral2 et al. 2019b]

[Zhao et al. 2016a; Trapp et al. 2019; Vergari et al. 2019]

Structure

greedy

top-down [Gens et al. 2013; Rooshenas et al. 2014] [Rahman et al. 2014; Vergari et al. 2015]

bottom-up [Peharz et al. 2013]

hill climbing [Lowd et al. 2008, 2013; Peharz et al. 2014] [Dennis et al. 2015; Liang et al. 2017a; Dang et al. 2020]

random RAT-SPNs [Peharz et al. 2019b] XCNet [Di Mauro et al. 2017]

deterministic

convex-opt MLE [Liang et al. 2019]

non-deterministic

EM [Rashwan et al. 2018] SGD [Gens et al. 2012; Sharir et al. 2016] [Peharz et al. 2019b] greedy

top-down [Shao et al. 2019]

hill climbing [Rooshenas et al. 2016; Liang et al. 2019]

Advanced Representations

Tractability to other semi-rings

Tractable probabilistic inference exploits *efficient summation for decomposable functions* in the probability commutative semiring:

$$(\mathbb{R}, +, \times, 0, 1)$$

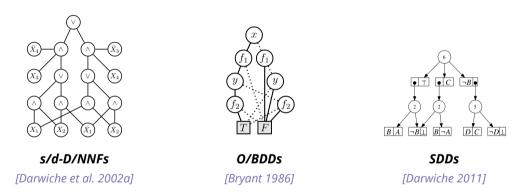
analogously efficient computations can be done in other semi-rings:

$$(\mathbb{S}, \oplus, \otimes, 0_{\oplus}, 1_{\otimes})$$

⇒ Algebraic model counting [Kimmig et al. 2017], Semi-ring programming [Belle et al. 2016]

Historically, *very well studied for boolean functions*:

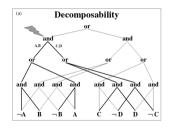
$$(\mathbb{B} = \{0, 1\}, \vee, \wedge, 0, 1) \qquad \implies \textit{logical circuits!}$$

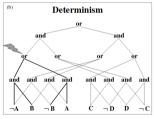


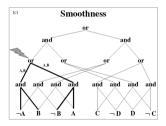
Logical circuits are compact representations for boolean functions...

structural properties

...and like probabilitistic circuits, one can define **structural properties**: (structured) decomposability, smoothness, determinism allowing for tractable computations

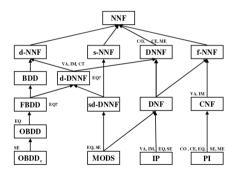






a knowledge compilation map

...inducing a hierarchy of tractable logical circuit families



connection to probabilistic circuits through WMC

A task called **weighted model counting** (WMC)

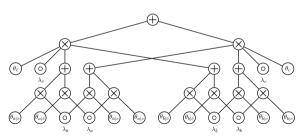
$$WMC(\Delta, w) = \sum_{\mathbf{x} \models \Delta} \prod_{l \in \mathbf{x}} w(l)$$

- Probabilistic inference by WMC:
 - 1. Encode probabilistic model as WMC formula Δ
 - 2. Compile Δ into a logical circuit (e.g. d-DNNF, OBDD, SDD, etc.)
 - 3. Tractable MAR/CON by tractable WMC on circuit
 - 4. Answer complex queries tractably by enforcing more structural properties

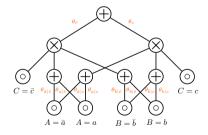
connection to probabilistic circuits through WMC

Resulting compiled WMC circuit equivalent to probabilistic circuit

 \Rightarrow parameter variables o edge parameters

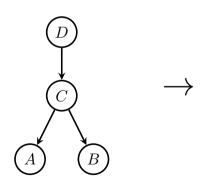


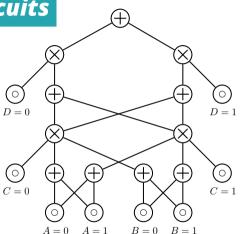
Compiled circuit of WMC encoding



Equivalent probabilistic circuit

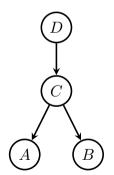
via compilation



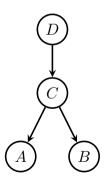


via compilation

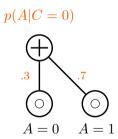
Bottom-up *compilation*: starting from leaves...



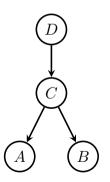
via compilation



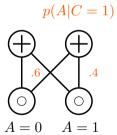
...compile a leaf CPT



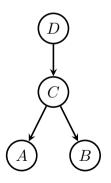
via compilation



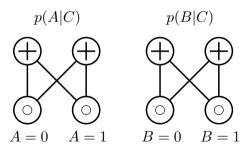
...compile a leaf CPT



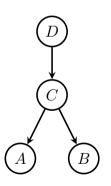
via compilation



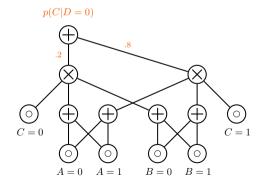
...compile a leaf CPT...for all leaves...



via compilation

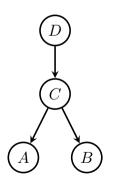


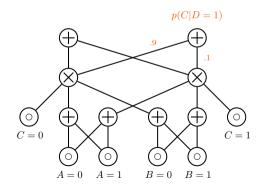
...and recurse over parents...



via compilation

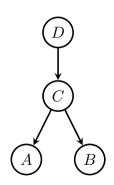
...while reusing previously compiled nodes!...

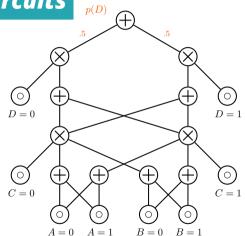




From BN trees to circuits

via compilation





Compilation: probabilistic programming

Chavira et al., "Compiling relational Bayesian networks for exact inference", 2006
Holtzen et al., "Symbolic Exact Inference for Discrete Probabilistic Programs", 2019
De Raedt et al.; Riguzzi; Fierens et al.; Vlasselaer et al., "ProbLog: A Probabilistic Prolog and Its
Application in Link Discovery."; "A top down interpreter for LPAD and CP-logic"; "Inference and
Learning in Probabilistic Logic Programs using Weighted Boolean Formulas"; "Anytime Inference in
Probabilistic Logic Programs with Tp-compilation", 2007; 2015; 2015

Olteanu et al.; Van den Broeck et al., "Using OBDDs for efficient query evaluation on probabilistic databases"; Query Processing on Probabilistic Data: A Survey, 2008; 2017

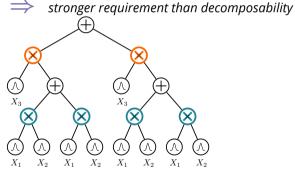
Vlasselaer et al., "Exploiting Local and Repeated Structure in Dynamic Bayesian Networks", 2016

Smooth∨decomposable∨deterministic∨structured decomposablePCs?

	smooth	dec.	det.	str.dec.
Arithmetic Circuits (ACs) [Darwiche 2003]	~	/	/	X
Sum-Product Networks (SPNs) [Poon et al. 2011]		/	X	X
Cutset Networks (CNets) [Rahman et al. 2014]		/		X
Probabilistic Decision Graphs [Jaeger 2004]				
PSDDs [Kisa et al. 2014a]				
AndOrGraphs [Dechter et al. 2007]				

Structured decomposability

A product node is structured decomposable if decomposes according to a node in a **vtree**





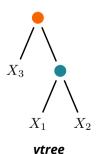
vtree

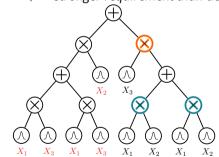
structured decomposable circuit

Structured decomposability

A product node is structured decomposable if decomposes according to a node in a **vtree**

⇒ stronger requirement than decomposability

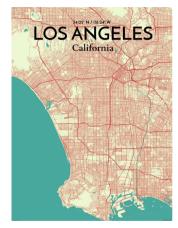




non structured decomposable circuit

Probability of logical events

q₈: What is the probability of having a traffic jam on my route to campus?



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Probability of logical events

q₈: What is the probability of having a traffic jam on my route to campus?

$$\mathbf{q_8}(\mathbf{m}) = p_{\mathbf{m}}(\bigvee_{i \in \mathsf{route}} \mathsf{Jam}_{\mathsf{Str}\; i})$$

marginals + logical events

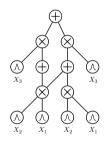


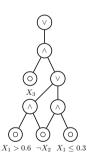
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Computing $p(\alpha)$: the probability of arbitrary logical formula

Multilinear in circuit sizes if the logical circuit:

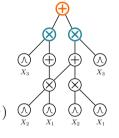
- is smooth, structured decomposable, deterministic
- shares the same vtree

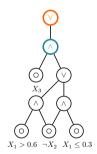




If
$$\mathbf{p}(\mathbf{x}) = \sum_i w_i \mathbf{p}_i(\mathbf{x})$$
, $\mathbf{\alpha} = \bigvee_j \mathbf{\alpha}_j$, (smooth \mathbf{p}) (smooth + deterministic $\mathbf{\alpha}$):

$$\mathbf{p}(\boldsymbol{\alpha}) = \sum_{i} w_{i} \mathbf{p}_{i} \left(\bigvee_{j} \boldsymbol{\alpha}_{j} \right) = \sum_{i} w_{i} \sum_{j} \mathbf{p}_{i} \left(\boldsymbol{\alpha}_{j} \right) \circlearrowleft_{X_{2}} \circlearrowleft_{X_{1}}$$

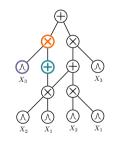


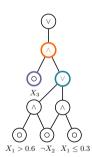


> probabilities are "pushed down" to

If
$$p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x})p(\mathbf{y})$$
, $\alpha = \beta \wedge \gamma$, (structured decomposability):

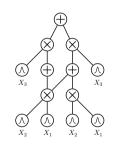
$$m{p}(m{lpha}) = m{p}\left(m{eta} \wedge m{\gamma}
ight) \cdot m{p}\left(m{eta} \wedge m{\gamma}
ight) = m{p}\left(m{eta}
ight) \cdot m{p}\left(m{\gamma}
ight)$$
 \implies probabilities decompose into simpler ones

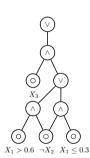




To compute $p(\alpha)$:

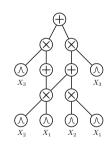
- compute the probability for each **pair** of probabilistic and logical circuit nodes for the **same vtree node**
 - cache the values!
- feedforward evaluation (bottom-up)

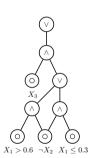




To compute $p(\alpha)$:

- compute the probability for each **pair** of probabilistic and logical circuit nodes for the **same vtree node**
 - cache the values!
- feedforward evaluation (bottom-up)



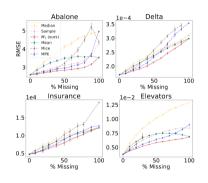


structured decomposability = tractable...

Symmetric and group queries (exactly-k, odd-number, etc.) [Bekker et al. 2015] For the "right" vtree

- Probability of logical circuit event in probabilistic circuit [Choi et al. 2015b]
- Multiply two probabilistic circuits [Shen et al. 2016]
- **KL Divergence** between probabilistic circuits [Liang et al. 2017b]
- Same-decision probability [Oztok et al. 2016]
- **Expected same-decision probability** [Choi et al. 2017]
- **Expected classifier agreement** [Choi et al. 2018]
- **Expected predictions** [Khosravi et al. 2019b]

ADV inference: expected predictions



Reasoning about the output of a classifier or regressor $m{f}$ given a distribution $m{p}$ over the input features

$$\begin{array}{c} \mathbb{E} \\ \mathbf{x}^m \sim p_{\theta}(\mathbf{x}^m | \mathbf{x}^o) \end{array} \left[f_{\phi}^k(\mathbf{x}^m, \mathbf{x}^o) \right] \\ \Longrightarrow \begin{array}{c} \mathbf{PR} \ \textit{if} \ \textit{f} \ \textit{is a logical formula} \\ \Longrightarrow \quad \textit{missing values at test time} \\ \Longrightarrow \quad \textit{exploratory classifier analysis} \end{array}$$

ADV inference in Julia with Juice.jl

```
using ProbabilisticCircuits
pc = load prob circuit(zoo psdd file("insurance.psdd"));
rc = load logistic circuit(zoo lc file("insurance.circuit"), 1);
q<sub>8</sub>: How different is the insurance costs between smokers and non smokers?
groups = make observations([["!smoker"], ["smoker"]])
exps, _ = Expectation(pc, rc, groups);
println("Smoker : \$ $(exps[2])");
println("Non-Smoker: \$ $(exps[1])");
println("Difference: \$ $(exps[2] - exps[1])");
Smoker : $ 31355.32630488978
Non-Smoker: $ 8741.747258310648
Difference: $ 22613.57904657913
```

ADV inference in Julia with Juice.jl

```
using ProbabilisticCircuits
pc = load prob circuit(zoo psdd file("insurance.psdd"));
rc = load logistic circuit(zoo lc file("insurance.circuit"), 1);
q<sub>9</sub>: Is the predictive model biased by gender?
groups = make_observations([["male"], ["female"]])
exps, _ = Expectation(pc, rc, groups);
println("Female : \$ $(exps[2])");
println("Male : \$ $(exps[1])");
println("Diff : \$ $(exps[2] - exps[1])");
Female: $ 14170.125469335406
Male : $ 13196.548926381849
Diff: $ 973.5765429535568
```

Stay tuned for ...



- How precise is the characterization of tractable circuits by structural properties?
- 2. How do structural constraints affect the circuit sizes?

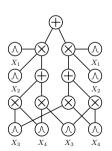
⇒ succinctness analysis

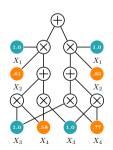


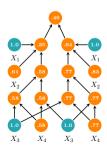
Conclusions!

Smoothness + decomposability = tractable MAR

Recall: Smoothness and decomposability allow tractable computation of marginal queries.





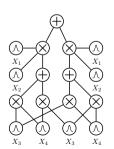


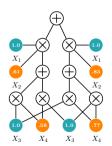
Smoothness + decomposability = tractable MAR

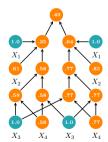
Recall: Smoothness and decomposability allow tractable computation of marginal queries.



Are these properties necessary?



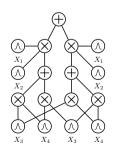


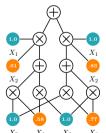


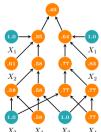
Smoothness + decomposability = tractable MAR

Recall: Smoothness and decomposability allow tractable computation of marginal queries.

Are these properties necessary?
 Yes! Otherwise, integrals do not decompose.

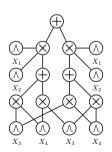


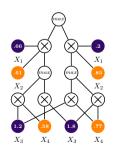


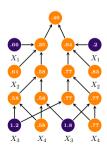


Determinism + decomposability = tractable MAP

Recall: Determinism and decomposability allow tractable computation of MAP queries.





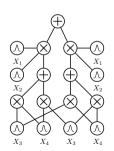


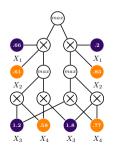
Determinism + decomposability = tractable MAP

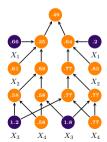
Recall: Determinism and decomposability allow tractable computation of MAP queries.



However, decomposability is not necessary!







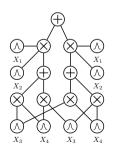
Determinism + decomposability = tractable MAP

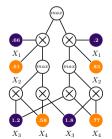
Recall: Determinism and decomposability allow tractable computation of MAP queries.

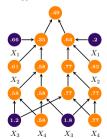


However, decomposability is not necessary!

A weaker condition, consistency, suffices.

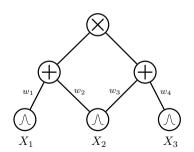




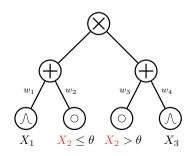


Consistency

A product node is consistent if any variable shared between its children appears in a single leaf node



consistent circuit



decomposability implies consistency

inconsistent circuit

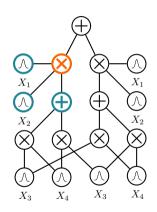
Determinism + consistency = tractable MAP

Determinism + consistency = tractable MAP

$$\begin{array}{l} \text{If } \max_{\mathbf{q}_{\text{shared}}} \textcolor{red}{p}(\mathbf{q}, \mathbf{e}) = \\ \max_{\mathbf{q}_{\text{shared}}} \textcolor{red}{p}(\mathbf{q}_{\mathbf{x}}, \mathbf{e}_{\mathbf{x}}) \cdot \max_{\mathbf{q}_{\text{shared}}} \textcolor{red}{p}(\mathbf{q}_{\mathbf{y}}, \mathbf{e}_{\mathbf{y}}) \text{ (consistent)} . \end{array}$$

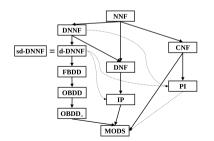
$$\begin{split} \max_{\mathbf{q}} \mathbf{p}(\mathbf{q}, \mathbf{e}) &= \max_{\mathbf{q_x}, \mathbf{q_y}} \mathbf{p}(\mathbf{q_x}, \mathbf{e_x}, \mathbf{q_y}, \mathbf{e_y}) \\ &= \max_{\mathbf{q_x}} \mathbf{p}(\mathbf{q_x}, \mathbf{e_x}) \cdot \max_{\mathbf{q_y}} \mathbf{p}(\mathbf{q_y}, \mathbf{e_y}) \end{split}$$

⇒ solving optimization independently



Tractability is defined w.r.t. the size of the model.

How do structural constraints affect **expressive efficiency** (**succinctness**) of probabilistic circuits?



Again, connections to logical circuits

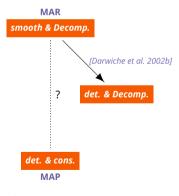
A family of probabilistic circuits \mathcal{M}_1 is **at least as succinct as** \mathcal{M}_2 iff for every $\mathbf{m}_2 \in \mathcal{M}_2$, there exists $\mathbf{m}_1 \in \mathcal{M}_1$ that represents the same distribution and $|m_1| \leq |\mathsf{poly}(m_2)|$.

$$\implies$$
 denoted $\mathcal{M}_1 \leq \mathcal{M}_2$

$$\implies$$
 strictly more succinct iff $\mathcal{M}_1 \leq \mathcal{M}_2$ and $\mathcal{M}_1 \not\geq \mathcal{M}_2$



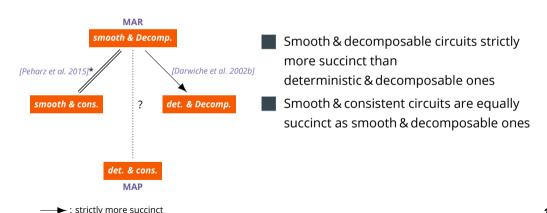
Are smooth & decomposable circuits as succinct as deterministic & consistent ones, or vice versa?



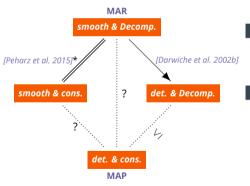
- Smooth & decomposable circuits strictly more succinct than deterministic & decomposable ones
- Smooth & consistent circuits are equally succinct as smooth & decomposable one:

: strictly more succinct

: equally succinct

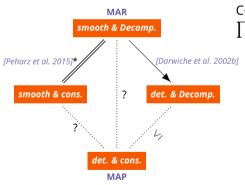


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- Smooth & decomposable circuits strictly more succinct than deterministic & decomposable ones
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: strictly more succinct: equally succinct

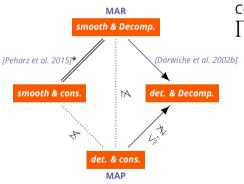


Consider following circuit over Boolean variables:

$$\prod_{i=1}^{r} (Y_i \cdot Z_{i1} + (\neg Y_i) \cdot Z_{i2}), \quad Z_{ij} \in \mathbf{X}$$

- Size linear in the number of variables
- Deterministic and consistent
 - Marginal (with no evidence) is the solution to #P-hard SAT' problem [Valiant 1979] ⇒
 no tractable circuit for marginals!

: strictly more succinct: equally succinct



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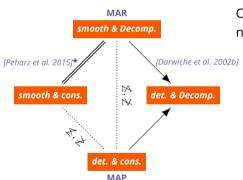
: strictly more succinct



Consider the marginal distribution $p(\mathbf{X})$ from a naive Bayes distribution $p(\mathbf{X}, C)$:

- Linear-size smooth and decomposable circuit
- MAP of $p(\mathbf{X})$ solves marginal MAP of $p(\mathbf{X}, C)$ which is NP-hard [de Campos 2011] \Rightarrow no tractable circuit for MAP!

: strictly more succinct: equally succinct

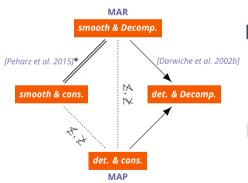


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Expressive efficiency of circuits



Neither smooth & decomposable nor deterministic & consistent circuits are more succinct than the other!

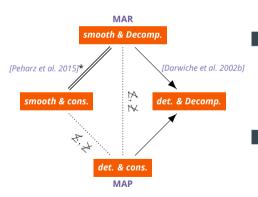
→ Choose tractable circuit family based on your query

More theoretical questions remaining

→ "Complete the map"

: strictly more succinct

Expressive efficiency of circuits



Neither smooth & decomposable nor deterministic & consistent circuits are more succinct than the other!

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More theoretical questions remaining

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: strictly more succinct: equally succinct

Conclusions

Why tractable inference?

or expressiveness vs tractability

Probabilistic circuits

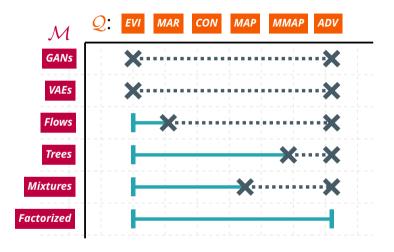
a unified framework for tractable probabilistic modeling

Learning circuits

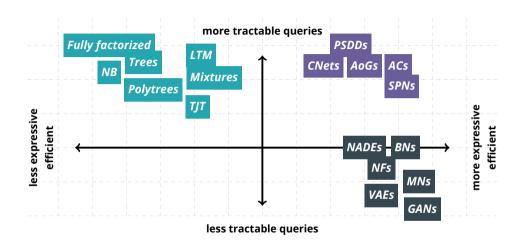
learning their structure and parameters from data

Advanced representations

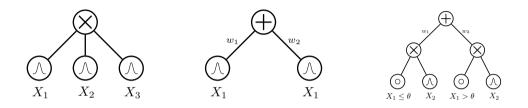
tracing the boundaries of tractability and connections to other formalisms



takeaway #1: tractability is a spectrum



takeaway #2: you can be both tractable and expressive



takeaway #3: probabilistic circuits are a foundation for tractable inference and learning



Learn tractable models
on millions of datapoints
and thousands of features
in tractable time!

Challenge #2

deep theoretical understanding

Trace a precise picture of the whole tractabile spectrum and complete the map of succintness!

Challenge #3

advanced and automated reasoning

Move beyond single probabilistic queries towards fully automated reasoning!

Readings

Probabilistic circuits: Representation and Learning starai.cs.ucla.edu/papers/LecNoAAAI20.pdf

Foundations of Sum-Product Networks for probabilistic modeling tinyurl.com/w65po5d

Slides for this tutorial starai.cs.ucla.edu/slides/ECML20.pdf



Juice.jl advanced logical+probabilistic inference with circuits in Julia github.com/Juice-jl/ProbabilisticCircuits.jl

SumProductNetworks.jl SPN routines in Julia
github.com/trappmartin/SumProductNetworks.jl

SPFlow easy and extensible python library for SPNs github.com/SPFlow/SPFlow

Libra several structure learning algorithms in OCaml **libra.cs.uoregon.edu**

More refs ⇒ github.com/arranger1044/awesome-spn

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