

Semantics of Datalog Languages

CS240B Spring 2002 Notes



From Section 8.8 of *Advanced Database Systems*—Morgan Kaufmann, 1997

Syntax of FOL—the alphabet

1. **Constants.**
2. *Variables.* In addition identifiers beginning with upper case, x , y and z also represent variables in this section.
3. **Functions.** Such as $f(t_1, \dots, t_n)$ where f is an n -ary functor and t_1, \dots, t_n are the arguments.
4. **Predicates.**
5. . The basic: \vee , \wedge , \neg and the derived implication symbol \leftarrow , \rightarrow , and \leftrightarrow .
6. *Quantifiers.* The existential quantifier \exists and the universal quantifier \forall .
7. Parentheses and punctuation symbols, used liberally as needed to avoid ambiguities.

Syntax of First Order Logic–cont.

A *Term* is defined inductively as follows:

- A variable is a term

Syntax of First Order Logic–cont.

A *Term* is defined inductively as follows:

- A variable is a term
- A constant is a term

Syntax of First Order Logic–cont.

A *Term* is defined inductively as follows:

- A variable is a term
- A constant is a term
- If f is an n -ary functor and t_1, \dots, t_n are terms, then $f(t_1, \dots, t_n)$ is a term.

Well-Formed Formulas (WFFs)

1. If p is an n -ary predicate and t_1, \dots, t_n are terms, then $p(t_1, \dots, t_n)$ is a formula (called an *atomic formula* or, more simply, an *atom*).
2. If F and G are formulas, then so are $\neg F$, $F \vee G$, $F \wedge G$, $F \leftarrow G$, $F \rightarrow G$ and $F \leftrightarrow G$.
3. If F is a formula and x is a variable, then $\forall x (F)$ and $\exists x (F)$ are formulas. When so, x is said to be *quantified* in F .

$\exists G_1(\text{took}(N, \text{cs101}, G_1)) \wedge \exists G_2(\text{took}(N, \text{cs143}, G_2)) \wedge$
 $\exists M(\text{student}(N, M, \text{junior}))$

Closed Formulas and Clauses

A WFF F is said to a *closed formula* if every variable occurrence in F is quantified.

The formula in the previous example is not closed. But the following one is.

$$\forall x \forall y \forall z (p(x, z) \vee \neg q(x, y) \vee \neg r(y, z))$$

Definite Clauses

A Definite Clause is a WFF which:

- is closed,
- all its variables are universally quantified, and
- is a disjunction of one positive atom and zero or more negated atoms.

A definite clause is representable with the rule notation:

$$\forall x \forall y \forall z p(x, z) \leftarrow q(x, y), r(y, z).$$

Positive Programs

- A definite clause with an empty body is called a *unit clause*.
- The notation used for unit clauses is “ $A.$ ” instead of the more precise notation “ $A \leftarrow .$ ”
- A *fact* is a unit clause without variables.

A unit clause (everybody loves himself) and three facts:

```
loves(X, X).
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loves(marc, mary).
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loves(mary, tom).
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hates(marc, tom).
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A positive logic program is a set of definite clauses.

Herbrand Interpretations for program P

- The *Herbrand Universe* for P , denoted U_P , is the set of all terms that can be recursively constructed by letting the arguments of the functions be constants in P or elements in U_P
- The *Herbrand Base* of P is defined as the set of atoms that can be built from the predicates by replacing their arguments with elements from U_P
- An *Herbrand Interpretation* is defined by assigning to each n -ary predicate q an n -relation Q , where $q(a_1, \dots, a_n)$ is true iff $(a_1, \dots, a_n) \in Q$.
- Also, every subset of the *Herbrand Base* of P defines an Herbrand interpretation of P

Example

$\text{anc}(X, Y) \leftarrow \text{parent}(X, Y).$
 $\text{anc}(X, Z) \leftarrow \text{anc}(X, Y), \text{parent}(Y, Z)$
 $\text{parent}(X, Y) \leftarrow \text{father}(X, Y).$
 $\text{parent}(X, Y) \leftarrow \text{mother}(X, Y).$
 $\text{mother}(\text{anne}, \text{silvia}). \text{mother}(\text{anne}, \text{marc}).$

Here: $U_P = \{\text{anne}, \text{silvia}, \text{marc}\}$, and

$$B_P = \{\text{parent}(x, y) \mid x, y \in U_P\} \cup \{\text{father}(x, y) \mid x, y \in U_P\} \\ \cup \{\text{mother}(x, y) \mid x, y \in U_P\} \cup \{\text{anc}(x, y) \mid x, y \in U_P\}$$

Example—cont.

$\text{anc}(X, Y) \leftarrow \text{parent}(X, Y).$
 $\text{anc}(X, Z) \leftarrow \text{anc}(X, Y), \text{parent}(Y, Z)$
 $\text{parent}(X, Y) \leftarrow \text{father}(X, Y).$
 $\text{parent}(X, Y) \leftarrow \text{mother}(X, Y).$
 $\text{mother}(\text{anne}, \text{silvia}). \quad \text{mother}(\text{anne}, \text{marc}).$

- Herbrand Base: 4 binary predicates, and for each, 3 possible assignments for each argument: $B_P = 4 \times 3 \times 3 = 36$.
- Herbrand Interpretations (HIs): There are $2^{|B_P|}$ subsets of B_P — 2^{36} for this program.
- With infinite universe we have an infinite number of interpretations.

The Models of a Program

Section 8.9 in *Advanced Database Systems*

Morgan Kaufmann, 1997

Ground Instances of a Rule

Let r be a rule in a program P . $ground(r)$ denotes the set of ground instances of r (i.e., all the rules obtained by assigning to the variables in r , values from the Herbrand universe U_P).

$$\text{parent}(X, Y) \leftarrow \text{mother}(X, Y).$$

With 2 variables and $U_P = 3$, $ground(r)$ has 3×3 rules:

$$\text{parent}(\text{anne}, \text{anne}) \leftarrow \text{mother}(\text{anne}, \text{anne}).$$
$$\text{parent}(\text{anne}, \text{marc}) \leftarrow \text{mother}(\text{anne}, \text{marc}).$$

...

...

$$\text{parent}(\text{silvia}, \text{silvia}) \leftarrow \text{mother}(\text{silvia}, \text{silvia}).$$

Ground version of a program

The ground version of a program P , denoted $ground(P)$, is the set of the ground instances of its rules:

$$ground(P) = \{ground(r) \mid r \in P\}$$

Models of a Program

Let I be an interpretation for a program P . If an atom $a \in I$ we say that a is true, otherwise we say that a is false. Conversely for negated atoms $\neg a$.

Satisfaction: A rule $r \in P$ is said to hold true in interpretation I , or to be satisfied in I , if every instance of r is satisfied in I .

Model. An interpretation I that satisfies all the rules in $ground(P)$ is said to be a model for P

Minimal Models and Least Models

- A model M for a program P is said to be a *minimal model* for P if there exists no other model M' of P where $M' \subset M$.
- A model M for a program P is said to be its *least model* if every model M' of P has the property that $M' \supseteq M$.

Model Intersection Property. Let P be a positive program, and M_1 and M_2 be two models for P . Then, $M_1 \cap M_2$ is also a model for P .

Theorem: Every positive program has a least model.