Beyond Stratification

CS240B Notes



Notes based on Section 10.4 of Advanced Database Systems-Morgan Kaufmann, 1997

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- Many proposals—e.g., locally stratified programs and well founded models—on how to go beyond stratified negation
- Objective is to approach the power of stable model, without its exponential complexity.
- also the semantic well-formedness of the program can be determined from the rules (independent of the DB) as for stratified programs
- XY-stratification: is a particular class of locally stratified programs for which we also have a simple compile-time check, and an efficient implementation
- In fact, XY-stratified programs are particular Datalog_{1s} programs.

Stratification by the Temporal Argument

Ancestors of marc and their generation gap expressed using the differential fixpoint:

$$\begin{array}{ll} r_1: \texttt{delta_anc(0, marc)}.\\ r_2: \texttt{delta_anc}(\texttt{J}+\texttt{1},\texttt{Y}) \leftarrow & \texttt{delta_anc}(\texttt{J},\texttt{X}), \texttt{parent}(\texttt{Y},\texttt{X}), \\ & \neg\texttt{all_anc}(\texttt{J},\texttt{Y}).\\ r_3: \texttt{all_anc}(\texttt{J}+\texttt{1},\texttt{X}) \leftarrow & \texttt{all_anc}(\texttt{J},\texttt{X}).\\ r_4: \texttt{all_anc}(\texttt{J},\texttt{X}) \leftarrow & \texttt{delta_anc}(\texttt{J},\texttt{X}). \end{array}$$

Stratification by the temporal Argument: cont.

- 1. This program is locally stratified by the first argument in anc that serves as temporal argument.
- 2. The zero stratum consists of atoms of nonrecursive predicates such as parent and of atoms that unify with all_anc(0, X) or delta_anc(0, X), where X can be any constant in the universe
- 3. The k^{th} stratum contains atoms all_anc(k,X) and delta_anc(k,X).

Thus, this program is locally stratified, since the heads of recursive rules belong to strata that are one above those of their goals.

- r is an X-rule when the temporal argument (TA) in every recursive predicate in r is the same variable (e.g., J),
- r is a Y-rule when for some variable J
 - 1. the head of r has J + 1 as its TA
 - 2. some goal of r has as TA J, and
 - 3. the remaining recursive goals have either J or J + 1 as their TAs.

XY-programs: Let P be a set of rules defining mutually recursive predicates. Then we say that P is an XY-program when:

- 1. Every recursive predicate of *P* has a distinguished temporal argument.
- 2. Every recursive rule r is either an X-rule or a Y-rule.

Given an XY -program P, its *bi-state program*, P_{bis} , is computed as follows: For each $r \in P$,

- 1. Rename all the recursive predicates in r that have the same temporal argument as the head of r with the distinguished prefix new_{-} .
- 2. Rename all other occurrences of recursive predicates in r with the distinguished prefix old_.
- 3. Drop the temporal arguments from the recursive predicates.

Definition: Let *P* be an XY-program. *P* is said to be XY-stratified when P_{bis} is a stratified program.

Our previous program is stratified with the following strata:

Theorem: Let P be an XY-stratified program. Then P has a unique stable model.

Computing the stable model of an XY-stratified program P

Inititialize: Set T = 0 and insert the fact counter(T). Forever repeat the following two steps:

- Apply the iterated fixpoint computation to the synchronized program P_{bis}, and for each recursive predicate q, compute new_q. Return the new_q atoms so computed, after adding a temporal argument T to these atoms; the value of T is taken from counter(T).
- 2. For each recursive predicate q, replace old_q with new_q, computed in the previous step. Then, replace counter(T) with counter(T + 1).
- Copy rules
- When does the computation stop?

Classical Algorithms can be Expressed as XY-stratified programs

A simple example: Coalescing after Temporal Projection.

emp_dep_sal(1001, shoe, 35000, 19920101, 19940101). emp_dep_sal(1001, shoe, 36500, 19940101, 19960101).

These two tuples must be merged.

Merging overlapping periods after a temporal projection

 $e_{hist}(0, Eno, Frm, To) \leftarrow$ emp_dep_sal(0, Eno, D, S, Frm, To). $overlap(J + 1, Eno, Frm1, To1, Frm2, To2) \leftarrow$ e_hist(J, Eno, Frm1, To1), e_hist(J, Eno, Frm2, To2), $\texttt{Frm1} \leq \texttt{Frm2}, \texttt{Frm2} \leq \texttt{To1},$ distinct(Frm1, To1, Frm2, To2). $\texttt{e_hist}(\texttt{J},\texttt{Eno},\texttt{Frm1},\texttt{To}) \leftarrow$ overlap(J, Eno, Frm1, To1, Frm2, To2 select_larger(To1, To2, To). $e_hist(J+1, Eno, Frm, To) \leftarrow e_hist(J, Eno, Frm, To),$ $overlap(J + 1, _, _, _, _, _),$ $\neg \text{overlap}(J + 1, \text{Eno}, \text{Frm}, \text{To}, _, _),$ $\neg \text{overlap}(J + 1, \text{Eno}, _, _, \text{Frm}, \text{To}).$ $final_e_hist(Eno, Frm, To) \leftarrow e_hist(J, Eno, Frm, To),$ $\neg e_{hist}(J + 1, .., ..).$ – p.10/11

Temporal Projection–auxiliary predicates

 $\begin{array}{lll} \texttt{distinct}(\texttt{Frm1},\texttt{To1},\texttt{Frm2},\texttt{To2}) \leftarrow & \texttt{To1} \neq \texttt{To2}.\\ \texttt{distinct}(\texttt{Frm1},\texttt{To1},\texttt{Frm2},\texttt{To2}) \leftarrow & \texttt{Frm1} \neq \texttt{Frm2}.\\ \texttt{select_larger}(\texttt{X},\texttt{Y},\texttt{X}) \leftarrow & \texttt{X} \geq \texttt{Y}.\\ \texttt{select_larger}(\texttt{X},\texttt{Y},\texttt{Y}) \leftarrow & \texttt{Y} > \texttt{X}. \end{array}$