

JOLT: REDUCING OBJECT CHURN

AJ Shankar, Matt Arnold, Ras Bodik
UC Berkeley, IBM Research | OOPSLA 2008

What is Object Churn?

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Allocation of intermediate objects with short lifespans

[Mitchell, Sevitsky 06]

```
int foo() {  
    return bar().length;  
}  
String bar() {  
    return new String("foobar");  
}
```



String

Churn is a Problem

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- A natural result of abstraction
 - ▣ Common in large component-based applications
- Reduces program performance
 - ▣ Puts pressure on GC
 - ▣ Inhibits parallelization (temp objects are synchronized)
 - ▣ Requires unnecessary CPU cycles
- Hard to eliminate
 - ▣ **Escape analysis?** Objects escape allocating function
 - ▣ Refactoring? It requires cross-component changes

What is escape analysis?

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- Typical defensive copying approach to returning a compound value

```
public class Point {
    private int x, y;
    public Point(int x, int y) {
        this.x = x; this.y = y;
    }
    public Point(Point p) { this(p.x, p.y); }
    public int getX() { return x; }
    public int getY() { return y; }
}

public class Component {
    private Point location;

    public Point getLocation() { return new Point(location); }

    public double getDistanceFrom(Component other) {
        Point otherLocation = other.getLocation();
        int deltaX = otherLocation.getX() - location.getX();
        int deltaY = otherLocation.getY() - location.getY();
        return Math.sqrt(deltaX*deltaX + deltaY*deltaY);
    }
}
```

What is escape analysis? cont'd

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- A smart JVM can see what is going on and **optimize away the allocation of the defensive copy**

```
public double getDistanceFrom(Component other) {  
    Point otherLocation = new Point(other.x, other.y);  
    int deltaX = otherLocation.x - location.x;  
    int deltaY = otherLocation.y - location.y;  
    return Math.sqrt(deltaX*deltaX + deltaY*deltaY);  
}
```

What is escape analysis? cont'd

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- Point is truly thread-local and its lifetime is known to be bounded by the basic block, it can be either stack-allocated or optimized away entirely.

```
public double getDistanceFrom(Component other) {  
    int tempX = other.x, tempY = other.y;  
    int deltaX = tempX - location.x;  
    int deltaY = tempY - location.y;  
    return Math.sqrt(deltaX*deltaX + deltaY*deltaY);  
}
```

Jolt: Our Contribution

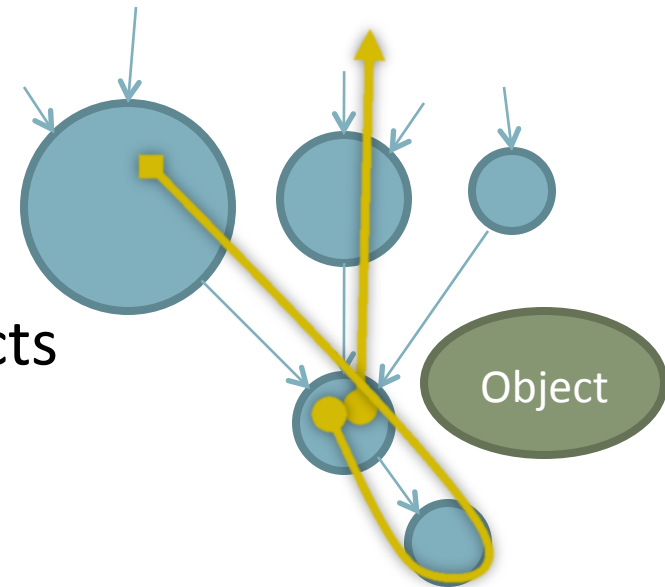
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- Automatic runtime churn reduction (in a JIT compiler)
 - ▣ Lightweight dynamic analyses, simple optimization
- Implemented in IBM's J9 JVM
 - ▣ Ran on large component-based benchmarks
- Removes 4x as many allocs as escape analysis alone
 - ▣ Speedups of up to 15%

Objects Escape Allocation Context

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- Traditional EA: hands tied
- Several escape analyses explore up the stack to add context [Blanchet 99, Whaley 99, Gay 00]
- Object allocation optimization based on escape analysis
 - ▣ Do not perform well component-based applications
 - ▣ Largely because many churn objects escape their allocating functions



Houston, We Have a Solution

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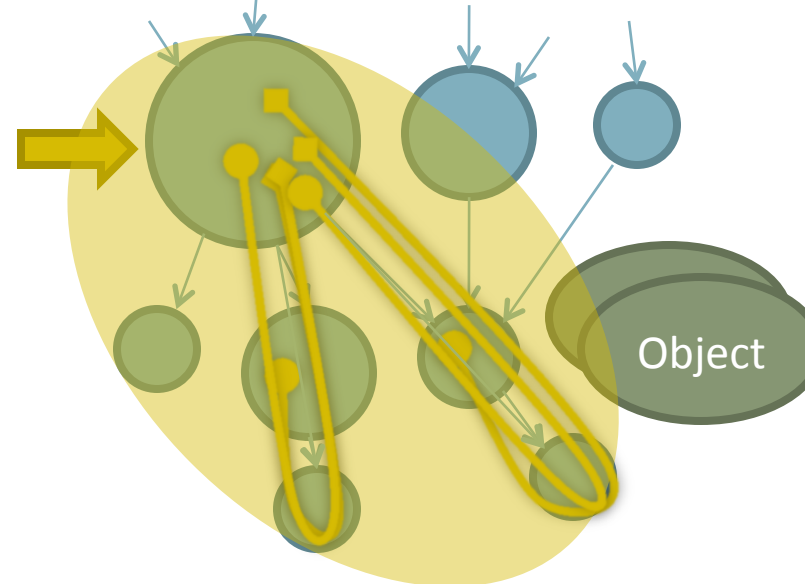
Jolt uses a two-part solution:

➔ 1. Dynamic analyses find churn-laden subprograms

- Rooted at a function
 - Only as many contexts as functions in program
- Subprograms can contain many churned objects

➔ 2. Selectively inline portions of subprogram into root to create context

- Churned objects no longer escape context
- Can now run escape analysis



Step 1: Find Roots: Churn Analysis

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- Goal: Identify roots of churn-laden subprograms
 - ▣ Operate on static call graph (JIT's domain)
 - ▣ Use dynamic heap information to track churn
- Use three dynamic analyses inspired by [Dufour 07]:
 - ▣ Capture
 - ▣ %Capture
 - ▣ %Control

Capture

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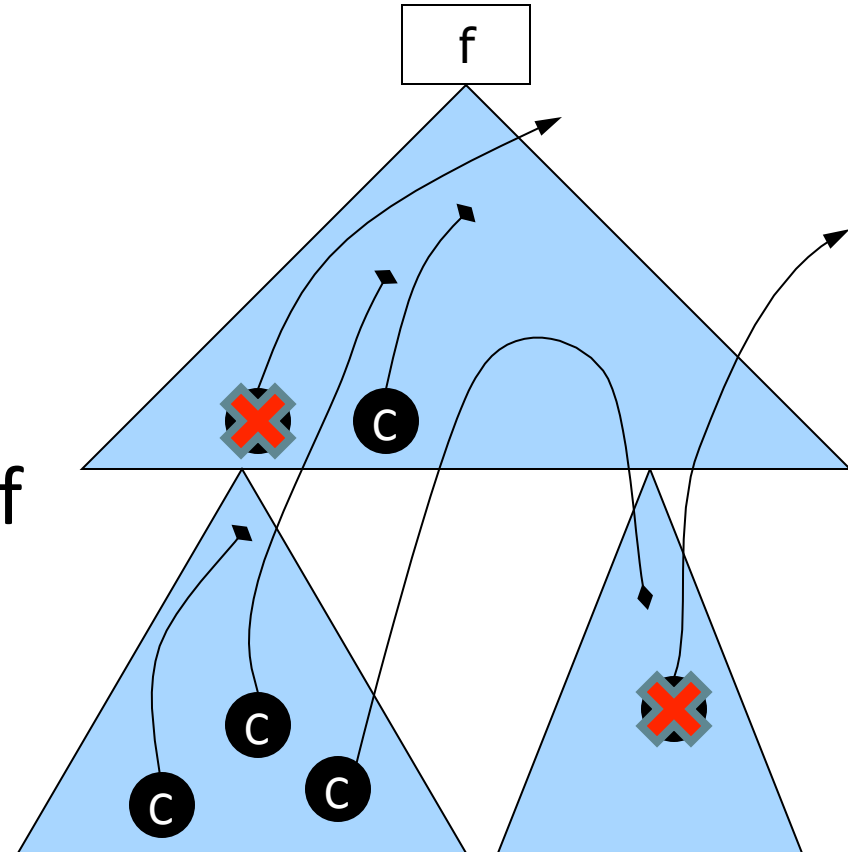
Capture(f) = # objs allocated by f or descendants that die before f returns

In example:

Capture(f) = 4

Answers: Enough churn in the subprogram rooted at f to be worth optimizing?

High Capture \rightarrow YES



%Capture

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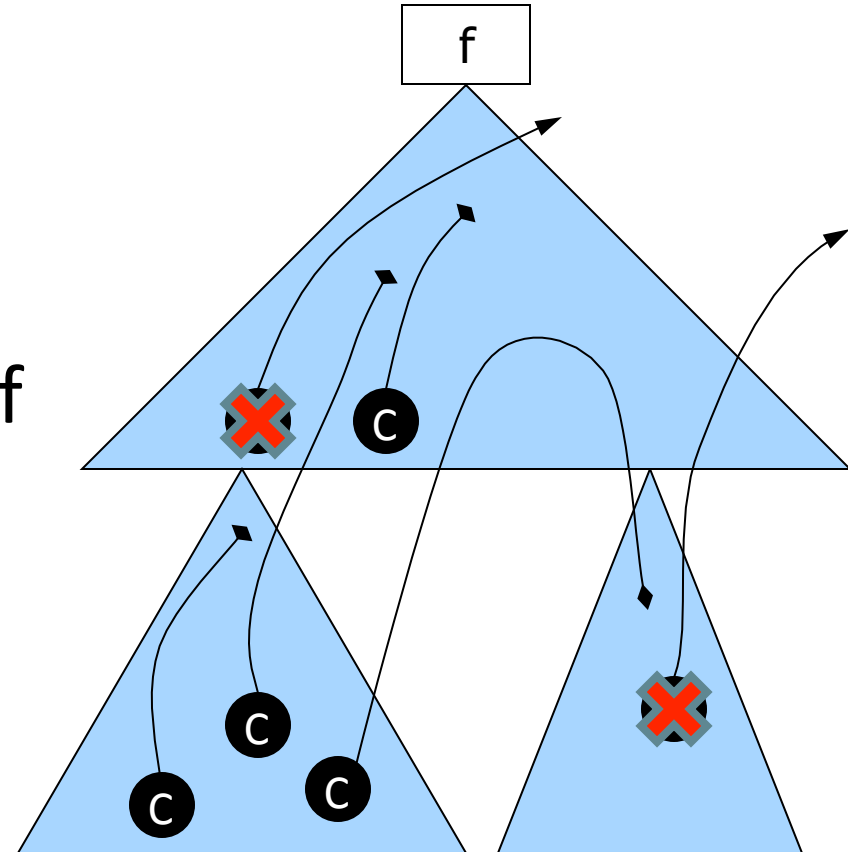
$\% \text{Capture}(f) = \% \text{ objs allocated by } f \text{ or descendants}$
that die before f returns

In example:

$$\% \text{Capture}(f) = 4/6$$

Answers: Better to root at f
than at parent of f ?

High %Capture \rightarrow YES



%Control

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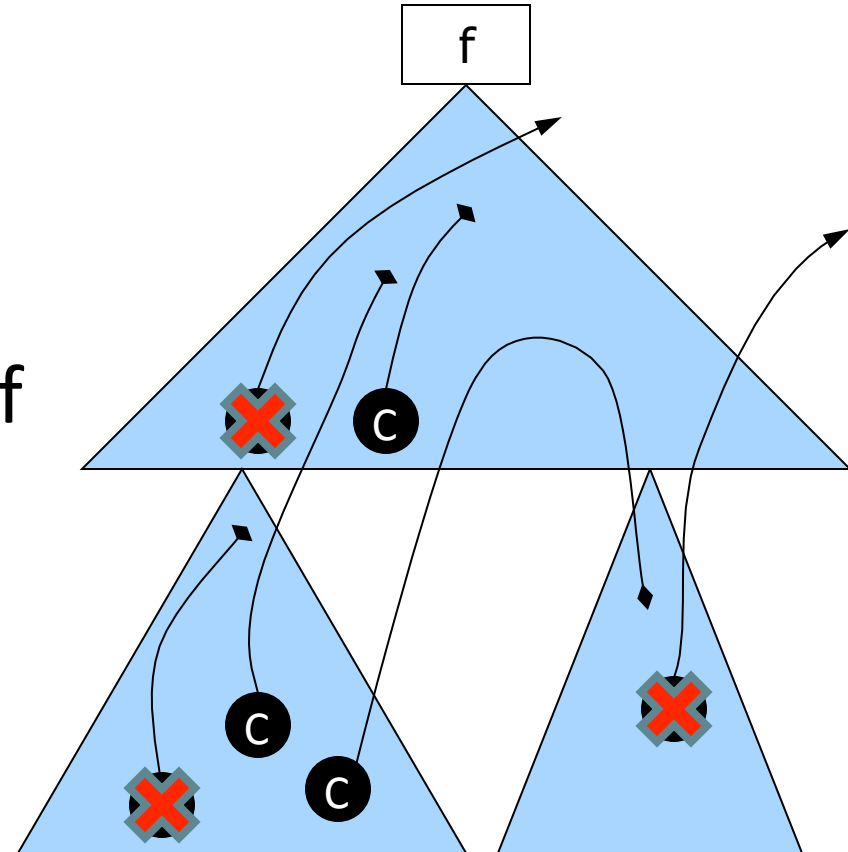
$\%Control(f)$ = % objs allocated that are captured by f
but not captured by descendants

In example:

$$\%Control(f) = 3/6$$

Answers: Better to root at f
than at child of f ?

High %Control \rightarrow YES



All Together Now

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- Three analyses together pinpoint subprogram root

High Capture:

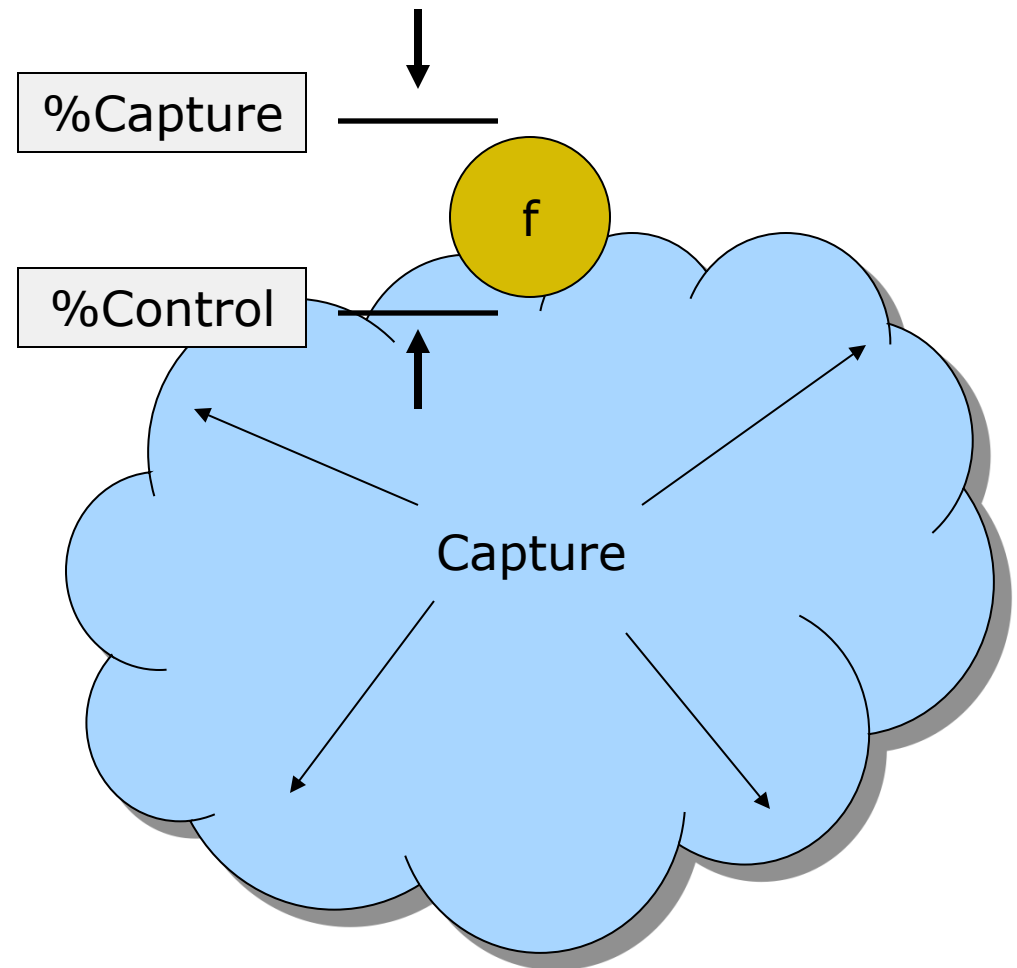
Worth optimizing

High %Capture:

Better f than parent

High %Control:

Better f than child



How to Compute Analyses

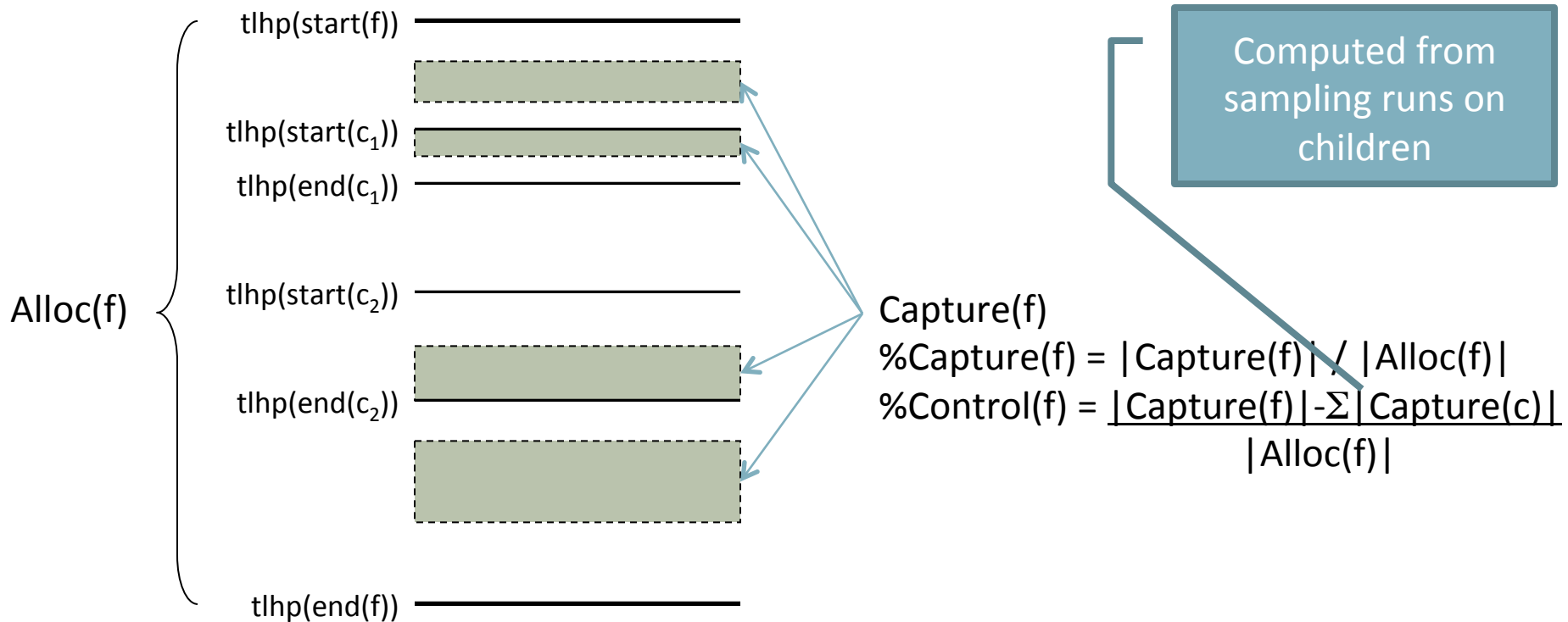
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- Goals:
 - ▣ Efficient runtime mechanism
 - ▣ Thread-safe
 - ▣ Simple to add to existing JIT code
- Solution: Track heap allocation pointer, GC
 - ▣ Requires thread-local heaps (TLHs) & copy collector
 - Supported by virtually all modern JVMs
 - ▣ Alternative solution works for any JVM + GC
 - Details in Appendix

Computing Analyses with TLHs

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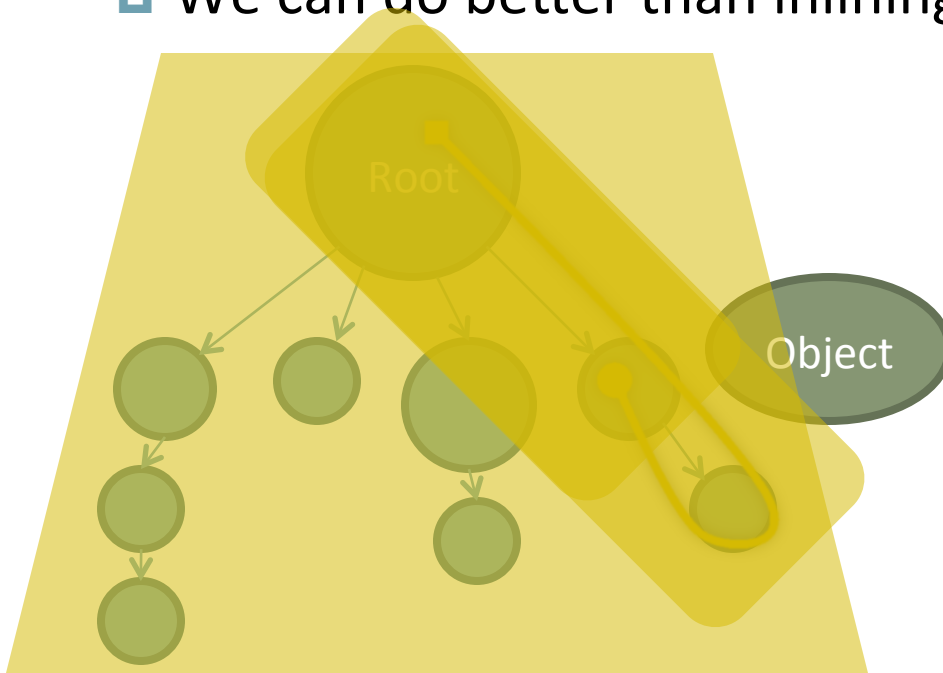
1. Choose to sample function f
2. Track thread local heap alloc pointer through f 's child calls
3. Run GC at the end of f
4. Compute capture and control



Step 2: Optimize: Smart Inlining

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- Churn analyses identified subprogram roots
- Now, inline subprogram to expose allocs to EA
 - ▣ Respect JIT optimization constraints (size bound)
 - ▣ We can do better than inlining whole subprogram

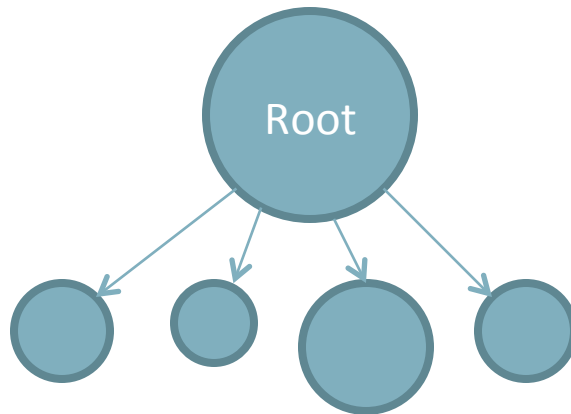


Only need to inline
functions that add churned
allocation sites to root

Step 2: Optimize: Smart Inlining

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- Goal: inline descendants that expose most # of churned allocs to EA
 - ▣ While still respecting size bound
- NP-Hard problem! (can solve Knapsack)

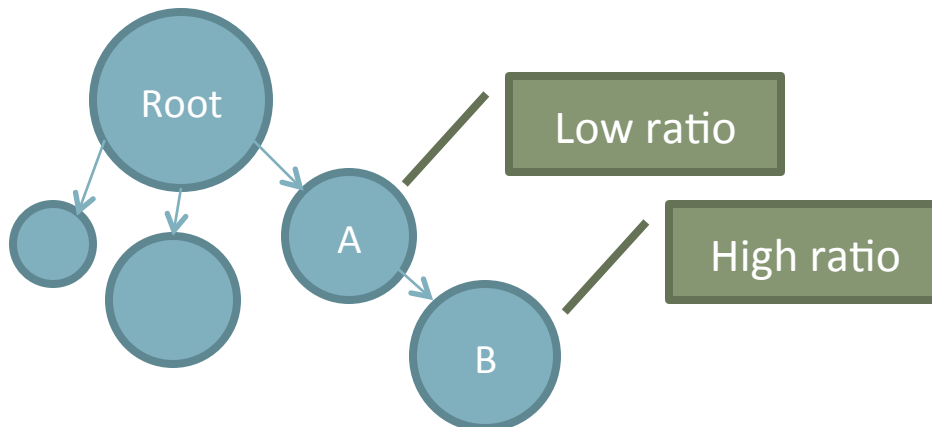
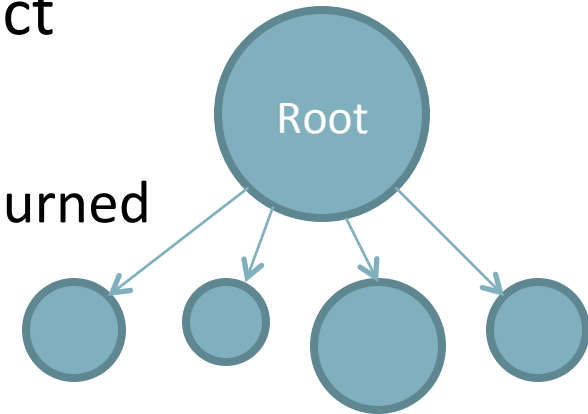


Which children to inline to get closest to size bound without exceeding it?

Knapsack Approximation

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- Simple poly-time approximation:
 - ▣ Inline child with greatest ratio of object allocations to code size
 - $\uparrow \%capture(f) \Rightarrow$ objs alloc'd in c are churned
 - ▣ Repeat until size limit is reached
 - ▣ But greedy = short-sighted!

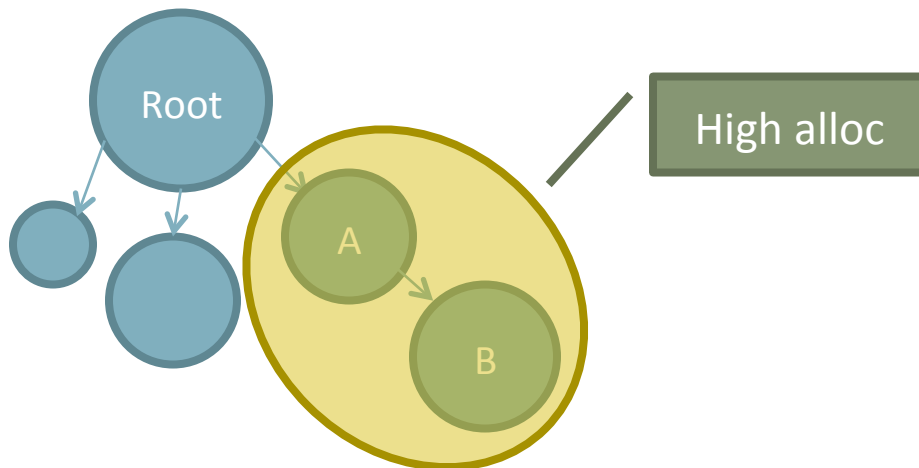


B will never be inlined because A will never be inlined

Churn Analyses to the Rescue

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- Would like to inline child if *its subprogram* has churn elimination potential
- We already have an approximation: $\text{alloc}(c)$
 - ▣ Recall that $\text{alloc}(c)$ is num allocs in entire subprogram
- So: feed Knapsack approx $\text{alloc}(c)$ instead of number of local object allocations in c



A inlined because subprogram has high alloc; then B inlined

Eliminating Allocations

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- Once descendants have been inlined, pass to Escape Analysis
 - ▣ Use JIT's existing EA
 - ▣ Because of smart inlining, objects' allocation sites in `f`, lifetimes don't escape `f`
 - ▣ EA eliminates allocations via stack allocation or scalar replacement
 - ▣ Bonus: improvements in EA == better JOLT

Experimental Methodology

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- Implemented Jolt in IBM's J9 JVM
- Fully automatic, transparent
- Ran on large-scale benchmarks
 - ▣ Eclipse
 - ▣ JPetStore on Spring
 - ▣ TPC-W on JBoss
 - ▣ SPECjbb2005
 - ▣ DaCapo

Results

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Program	Base %Objs Elim
Eclipse	0.4%
JPetStore on Spring	0.7%
TPCW on JBoss	0.0%
SPECjbb2005	9.6%
DaCapo	3.4%

- EA performs poorly on large component-based apps
- Median ratio: 4.3x as many objects removed by Jolt
 - ▣ Still many more to go
- Median speedup: 4.8%

Additional Experiments

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- Runtime overhead acceptable
 - ▣ Average compilation overhead: 32% longer
 - Acceptable for long-running programs (< 15 s)
 - Often outweighed by speedup
 - ▣ Average profiling overhead: 1.0%
 - Run at 1 sample per 100k function invocations
- Combination of churn analyses and inlining performs better than either alone
 - ▣ In every case, Jolt outperformed separate configurations

Summary

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- Jolt reduces object churn
 - ▣ Transparently at runtime
 - ▣ In large applications
 - ▣ Easy to implement
 - Uses existing JIT technologies heavily
- Two-part approach
 - ▣ Dynamic churn analyses: capture and control
 - Pinpoint roots of good subprograms
 - ▣ Smart inlining
 - Uses analyses and Knapsack approximation to inline beneficial functions into root
- Thanks!