CS 289 Communication Complexity Instructor: Alexander A. Sherstov Handout: Separating hyperplane theorem

Strict separation

For $x, y \in \mathbb{R}^n$, we write d(x, y) = ||x - y||. For subsets $A, B \subseteq \mathbb{R}^n$, we define $d(A, x) = d(x, A) = \inf_{a \in A} d(x, a)$ and $d(A, B) = \inf_{a \in A, b \in B} d(a, b)$. Let diam $A = \sup_{x,y \in A} d(x, y)$. For $A \subseteq \mathbb{R}^n$ and $x \in \mathbb{R}^n$, we define $\langle A, x \rangle = \{\langle a, x \rangle : a \in A\}$. In Euclidean space \mathbb{R}^n , the term *compact set* refers to any set that is closed and bounded.

Theorem 1 (Separating hyperplane theorem, strict case). Let $C, K \subseteq \mathbb{R}^n$ be nonempty convex sets with $C \cap K = \emptyset$. If C is closed and K compact, then there exists $\psi \in \mathbb{R}^n$ with

$$\inf \langle C, \psi \rangle > \sup \langle K, \psi \rangle.$$

Proof. The strategy of the proof is illustrated in Figure 1. We start by proving the existence of a pair of closest points x^* and y^* , where $x \in C$ and $y \in K$. We then show that the hyperplane with normal vector $\psi = x^* - y^*$ separates the two convex sets. Details follow.

Claim 2. There exist $x^* \in C$ and $y^* \in K$ such that $d(x^*, y^*) = d(C, K)$.

Proof. For this, pick an arbitrary point $x_0 \in C$ and define $r = 2d(x_0, K) + \text{diam } K$. By the triangle inequality, $d(x, x_0) \leq d(x, K) + \text{diam } K + d(x_0, K)$. It follows that any point x with $d(x, x_0) > r$ satisfies

$$d(x, K) \ge d(x, x_0) - \operatorname{diam} K - d(x_0, K)$$

> $d(x_0, K)$.

As a result, the compact set $C' = C \cap \{x : d(x, x_0) \leq r\}$ obeys d(C, K) = d(C', K). Since $d(\cdot, \cdot)$ is a continuous function on the compact $C' \times K$, it must attain its infimum on $C' \times K$, i.e., there must exist $(x^*, y^*) \in C' \times K$ with $d(x^*, y^*) = d(C', K) = d(C, K)$.

In the remainder of the proof, fix x^* and y^* as in Claim 2, and define $\psi = x^* - y^*$.

Claim 3. inf $\langle C, \psi \rangle \ge \langle x^*, \psi \rangle$.



Figure 1: Separating two convex sets by a hyperplane.

Proof. For the sake of contradiction, suppose that $\langle x, \psi \rangle < \langle x^*, \psi \rangle$ for some $x \in C$. This is equivalent to

$$\langle x - x^*, x^* - y^* \rangle < 0. \tag{1}$$

For $\varepsilon \in (0, 1)$, the point $x_{\varepsilon} = (1 - \varepsilon)x^* + \varepsilon x$ is contained in C by convexity. However,

$$||x_{\varepsilon} - y^*||^2 = \langle x^* - y^* + \varepsilon(x - x^*), x^* - y^* + \varepsilon(x - x^*) \rangle$$

= $||x^* - y^*||^2 + 2\varepsilon \underbrace{\langle x - x^*, x^* - y^* \rangle}_{<0 \text{ by (1)}} + \varepsilon^2 ||x - x^*||^2.$

Hence $d(x_{\varepsilon}, y^*) < d(x^*, y^*)$ for $\varepsilon > 0$ small enough, contradicting $d(x^*, y^*) = d(C, K)$.

Claim 4. $\langle x^*, \psi \rangle > \langle y^*, \psi \rangle$.

Proof. We have $\langle x^* - y^*, \psi \rangle = ||x^* - y^*||^2 > 0$, where the last step uses the fact that $x^* \neq y^*$ by the disjointness of C and K.

Claim 5. $\langle y^*, \psi \rangle \ge \sup \langle K, \psi \rangle$.

Proof. The proof is analogous to Claim 3. Specifically, suppose for the sake of contradiction that $\langle y, \psi \rangle > \langle y^*, \psi \rangle$ for some $y \in K$. This is equivalent to

$$\langle y^* - y, x^* - y^* \rangle < 0. \tag{2}$$

For $\varepsilon \in (0, 1)$, the point $y_{\varepsilon} = (1 - \varepsilon)y^* + \varepsilon y$ is contained in K by convexity. However,

$$||x^* - y_{\varepsilon}||^2 = \langle x^* - y^* + \varepsilon(y^* - y), x^* - y^* + \varepsilon(y^* - y) \rangle$$

= $||x^* - y^*||^2 + 2\varepsilon \underbrace{\langle y^* - y, x^* - y^* \rangle}_{<0 \text{ by } (2)} + \varepsilon^2 ||y^* - y||^2.$

Hence $d(x^*, y_{\varepsilon}) < d(x^*, y^*)$ for $\varepsilon > 0$ small enough, contradicting $d(x^*, y^*) = d(C, K)$.

By Claims 3–5, the proof is complete.

Nonstrict separation

The proofs below use the following property of compact sets $K \subset \mathbb{R}^n$: given any sequence $x_1, x_2, \ldots, x_n, \ldots \in K$, there is a subsequence $x_{i_1}, x_{i_2}, \ldots, x_{i_n}, \ldots$ and some $x^* \in K$ such that $x_{i_n} \to x^*$ as $n \to \infty$. In other words, every sequence in a compact set has a convergent subsequence. The *closure* of a set $A \subseteq \mathbb{R}^n$ is a superset of A defined by $cl A = \{x \in \mathbb{R}^n : d(x, A) = 0\}$. Put differently, cl A is the smallest closed set that contains A. A point x is called an *interior* point of A if there exists $\varepsilon > 0$ such that $\{y \in \mathbb{R}^n : d(x, y) < \varepsilon\} \subseteq A$. The set of all interior points of A is denoted int A.

Lemma 6. Let $M \in \mathbb{R}^{n \times (n+1)}$ be given by

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & -1 \\ \vdots & \vdots & \vdots & \ddots & 0 & -1 \\ 0 & 0 & 0 & & 1 & -1 \end{bmatrix}.$$

Let $\{M_k\}$ be a sequence with $M_k \to M$. Then for some k, there exists a vector $\lambda \in (0, \infty)^{n+1}$ with $M_k \lambda = 0$.

Proof. Since the nullspace of every M_k is nonempty, we can fix a sequence $\{\lambda_k\}$ of unit vectors with $M_k\lambda_k = 0$. By passing to a subsequence if necessary, we may assume that $\lambda_k \to \lambda^*$. But then λ^* is a unit vector with $M\lambda^* = 0$, which forces

$$\lambda^* = \frac{\pm 1}{\sqrt{n+1}} \begin{bmatrix} 1\\1\\\vdots\\1 \end{bmatrix}.$$

In particular, for all k large enough, the components of λ_k are either all positive or all negative, so that either λ_k or $-\lambda_k$ is the desired vector.

Theorem 7 (Separating hyperplane theorem, nonstrict case). Let $X, Y \subseteq \mathbb{R}^n$ be nonempty convex subsets. If $X \cap Y = \emptyset$, then there exists a nonzero $\psi \in \mathbb{R}^n$ with

$$\inf \langle X, \psi \rangle \ge \sup \langle Y, \psi \rangle.$$



Figure 2: Separating 0 from *B* by a hyperplane.

Proof. Consider the convex set $A = X - Y = \{x - y : x \in X, y \in Y\}$. Then $0 \notin A$, and our objective is to find a nonzero $\psi \in \mathbb{R}^n$ with $\inf \langle A, \psi \rangle \ge 0$. Let $B = \operatorname{cl} A$ be the closure of A.

First of all, we claim that $0 \notin \text{int } B$. For the sake of contradiction, suppose otherwise. Then for $\varepsilon > 0$ small enough, B contains the ball $\{v : ||v||_{\infty} \leqslant \varepsilon\}$. In particular, B contains $\varepsilon v_1, \varepsilon v_2, \ldots, \varepsilon v_{n+1}$, where v_i is the *i*th column of the matrix M in Lemma 6. Recall that each v_i is the limit of a sequence in A. By Lemma 6, it follows that some $\tilde{v}_1, \tilde{v}_2, \ldots, \tilde{v}_{n+1} \in A$ obey $\sum \lambda_i v_i = 0$ for some positive coefficients $\lambda_1, \lambda_2, \ldots, \lambda_{n+1}$. Since A is convex, we conclude that $0 \in A$, a contradiction. Hence $0 \notin \text{int } B$, as claimed.

The remainder of the proof is illustrated in Figure 2. By the claim just settled, we can fix a sequence of points $\{z_k\}$ outside of B with $z_k \to 0$. By the strict version of the separating hyperplane theorem, for each k there exists a unit vector ψ_k with

$$\inf \langle B, \psi_k \rangle > \langle z_k, \psi_k \rangle. \tag{3}$$

Passing to a subsequence if necessary, we may assume that $\psi_k \to \psi$ for some unit vector ψ . We now claim that $\inf \langle B, \psi \rangle \ge 0$. Indeed, for every $v \in B$,

$$\begin{aligned} \langle v, \psi \rangle &= \lim_{k \to \infty} \langle v, \psi_k \rangle & \text{since } \psi_k \to \psi \\ &\geqslant \lim_{k \to \infty} \langle z_k, \psi_k \rangle & \text{by (3)} \\ &= 0 & \text{since } \|\psi_k\| = 1 \text{ and } z_k \to 0. \end{aligned}$$