

# Probabilistic Programming in Scala

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# What is a PPL?

- ▶ Probabilistic graphical models (Bayesian networks) important in machine learning, statistics, robotics, vision, biology, neuroscience, artificial intelligence (AI) and cognitive science.
- ▶ **Probabilistic Programming Languages** unify general purpose programming with probabilistic modeling
- ▶ Examples
  - ▶ Functional, extending Scheme (Church) or Scala (Figaro, FACTORIE, ScalaPPL)
  - ▶ Logical, extending Prolog (ProbLog, PRISM, BLOG, Dyna)
  - ▶ Extending C# (Infer.NET)
- ▶ Tasks
  - ▶ Compute probabilities, most likely assignments given observations
  - ▶ Learn parameters and programs
- ▶ Applications in natural language processing, computer vision, machine learning, bioinformatics, probabilistic planning, seismic monitoring, . . .

# PPLs: The Easy Case

## Idea behind functional PPLs

Any function  $(A, B, \dots) \Rightarrow R$  can also operate on probability distributions  $(\text{Distr}[A], \text{Distr}[B], \dots) \Rightarrow \text{Distr}[R]$

## Starting Point

Many library functions operate on Booleans:

- ▶ `&&`, `||`, `!`, `==`, `!=`
- ▶ `exists`, `forall`

## Idea

1. Make a version of those functions that operates on distributions and returns a `Distr[Boolean]`.
2. Extend with probabilistic data structures.
3. Use them to model complex probability distributions.

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# Examples



# Boolean formulae

- ▶ Random Variables are objects (each object independent)

```
val a = Flip(0.3)
val b = Flip(0.6)
```

- ▶ BooleanDistr has member functions that build Formula objects.

```
val xor = a && !b || !a && b
```

- ▶ Run inference on BooleanDistr

```
println("Probability = " + xor.probability())
```

```
Probability = 0.54
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## 2-state weather HMM

```
abstract class Timestep {
  def rainy: BooleanDistr
  def umbrella = If(rainy, Flip(0.9), Flip(0.1))
}

object StartState extends Timestep {
  val rainy = Flip(0.2)
}

class SuccessorState(predecessor: Timestep) extends Timestep {
  val rainy = If(predecessor.rainy, Flip(0.5), Flip(0.1))
}
```

```
var timestep: Timestep = StartState
for(i <- 1 until 2000) timestep = new SuccessorState(timestep)
```

```
println("Probability = " + timestep.umbrella.probability())
```

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# Probabilistic Data Structures

- ▶ Probabilistic List: objects are in the list with a certain probability, given by a BooleanDistr

```
trait ListDistr[T] extends Distribution[List[T]]{  
  def forall(f: T => BooleanDistr) : BooleanDistr  
  def exists(f: T => BooleanDistr) : BooleanDistr  
}
```

- ▶ Replace all Boolean by BooleanDistr in member functions
- ▶ Many possibilities (Set, Tree, ...)



# Probabilistic Graphs

- ▶ Viral marketing
- ▶ Learning biological pathways
- ▶ Spread of influence in social networks

```
class Person {  
  val influencedFriends = new ListDistr[Person]  
  def influences(target: Person): BooleanDistr = {  
    if(target == this) True  
    else friends.exists(_.influences(target))  
  }  
}
```

```
val p1,p2,p3,p4,p5,p6 = new Person  
  
val influence1to2 = Flip(0.9)  
n1.influencedFriends += (influence1to2, p2)  
n2.influencedFriends += (influence1to2, p1)  
...
```

```
println("Probability = " + p1.influences(p4).probability())
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# Probabilistic Values

- ▶ Model any discrete distribution

```
class ValDistr[T] extends Distribution[T]{  
  def ==(v: T): BooleanDistr  
  def map[R](f: T => ValDistr[R]): ValDistr[R]  
}
```

- ▶ Apply any deterministic function to ValDistr arguments

```
def Apply[A,R](f: (A) => R)(a: ValDistr[A]): ValDistr[R]  
def Apply[A,B,R](f: (A,B) => R) ...  
...
```

## Example

- ▶ Two dice: probability that their sum is 8?

```
val die1 = Uniform(1 to 6)  
val die2 = Uniform(1 to 6)  
  
val sum = Apply(_+_)(die1,die2)  
  
println("Probability = " + (sum == 8).probability())
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```

## 3-state weather HMM

```
object Sunny extends Weather
object Foggy extends Weather
object Rainy extends Weather

abstract class Timestep {
  def weather: ValDistr[Weather]
  def umbrella = weather.map{
    case Sunny => Flip(0.1)
    case Foggy => Flip(0.3)
    case Rainy => Flip(0.8)
  }
}

object StartState extends Timestep {
  val weather = ValDistr((0.3,Sunny), (0.3,Foggy), (0.4,Rainy))
}

class SuccessorState(predecessor: Timestep) extends Timestep {
  val weather = predecessor.weather.map{
    case Sunny => ValDistr((0.8,Sunny), (0.15,Foggy), (0.05,Rainy))
    case Foggy => ValDistr((0.05,Sunny), (0.3,Foggy), (0.65,Rainy))
    case Rainy => ValDistr((0.15,Sunny), (0.35,Foggy), (0.5,Rainy))
  }
}
```



# Why Scala for Probabilistic Programming?

- ▶ Probabilistic programming as a library
  - ▶ No separate compiler or VM
- ▶ mixin DSL
- ▶ Higher-order functions and generics
  - ▶ Pass existing deterministic code to probabilistic model
  - ▶ Memoization for efficient inference
- ▶ Object-oriented easy to model probabilistic databases
- ▶ Other advantages carry over to the probabilistic case

Thanks