Bit Blasting Probabilistic Programs

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Probabilistic programming languages (PPLs) are expressive means for creating and reasoning about probabilistic models. Unfortunately *hybrid* probabilistic programs, involving both continuous and discrete structures, are not well supported by today's PPLs. In this paper we develop a new approximate inference algorithm for hybrid probabilistic programs that first discretizes the continuous distributions and then performs discrete inference on the resulting program. The key novelty is a form of discretization that we call *bit blasting*, which uses a binary representation of numbers such that a domain of 2^b discretized points can be succinctly represented as a discrete probabilistic program over $poly(b)$ Boolean random variables. Surprisingly, we prove that many common continuous distributions can be bit blasted in a manner that incurs no loss of accuracy over an explicit discretization and supports efficient probabilistic inference. We have built a probabilistic programming system for hybrid programs called HyBit, which employs bit blasting followed by discrete probabilistic inference. We empirically demonstrate the benefits of our approach over existing sampling-based and symbolic inference approaches.

CCS Concepts: • **Mathematics of computing → Probabilistic inference problems**.

Additional Key Words and Phrases: discretization, bit blasting, probabilistic inference

1 INTRODUCTION

Probabilistic programming languages (PPLs) are an expressive means for creating and reasoning about probabilistic models. Many such models are naturally *hybrid*, involving both continuous (e.g., Gaussian distributions) and discrete structures (e.g., Bernoulli random variables, if statements and other control flow). For example, hybrid models arise in applications such as medical diagnosis, gene expression and cyber-physical systems [Chen et al. 2020; Lee and Seshia 2017].

Unfortunately, hybrid programs are not well supported by today's PPLs. The primary analysis task in probabilistic programming languages is *probabilistic inference*, computing the probability that an event occurs according to the distribution defined by the program. Existing inference algorithms employ forms of sampling to perform approximate inference. Some approaches, notably Hamiltonian Monte Carlo used in the PPLs Pyro and Stan [Bingham et al. 2018a; Gorinova et al. 2021], do not support discrete random variables, instead requiring them to be (manually or automatically) marginalized out. However, this approach has numerous fatal cases that explode exponentially in the number of discrete variables.[1] Other sampling-based approaches are universal and so can

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[1]Indeed, the Pyro documentation states that it cannot support more than 25 discrete variables in CUDA and 64 discrete variables on a CPU [Bingham et al. 2018b].

Table 1. Distributions with sound and efficient bit blasting subsumed by mixed-gamma densities.

Distribution	Density	Distribution	Density
Uniform	1	Gamma	$\frac{\beta^{\alpha} x^{\alpha-1} e^{-\beta x}}{\Gamma(\alpha)}$
Linear	x	Laplace	$\frac{1}{2b} e^{\frac{-|x-\mu|}{b}}$
Polynomial	x^n	Chi-squared	$\frac{1}{2^{\frac{k}{2}}\Gamma(\frac{k}{2})} x^{\frac{k}{2}-1} e^{\frac{-x}{2}}$
Exponential	$\lambda e^{-\lambda x}$	Student-T	$c\left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}$

handle discreteness, such as importance sampling, Markov Chain Monte Carlo and Sequential Monte Carlo, etc. [Koller and Friedman 2009]. However, these algorithms are known to struggle with multimodal distributions [Yao et al. 2021], which arise through discreteness, as well as with programs that condition on low-probability events.

In this paper we develop a new inference algorithm for hybrid probabilistic programs via *discretization*: we convert the continuous distributions in a hybrid program to discrete distributions. This yields a fully discrete probabilistic program on which existing algorithms for discrete inference can be used. Discretization approximates a continuous distribution as a sequence of *intervals*, with each interval associated with the probability of the value falling in that interval. Forms of discretization have been used in prior work [Albarghouthi et al. 2017; Beutner et al. 2022; Claret et al. 2013; Huang et al. 2021] but they all scale linearly in the number of intervals. This imposes a clear tradeoff: one needs many small intervals in order to avoid losing too much precision, but the cost of inference quickly becomes prohibitive as the number of intervals grows.

We introduce a new approach to discretization that we call *bit blasting*, by analogy with the technique of the same name in verification [Bruttomesso and Sharygina 2009]. The key property of a bit blasted discretization is that it uses only *poly*($\log n$) Boolean random variables to represent a discretization on n intervals. This is achieved by employing a binary representation of numbers and representing discretizations as discrete probabilistic programs over this binary representation. At first blush, this succinct representation would appear to lose too much accuracy to be a viable strategy, but we present both theoretical and empirical results to the contrary.

First, we prove that a large class of common continuous densities can be bit blasted *soundly*, that is with no loss of accuracy versus a naive discretization. Table 1 lists example distributions that are in this class; we refer to the entire class as *mixed-gamma* distributions.

For instance, consider discretizing a continuous uniform distribution between 0 and 1. Naïve discretization to 2^{32} intervals requires enumeration of 2^{32} values. Instead, this distribution can be represented in binary as a tuple of 32 Bernoulli random variables of the form flip(0.5), i.e., coin tosses that are equally likely to have the value 0 or 1. This observation is not new, and a similar result holds for exponential distributions as well [Marsaglia 1971]. However, the bit blasted discretizations of other mixed-gamma densities are novel. Further, unlike the case for uniforms and exponentials, these discretizations are not defined as simply a tuple of independent Bernoulli random variables but rather require full-fledged discrete probabilistic programs over such variables.

A succinct representation does not necessarily imply efficient inference, which is hard in general. As our second contribution, however, we prove that bit blasted mixed-gamma distributions are not only sound and succinct, but they also support polynomial-time inference in the number of bits of precision. Specifically, we prove that the *knowledge compilation* approach to discrete probabilistic inference [Chavira and Darwiche 2008; Chavira et al. 2006; Fierens et al. 2015; Holtzen et al. 2020; Raedt et al. 2007], which reduces inference to weighted model counting on a boolean formula, has

this property for bit blasted mixed-gamma distributions. Therefore, the process of bit blasting a mixed-gamma distribution followed by discrete inference via knowledge compilation is guaranteed to take time that is polynomial in the bitwidth used for discretization.

Third, we have used the above theoretical results to design a new PPL called HyBit that performs non-stochastic approximate inference for hybrid probabilistic programs via bit blasting. Given a hybrid probabilistic program, HyBit first obtains a purely discrete program by replacing continuous distributions with their bit blasted discrete approximations. Mixed-gamma distributions are replaced with their sound bit blasted discrete distributions. Other distributions are replaced with piece-wise discrete approximations, where each piece is a bit blasted mixed-gamma distribution. HyBit then leverages knowledge compilation to perform exact inference on the resulting discrete probabilistic program. We empirically demonstrate the benefits of our approach over existing sampling-based and symbolic inference approaches on hybrid probabilistic programs.

Overall, we present the following contributions in this paper:

(1) We describe and motivate the challenges for inference on hybrid probabilistic programs in Section 2.
(2) We present a new form of discretization called bit blasting that is characterized by its succinctness in the number of discrete intervals in Section 3.
(3) We present a class of continuous distributions, namely mixed-gamma distributions, for which a sound bit blasted representation exists. We formalize this construction and prove its properties in Section 3. We further prove that knowledge compilation based inference scales polynomially in the bitwidth for these distributions.
(4) We describe the HyBit PPL and its new inference algorithm via bit blasting in Section 4.
(5) In Section 5, we empirically compare HyBit with other PPLs on benchmarks obtained from the existing literature. We also characterize the behavior of HyBit with respect to its hyperparameters, i.e. number of bits and pieces.

2 MOTIVATING EXAMPLES

This section motivates the challenge of inference for hybrid probabilistic programs using three examples. First, we present an example from computational biology with inherent logical structure. Next, we show an example from the literature with a multimodal posterior arising due to discrete control flow. Finally, we show an example of low probability observations through conjugate Gaussians. We then investigate the performance of various inference algorithms, including HyBit.

2.1 Logical Structure

We present a simplified example from computational biology which relates genetic expression with blood sugar levels. Figure 1 shows the probabilistic program, where the task is to get the updated belief of a gene's occurrence in a patient given their blood sugar levels.

The first four lines of the probabilistic program in Figure 1 use a beta distribution as the prior probability of each of T genes occurring in the general population. The syntax flip(θ) denotes a Bernoulli random variable with success probability θ. On line 5, the program uses the syntax reduce(|, gene) to denote the expression $\bigvee_{i=1}^{T}$ gene[i]. In other words, the patient is considered to have diabetes if at least one of the genes is expressed. What follows is multiple readings of the patient's blood sugar level. For each reading a random variable first defines the blood sugar depending on whether they have diabetes. Then we use the syntax observe (y, v) to condition on the random variable y having the value v — in the program this is used to condition on actual blood-sugar readings from the patient. Finally, on line 12, the program queries for the expectation of the posterior distribution of the occurrence of the first gene.

Figure 2 shows the results of inference with a timeout of 20 minutes on this program using different inference algorithms, as the number of genes (T) increases. Stan uses Hamiltonian Monte Carlo, which does not directly support the discrete random variables. Instead, they are marginalized out, either manually or automatically using variable elimination [Gorinova et al. 2020]. As shown in the figure, Stan times out when there are more than 15 genes — as its strategy scales exponentially in T. The same issue of exponential blowup plagues

```
1   for i in 1:T
2       gene_occurrence[i] = beta(1, 1)
3       gene[i] = flip(gene_occurrence[i])
4   end
5   diabetes = reduce(|, gene)
6   blood_sugar1 = if diabetes normal(80, 2)
7                   else normal(135, 2) end
8   observe(blood_sugar1, 79)
9   blood_sugar2 = if diabetes normal(80, 2)
10                  else normal(135, 2) end
11  observe(blood_sugar2, 136)
12  return Expectation(gene_occurrence[1])
```

Figure 1. Example 1: Gene Expression

Psi [Gehr et al. 2016], which employs a symbolic approach to perform exact inference. As the figure shows, the universal sampling methods MCMC with Metropolis Hastings kernel (WebPPL MH) and Sequential Monte Carlo (WebPPL SMC) can scale and provide reasonable accuracy. AQUA discretizes hybrid programs [Huang et al. 2021] but does not support this program.

Our system and approach, HyBit, scales to 50 genes and has the least absolute error. It first replaces all continuous distributions (specifically on Lines 2, 6, 9 in Figure 1) with their bit blasted discrete approximations, obtaining a discrete bit-level abstraction of the program. In the experiment shown we use a bitwidth of 27 — each continuous distribution is discretized as a program over a tuple of 27 bits interpreted as a fixed-point number. Further, we approximate each continuous distribution using 1024 pieces, each of which is a bit blasted exponential distribution. Naive discretization with 27 bits would be prohibitively slow, as it yields 2^{27} intervals — 589M continuous intervals to be precise. However, our bit blasted program only uses 70K coin flips (Boolean random variables) to represent them.

Figure 2. Scaling on Logical Constraints. HyBit scales to 50 genes with the least absolute error.

Moreover, knowledge compilation based inference [Fierens et al. 2015; Holtzen et al. 2020] automatically identifies and exploits conditional independences in the program's logical structure and helps to scale inference. More details of this experiment can be found in the appendix.

2.2 Handling Multimodality

This section presents an example of a multimodal distribution to highlight another challenge for inference on hybrid probabilistic programs. Multimodal distributions have multiple peaks separated by low probability regions. These distributions commonly emerge in various applications such as sensor network localization, cosmology and many more [Shaw et al. 2007; Tak et al. 2018]. We adapt an example from the existing literature [Yao et al. 2021], as shown in Figure 3.

The probabilistic program shown in Figure 3 is hard for existing probabilistic inference approaches. The datapts on Line 3 are drawn independently from the mixture $\frac{2}{3} normal(5, 1) +$

Figure 4. Posterior from different baselines compared with that of `HyBit` for Figure 3. `HyBit` and WebPPL SMC are able to identify the both the modes in the posterior distribution. (a) Different runs of WebPPL MCMC with Metropolis Hastings kernel converge to different modes. (b) Different runs of Stan HMC converge to different modes. (c) Different runs of WebPPL SMC are able to find both the modes. (d) AQUA with its adaptive interval strategy only finds the more probable mode

$\frac{1}{3} normal(-5, 1)$. Since there are limited data points, the posterior for (μ_1, μ_2) is bimodal around $(5, -5)$ and $(-5, 5)$. As the numb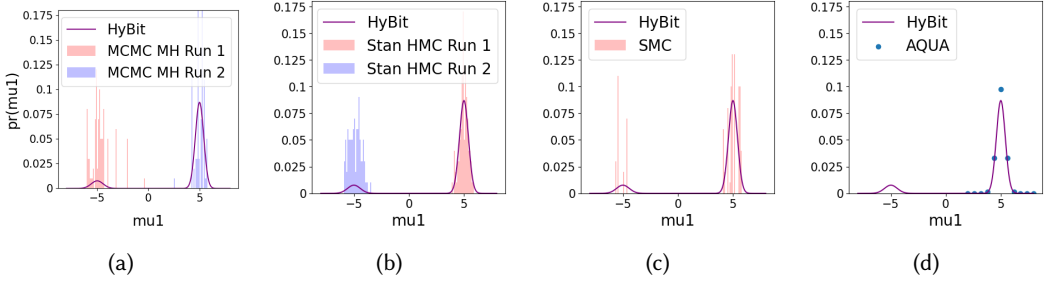er of data points increase, the posterior of (μ_1, μ_2) converges to $(5, -5)$. But in presence of 9 data points (Figure 3), the posterior for μ_1 is bimodal around 5 and -5.

The existence of multiple modes challenges sampling based algorithms as they tend to get stuck at one of the modes. Specifically, WebPPL using MCMC with Metropolis Hastings kernel and both Stan and WebPPL using HMC end up arbitrarily in one of the modes and completely fail to explore the other mode. Figures 4a and 4b show the results obtained using WebPPL, where two different runs get stuck in two different modes. On the other hand, `HyBit` performs exact inference on its discrete abstraction and so explores the distribution globally, allowing it to identify both

```
1  mu1 = uniform(-16, 16)
2  mu2 = uniform(-16, 16)
3  datapts = [5, 5, 5, 5, 5, 5, -5, -5, -5]
4  for data in datapts
5      y = if flip(⅔) normal(mu1, 1)
6          else normal(mu2, 1) end
7      observe(y, data)
8  end
9  return mu1
```

Figure 3. Example 2: Yao-Vehtari-Gelman model

modes. This is also the case for Sequential Monte Carlo (SMC) (Figure 4c). Finally, to address the computational challenge of direct discretization, AQUA adapts its discretizing intervals to focus on high probability regions, and so it ends up identifying the higher probability mode (Figure 4d).

2.3 Handling Low Probability Observations

This section presents conjugate Gaussians (Figure 5) with low probability observations. In Figure 5, the posterior distribution for random variable mu is queried after conditioning on low probability data on Lines 2 and 3.

Why are low probability observations hard? Intuitively, general-purpose sampling algorithms begin sampling from the prior distribution and struggle to find samples with considerable weight. Only after a very large number of samples do these algorithms manage to sample from the true posterior. On the other hand, `HyBit` performs a global exploration of the domain

```
1  mu = normal(0, 1)
2  observe(normal(mu, 1), 8)
3  observe(normal(mu, 1), 9)
4  return mu
```

Figure 5. Example 3: Conjugate Gaussians

of the posterior distribution, via exact inference on a bit blasted abstraction, and so it is insensitive to this issue.
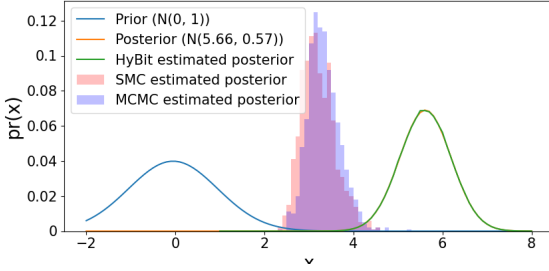

Figure 6. Results for Example 3. The HyBit estimated posterior overlaps closely with the true posterior distribution.

Figure 6 plots the true prior and posterior distributions along with results from different inference algorithms. For the sampling-based algorithms MCMC with Metropolis Hastings kernel and SMC, we obtained and plotted 1000 samples after running the corresponding WebPPL [Goodman and Stuhlmüller 2014] program. The importance sampling algorithm was not able to obtain any sample with non-zero weight for this program. The samplers are shifting the posterior towards the true posterior distribution but require many more samples to achieve that. Even after sampling about 16 million samples, the expectation of the samples obtained from MCMC and SMC have absolute error respectively of 0.549798 and 1.520776. On the other hand, the posterior distribution from HyBit overlaps perfectly with the true posterior distribution. Stan HMC handles low probability observations well and also obtains high accuracy. Finally, the mean of AQUA's reported posterior had an error of 5.66 as it fails to make any update to the prior of μ.

3 BIT BLASTING: KEY INSIGHTS

To scale inference on hybrid probabilistic programs with respect to discrete structure, we need an algorithm that treats discreteness as first class, and that discretizes away continuous structure. This section defines the semantic notion of bit blasting and sets it up as a special case of discretization with desirable properties. Then, we provide bit blasting functions for common classes of continuous distributions. We provide discretization techniques that are sound (accurate up to b bits), succinct, and amenable to efficient inference.

3.1 Discretization and Bit Blasting

In the standard terminology of probability theory [Rosenthal 2006], a probability space (Ω, Σ, μ) consists of a sample space Ω, a σ-algebra on Ω denoted Σ, and a probability measure on Σ denoted μ. In a general sense, a discretization function takes as input such a probability space (Ω, Σ, μ) and outputs a discrete probability space $(\Omega_D, \Sigma_D, \mu_D)$ where Ω_D is a countable set.

We will study a more specific notion of discretization: one that takes as input a continuous distribution over a finite interval and outputs a discrete distribution over 2^b points for some number of bits b. Formally, let $[l, u)$ be an interval with $l, u \in \mathbb{R}$. For the input probability space, we use $\mathcal{B}([l, u))$ to denote the Borel σ-algebra of subsets of interval $[l, u)$ [Rosenthal 2006]. For the output probability space, we write $\mathcal{P}(S)$ to refer to the power set (a σ-algebra) of set S. Moreover, we will assume the sample space to be discretized as follows.

DEFINITION 1 (*b-BIT INTERVAL*). *A b-bit interval $[l, u]_b$ is the set of points obtained by dividing $[l, u)$ into 2^b intervals: $[l, u]_b = \{r \mid r2^b \in \mathbb{Z}, r \in [l, u)\}$*

We are now ready to define the notion of discretization function used in this paper.

DEFINITION 2 (b-BIT DISCRETIZATION FUNCTION). *A b-bit discretization function takes as input a probability space $([l, u), \mathcal{B}([l, u)), \mu)$, a bit width $b \in \mathbb{Z}^+$ and outputs a discrete probability space $([l, u]_b, \mathcal{P}([l, u]_b), \mu_D)$ for some measure μ_D.*

EXAMPLE 1. *Let π be a uniform distribution on the unit interval, described by the probability space $([0, 1), \mathcal{B}([0, 1)), \mu)$ such that the probability density function specified by μ is 1 on the unit interval. Consider a function f_1 that takes π as input and outputs the probability space $(S, \mathcal{P}(S), \mu_D)$ where $S = \{0, 0.25, 0.5, 0.75\}$ and μ_D is a probability measure over S. Then f_1 is a 2-bit discretization function.*

As the example shows, one can come up with any arbitrary b-bit discretization function. To qualify them further, we need a notion of accuracy — soundness up to b bits defined as follows.

DEFINITION 3 (SOUNDNESS OF b-BIT DISCRETIZATION FUNCTION). *For any integer $b > 0$, a b-bit discretization function is b-sound for a particular input probability space $([l, u), \mathcal{B}([l, u)), \mu)$ if it outputs a discrete probability space $([l, u]_b, \mathcal{P}([l, u]_b), \mu_D)$ such that the following holds:*

$$\forall x \in [l, u]_b \qquad \int_x^{x + \frac{1}{2^b}} d\mu(y) = \mu_D(x)$$

EXAMPLE 2. *Let f_2 be a b-bit discretization function that takes π (as defined in Example 1) as input and outputs the probability space $(S, \mathcal{P}(S), \mu_D)$ where $S = \{0, 0.25, 0.5, 0.75\}$ and for any subset T of S, $\mu_D(T) = |T| \times 0.25$. Then f_2 is a sound 2-bit discretization function.*

Before we define a b-bit blasting function, we need to fix a generic representation of discrete probability distributions. To that purpose, we define the concept of a discrete probabilistic closure, akin to probabilistic Turing machines [Arora and Barak 2006].

Each probabilistic closure is a deterministic function from a set of biased coin flips to a discrete set. This induces a probability distribution on the output of the function through probabilities associated with coin flips. It also consists of an accepting Boolean formula that handles observations and limits the set of values that input flips can take. We provide a formal definition below:

DEFINITION 4 (DISCRETE PROBABILISTIC CLOSURE). *A discrete probabilistic closure is defined as the tuple (φ, γ, w) where w is a vector of Boolean random variables (or biased coin flips), φ is a deterministic function from $\{\mathsf{T}, \mathsf{F}\}^{|w|}$ to a finitely countable set S and γ is a deterministic Boolean formula over variables in w.*

The semantics of a discrete probabilistic closure, i.e. $\langle (\varphi, \gamma, w) \rangle$ defines a probability space $(S, \mathcal{P}(S), \mu)$ such that

$$\forall T \subseteq S, \mu(T) = \frac{\mathbb{E}_w((\varphi(w) \in T) \wedge \gamma)}{\mathbb{E}_w(\gamma)} \qquad \text{if } \mathbb{E}_w(\gamma) \neq 0$$

Dice [Holtzen et al. 2020] and Problog [Fierens et al. 2015] are examples of PPLs that directly fit into the paradigm of a discrete probabilistic closure.

Note that any discrete distribution μ_D over 2^b numbers can be represented as a discrete probabilistic closure (φ, γ, w) where $|w| = 2^b - 1$. More concretely, consider $\varphi = $ naïve as defined below, $\gamma = \mathsf{T}$ and $w = [\texttt{flip}(\mu_D(0)), \texttt{flip}(\mu_D(1)), \ldots, \texttt{flip}(\mu_D(2^b - 2))]$.

We want a discrete probabilistic closure to be more succinct — of size polynomial in the number of bits of precision, b. To this purpose, we define a bit blasting function as follows:

```
1   function naïve(f₀, f₁, ..., f_{2^b−2})
2       val = if f₀ then 0
3       else if f₁ then 1
4       ...
5       else if f_{2^b−2} then 2^b − 2
6       else 2^b − 1
7       return val
```

DEFINITION 5 (*b*-BIT BLASTING FUNCTION). *A b-bit blasting function* $[.]_b$ *is a b-bit discretization function that outputs a discrete probabilistic closure* (φ, γ, w) *that uses a number of Boolean random variables that is polynomial in the number of bits b, that is,* $|w| \in O(poly(b))$

It follows from Definitions 3, 4 and 5 that for an integer $b > 0$, a b-bit blasting function is sound for a given probability space $([l, u), \mathcal{B}([l, u)), \mu)$ if

$$\forall x \in [l, u]_b \qquad \int_x^{x + \frac{1}{2^b}} dp(y) = \langle [p]_b \rangle,$$
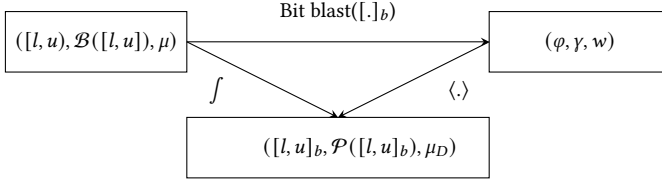
that is, if the following diagram commutes:

Figure 7. Commutative diagram for a b-sound bit blasting function

3.2 Concrete Bit Blasting Function: Preliminaries

Next, our goal is to provide a concrete instantiation of a sound bit blasting function for mixed gamma distributions, which have probability density functions as defined below.

DEFINITION 6 (GENERALIZED-GAMMA DENSITY). *Given parameters* $\alpha \in \mathbb{Z}^+$ *and* $\beta \in \mathbb{R}$, *a generalized-gamma density* $\pi_{\alpha, \beta}$ *is a probability density function over the interval* $[0, 1)$ *of the form*

$$\pi_{\alpha, \beta}(x) = \frac{x^\alpha e^{\beta x}}{\int_{[0,1)} y^\alpha e^{\beta y} \, dy}.$$

DEFINITION 7 (MIXED-GAMMA DENSITY). *Given a collection of* $N \in \mathbb{Z}^+$ *generalized-gamma densities* π_{α_i, β_i} *with their associated weights* $a_i \in [0, 1]$ *such that* $\sum_{i=1}^N a_i = 1$, *a mixed-gamma density* Υ *is a probability density function over the interval* $[0, 1)$ *of the form*

$$\Upsilon(x) = \sum_{i=1}^N a_i \pi_{\alpha_i, \beta_i}(x).$$

For notational convenience, we confine the continuous distributions to the unit interval to get discrete distributions over a b-bit unit interval. We generalize our approach to any finite interval for building the probabilistic programming system HyBit based on bit blasting.

To describe our construction of the bit blasting function, we make use of Dice [Holtzen et al. 2020]. Dice already compiles its programs to weighted Boolean formulas (via the $\rightsquigarrow$ judgement) that fit the definition of a discrete probabilistic closure.[2] This allows us to only define a $\rightsquigarrow_b$ judgment from probability density functions to Dice programs to specify a bit blasting function. Dice also defines a distributional semantics function $[\![.]\!]_D : p \rightarrow V \rightarrow [0, 1]$ that takes as input a Dice program p and outputs a normalized probability distribution. We use the function $[\![.]\!]_D$ to argue about soundness of our construction later. More details can be found in the appendix.

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[2]Dice compiles to weighted Boolean formulas (φ, γ, w) where φ outputs (tuples of) Boolean values, γ represents observations in a Dice program and w consists of weights associated with Boolean variables (biased coin flips)

The compilation judgement for mixed-gamma densities are of the form $\Upsilon \leadsto_b \mathsf{p}$ where p are Dice programs. We further provide the following definitions for b-equivalence between densities and Dice programs and b-succinctness of Dice programs.

DEFINITION 8 (BINARIZING FUNCTION). *The binarizing function for b bits, $(\!|.|\!)_b$ takes as input a number $r \in [0,1]_b$ and returns a b-bit tuple $(v_1, (v_2, (\ldots v_b) \ldots))$ such that $r = \sum_{i=1}^{b} \frac{v_i}{2^i}$*

DEFINITION 9 (B-EQUIVALENCE). *A mixed-gamma density Υ and a Dice program p are b-equivalent for some $b \in \mathbb{Z}^+$ if for all $r \in [0,1]_b$*

$$\int_{r}^{r+\frac{1}{2^b}} \Upsilon(y) \; dy = [\![\mathsf{p}]\!]_D \, ((\!|r|\!)_b)$$

Note that b-equivalence is analogous to b-soundness but is specialized for Dice programs.

DEFINITION 10. *The flip count function flip_count (.) takes as input a Dice program p and outputs the number of Boolean random variables (coin flips).*

DEFINITION 11 (B-SUCCINCT). *Compilation $\Upsilon \leadsto_b \mathsf{p}$ is b-succinct if flip_count (p) $\in O(b)$.*

We define b-succinctness such that the Dice program p employs coin flips linear in the number of bits b. Observe that b-succinctness imposes a stricter condition than that required by a b-bit blasting function (which requires $poly(b)$ coin flips). This implies that if we have a b-succinct judgment for a mixed-gamma density, then we can have a b-bit blasting function for that distribution. We describe this in more detail later.

3.3 Judgment $\leadsto_b$ and bit blasting

This section describes the rules for the judgement $\leadsto_b$. We first describe the rules for an exponential distribution and then move on to generalized gamma distributions. Finally, we describe the rule for mixed-gamma densities. For each of the rules $\Upsilon \leadsto_b \mathsf{p}$, we prove the b-equivalence of the density Υ and the Dice program p and the b-succinctness of p. Detailed proofs can be found in the appendix. We also demonstrate how $\leadsto_b$ allows us to come up with a bit blasting function for mixed-gamma densities.

3.3.1 Exponential Distribution, $\pi_{0,\beta}$. Let us first consider the uniform distribution ($\pi_{0,0}$), a special case of an exponential distribution. If we bit blast a uniform distribution using b bits into 2^b intervals, we end up with a discrete distribution D_b over $[0,1]_b$ with 2^b discrete points each having probability $\frac{1}{2^b}$. A straightforward discretization strategy enumerates 2^b values using $2^b - 1$ coin flips. But the same can be achieved using a tuple of b bits, where each bit is an unbiased coin flip(0.5).

The strategy to bit blast a uniform distribution using its binary representation works because of the independence between binary digits. The same strategy can be extended to general exponential distributions as well. This fact was shown in a classic paper in the statistics literature [Marsaglia 1971]. We formalize that idea using the following rule.

DEFINITION 12. *The function flip_param: $\mathbb{R} \times \mathbb{Z}^+ \to [0,1]$ is defined flip_param$(\beta, b) = \dfrac{e^{\frac{\beta}{2^b}}}{1+e^{\frac{\beta}{2^b}}}$*

$$\frac{\begin{array}{c} \texttt{fresh } y_1, \ y_2, \ \ldots y_b \\ \texttt{flip\_param}(\beta, 1) = \theta_1 \quad \texttt{flip\_param}(\beta, 2) = \theta_2 \quad \ldots \quad \texttt{flip\_param}(\beta, b) = \theta_b \end{array}}{\pi_{0,\beta} \rightsquigarrow_b \begin{array}{l} \texttt{let } y_1 = \texttt{flip}(\theta_1) \texttt{ in} \\ \texttt{let } y_2 = \texttt{flip}(\theta_2) \texttt{ in} \\ \ldots \\ \texttt{let } y_b = \texttt{flip}(\theta_b) \texttt{ in} \\ (y_1, \ (y_2, \ (\ldots, \ y_b)) \ldots)) \end{array}} \quad \text{(Expo0)}$$

We prove the b-equivalence of the density $\pi_{0,0}$ and the Dice program in rule Expo0 and b-succinctness of the latter in the following lemmass. It is more straightforward to see the succinctness of the Dice program — it uses only b coin flips.

LEMMA 1. $\forall b \in \mathbb{Z}^+, \beta \in \mathbb{R}, \mathsf{p}, if \ \pi_{0,\beta} \rightsquigarrow_b \mathsf{p}, then \ \pi_{0,\beta} \ and \ \mathsf{p} \ are \ b\text{-}equivalent.$

LEMMA 2. $\forall \beta \in \mathbb{R}, \rightsquigarrow_b \ is \ b\text{-}succinct \ for \ \pi_{0,\beta}$

We provide detailed proofs of the above lemmas in the appendix. For rest of the paper, we consider exponential distributions as primitives to build other distributions, since these are the only ones that enjoy the property of independent bits. But, sound bit blasting functions are still possible for other distributions, as we show next.

3.3.2 Gamma Distribution $\pi_{1,\beta}$. To come up with a sound bit blasting function for $\pi_{1,\beta}$, we present a key mathematical insight. Consider the program in Figure 8a. Continuous random variables X and Y have a uniform ($\pi_{0,0}$) and exponential ($\pi_{0,\beta}$) distribution respectively. It returns the new distribution of X after conditioning on the inequality Y < X. It turns out that the posterior distribution is a specific gamma distribution $\pi_{1,\beta}$. We show the resulting calculation below, where *pdf* refers to the the probability density function.

$$pdf(X|Y<X) \propto \int_{y=0}^{1} pdf(Y) \cdot pdf(X) \cdot \mathbb{1}(Y<X) \ dy = \int_{y=0}^{x} 1 \cdot e^{\beta x} \ dy \propto x e^{\beta x} \tag{1}$$

What happens if we discretize the program in Figure 8a using b bits? We get the program in Figure 8b where each continuous random variable has been replaced with its bit blasted counterpart (X replace by X_b and so on). We have already seen that for uniform and exponential distributions, b-equivalent Dice programs exist. But what about the other constructs? As Figure 8d demonstrates, `observe (`Y_b` < `X_b`)` incurs error over its continuous counterpart `observe (X < Y)`. The good news is that we can account for the error as shown by the following equations:

$$\Pr(X_b \mid Y<X) = \Pr(X_b, Y_b < X_b \mid Y<X) + \Pr(X_b, Y_b == X_b \mid Y<X)$$

$$= \underbrace{\Pr(X_b \mid Y_b < X_b)}_{\text{Output of the discrete program}} \cdot \Pr(Y_b < X_b \mid Y<X) + \underbrace{\Pr(X_b \mid Y_b == X_b, Y<X)}_{\text{Correction} \propto [\pi_{0,\beta}]_b} \cdot \Pr(Y_b == X_b \mid Y<X).$$

The correction term in the above equations when computed algebraically turns out to be proportional to the exponential density ($\pi_{0,\beta}$). So now, the resulting discrete probabilistic program after correction looks as shown in Figure 8c where $\theta = Pr(Y_b == X_b|Y < X)$.

```
1  Y ~ uniform(0, 1)
2  X ~ exponential(β)
3  observe(Y < X)
4  return X
```

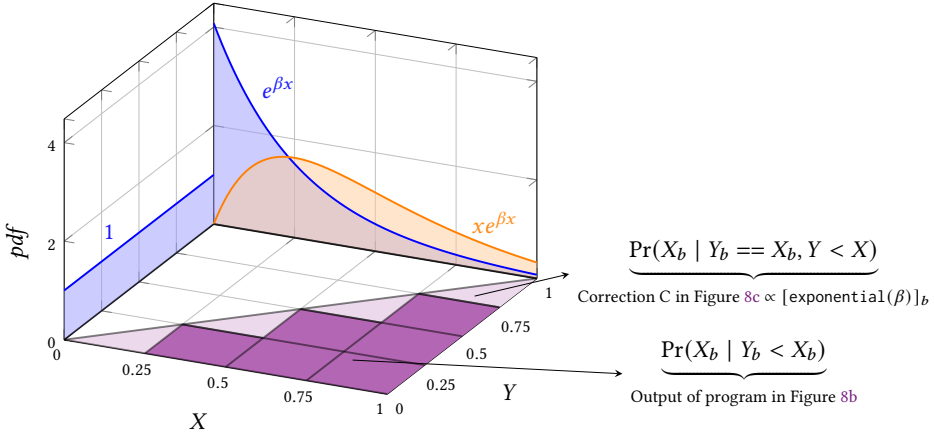(a) Continuous probabilistic program for density $xe^{\beta x}$

```
1  Y_b ~ [uniform(0, 1)]_b
2  X_b ~ [exponential(β)]_b
3  observe(Y_b < X_b)
4  return X_b
```

(b) bit blasted probabilistic program analogous to program 8a

```
1  Y_b ~ [uniform(0, 1)]_b
2  X_b ~ [exponential(β)]_b
3  C ~ [exponential(β)]_b
4  observe(Y_b < X_b)
5  Z = if flip(θ) then C
       else X_b
6  return Z
```

(c) Sound bit blasted probabilistic program for density $xe^{\beta x}$

$$\underbrace{\Pr(X_b \mid Y_b == X_b, Y < X)}$$
Correction C in Figure 8c $\propto$ [exponential(β)]$_b$

$$\underbrace{\Pr(X_b \mid Y_b < X_b)}$$
Output of program in Figure 8b

(d) Sound b-bit blasting of $xe^{\beta x}$. Prior densities for X and Y (shown in blue) when conditioned on $Y < X$ (shown in violet) returns the posterior for X (shown in orange).

Figure 8. Key insight in bit blasting $xe^{\beta x}$ probability density. $[.]_b$ refers to discretization of a continuous density into 2^b intervals and X_b refers to the discretization of X.

The rule Expo1 captures the above intuition. Here, unifObs(y, b) = p is a helper judgment where p constructs a uniform distribution that it conditions through observe on being less than y.

$$\frac{\begin{array}{c} \text{fresh } y_1, y_2, y_3 \qquad \beta \neq 0 \\ \pi_{0,\beta} \rightsquigarrow_b p_1 \qquad \text{unifObs}(y_1,\ b) = p_3 \qquad \theta = \frac{(e^{\beta \cdot 2^{-b}}(\beta \cdot 2^{-b}-1)+1)(1-e^\beta)}{(1-e^{\beta \cdot 2^{-b}})(e^\beta(\beta-1)+1)} \end{array}}{\pi_{1,\beta} \rightsquigarrow_b \begin{array}{l} \text{let } y_1 = p_1 \text{ in} \\ \text{let } \_ = p_3 \text{ in} \\ \text{let } y_2 = p_1 \text{ in} \\ \text{let } y_3 = \text{flip}(\theta) \text{ in} \\ \text{if } y_3 \text{ then } y_2 \text{ else } y_1 \end{array}} \tag{Expo1}$$

We prove the b-equivalence and b-succinctnesss. The proof for b-equivalence is much more involved but it is easy to see that the Dice program in the above rules uses $3b + 1$ coin flips: b coin flips in each occurrence of p_1, b coin flips in p_3 and 1 coin flip in the if then else guard to create a mixture.

LEMMA 3. $\forall b \in \mathbb{Z}^+, \beta \neq 0 \in \mathbb{R},$, p, if $\pi_{1,\beta} \rightsquigarrow_b$ p, then $\pi_{1,\beta}$ and p are b-equivalent.

LEMMA 4. $\forall \beta \in \mathbb{R}, \rightsquigarrow_b$ is b-succinct for $\pi_{1,\beta}$

3.3.3   Generalized Gamma Distribution $\pi_{\alpha,\beta}$. The previous subsection shows how conditioning on the inequality (Y < X) introduces a linear factor to $\pi_{0,\beta}$ to obtain $\pi_{1,\beta}$. Note that conditioning on (Y < X) introduces a linear factor regardless of what initial probability density X had. That is, if X's initial probability density was $f(x)$, the resulting density of the following probabilistic program would be $xf(x)$. This implies that if we can bit blast $f(x)$, we can bit blast $xf(x)$.

```
1   Y ~ uniform(0, 1)
2   X ~ f(x)
3   observe(Y < X)
4   return X
```

We still need to account for the error incurred by observe (Y_b < X_b) i.e. $\Pr(X_b | Y_b == X_b, Y < X)$. It turns out that the correction term is a mixture of gamma distributions which can be bit blasted soundly as well. We provide the judgement rule and proof of the following lemma in the appendix.

LEMMA 5. $\forall b, \alpha \in \mathbb{Z}^+, \beta \in \mathbb{R},$, p, if $\pi_{\alpha,\beta} \rightsquigarrow_b$ p, then $\pi_{\alpha,\beta}$ and p are b-equivalent.

LEMMA 6. $\forall \beta \in \mathbb{R}, \alpha \in \mathbb{Z}^+, \rightsquigarrow_b$ is b-succinct for $\pi_{\alpha,\beta}$

3.3.4   Mixture of Gamma Distributions $\sum_i a_i \pi_{\alpha_i,\beta_i}$. Since generalized gamma densities $\pi_{\alpha,\beta}$ can be bit blasted, mixed gamma densities can be bit blasted as well. One bit blasts each individual generalized gamma density and creates their mixture using if then else constructs as follows.

$$\frac{N > 1 \qquad \pi_{\alpha_N,\beta_N} \rightsquigarrow_b \mathsf{p}_1 \qquad \sum_{i=1}^{N-1} \frac{a_i}{1-a_N} \pi_{\alpha_i,\beta_i} \rightsquigarrow_b \mathsf{p}_2 \qquad \forall i, a_i \in [0,1] \qquad \sum_{i=1}^{N} a_i = 1}{\sum_{i=1}^{N} a_i \pi_{\alpha_i,\beta_i} \rightsquigarrow_b \begin{array}{l} \mathtt{fresh\ y_1,\ y_2,\ y_3} \\ \mathtt{let\ y_1 = flip(}a_N\mathtt{)\ in} \\ \mathtt{let\ y_2 = p_1\ in} \\ \mathtt{let\ y_3 = p_2\ in} \\ \mathtt{if\ y_1\ then\ y_2\ else\ y_3} \end{array}}$$

(Trans-mix)

We prove the following theorems with details in the appendix.

THEOREM 7. $\forall \Upsilon, b \in \mathbb{Z}^+, \mathsf{p}$, if $\Upsilon \rightsquigarrow_b \mathsf{p}$ then Υ and p are b-equivalent.

THEOREM 8. $\rightsquigarrow_b$ is b-succinct for all mixed-gamma densities Υ

Now that we have specified the rules for judgment $\rightsquigarrow_b$, we specifically define a sound bit blasting function for all mixed-gamma densities Υ, that is $\rightsquigarrow \circ \rightsquigarrow_b$.

THEOREM 9. $\rightsquigarrow \circ \rightsquigarrow_b$ is a sound b-bit blasting function

Earlier work [Holtzen et al. 2020] defines the judgment $\rightsquigarrow$ that takes as input a Dice program p and outputs a weighted Boolean formula (φ, γ, w) that aligns with Definition 4 of a discrete probabilistic closure. And since $\rightsquigarrow_b$ is b-succinct for all mixed-gamma densities by Theorem 8, $\rightsquigarrow$ always outputs a w with $poly(b)$ coin flips. Thus, $\rightsquigarrow \circ \rightsquigarrow_b$ is a b-bit blasting function. Earlier work [Holtzen et al. 2020] also proves the correctness of compilation to weighted Boolean formula with respect to the semantics of the Dice program. This fact combined with Theorem 7 concludes that $\rightsquigarrow \circ \rightsquigarrow_b$ is a sound b-bit discretization function. Detailed proofs can be found in the appendix.

3.3.5   Example: Laplace Distribution. Previous sections described how mixed gamma densities can be bit blasted when they are confined to a unit interval. But how can distributions that are shifted or scaled to other finite intervals be bit blasted? We explain it through the example of a Laplace distribution. A Laplace distribution has two parameters: location (μ) and scale (b) and has the probability density function as described below where $x \in \mathbb{R}$.

$$Laplace(x|\mu, b) = \frac{1}{2b} e^{-\frac{|x-\mu|}{b}} = \begin{cases} \frac{1}{2b} e^{\frac{\mu}{b}} e^{-\frac{x}{b}} & x \geq \mu \\ \frac{1}{2b} e^{-\frac{\mu}{b}} e^{\frac{x}{b}} & x < \mu \end{cases}$$

Let us consider the Laplace distribution truncated at the interval $[\mu - r, \mu + r]$. We assume that r would be a suitable power of 2 allowing product with r (denoted by $r \times \mathsf{p}$) to be just a decimal shift and μ to be a b-bit representable number allowing precise shifting of p. First we generate the exponentials scaled for an interval of width r instead of width 1:

$$\pi_{0,-\frac{r}{b}} \rightsquigarrow_b \mathsf{p}_1 \qquad \pi_{0,\frac{r}{b}} \rightsquigarrow_b \mathsf{p}_2$$

And then we create a mixture of them:

$$Laplace(x|\mu, b) \rightsquigarrow_b \texttt{if flip } 0.5 \texttt{ then } \mu + r \times \mathsf{p}_1 \texttt{ else } \mu - r + r \times \mathsf{p}_2$$

Since p_1 and p_2 use b coin flips each, the program shown above uses $2b$ coin flips and $\rightsquigarrow \circ \rightsquigarrow_b$ is a sound bit blasting function for Laplace distributions as well.

3.4 How does bit blasting help in inference?

We have demonstrated sound bit blasting functions for mixed gamma distributions. But how does that help in inference for probabilistic programs with these distributions? To answer this question, we focus on a particular inference strategy - that is knowledge compilation. We first describe the necessary preliminaries about knowledge compilation and then argue about how the programs obtained through $\rightsquigarrow_b$ are efficient for knowledge compilation.

Knowledge compilation based approaches [Fierens et al. 2015; Holtzen et al. 2020] for exact discrete probabilistic inference compile discrete probabilistic programs into weighted Boolean formulas that are represented using (reduced) ordered binary decision diagrams (OBDDs). These OBDDs are single rooted in case of a single Boolean random variable being returned and multi-rooted in case of a tuple of Boolean random variables being returned. By fixing a value for all the flips (biased coin flips with associated weights) in the program, and by traversing the OBDD following those values (solid line for true, dashed for false), we reach the terminal corresponding to the value of each bit. The operation of weighted model counting computes the probability of reaching the 1-terminal for each bit in the returned value. It is a dynamic programming algorithm that runs in time linear in the OBDD size. The size of an OBDD for a Boolean formula ϕ, denoted $OBDD(\phi)$, is the number of nodes in the OBDD. Thus, if we can obtain a smaller OBDD representation for a distribution, we can efficiently compose it with other constructs in a discrete probabilistic program.

We discuss and prove formally how every program obtained through the judgement $\rightsquigarrow_b$ compiles into a weighted Boolean formula that compiles to a multi-rooted OBDD that grows linearly in the number of bits as opposed to the worst case exponentially. Recall that Dice programs compile to weighted Boolean formula (φ, γ, w) where φ is the Boolean formula corresponding to the return value of the program, γ is the accepting Boolean formula to encode observations and w is the weight function with flip probabilities.

THEOREM 10. $\forall \Upsilon, \mathsf{p}, \varphi, \gamma, w, \exists k, \forall b,$ if $\Upsilon \rightsquigarrow_b \mathsf{p}$ and $\mathsf{p} \rightsquigarrow (\varphi, \gamma, w)$, then there exists a variable order Π of Boolean random variables in w such that $OBDD(\varphi) + OBDD(\gamma) \leq kb$

We now provide intuition for the proof of the above theorem. Note that in the programs obtained through the judgement $\rightsquigarrow_b$, there are only two constructs that depend on the number of bits: (1) construction of exponential distribution $\pi_{0,\beta}$, and (2) conditioning on inequality between an exponential and a uniform distribution through $\texttt{unifObs(y, b)}$. We provide intuition how the $OBDD$ size for these constructs increase linearly in the number of bits, b.

3.4.1 Exponential Distribution. In Figure 9, we 3-bit blast an exponential distribution, i.e. we have a discrete exponential distribution over 8 values (0, 0.125, 0.25, . . ., 0.875). The figure shows a 3-rooted BDD where each root labeled as b_1, b_2 and b_3 represents a bit in the returned value of 3 bits. Consider that we fix the value of the flip corresponding to the node f_1 to be true, then for b_1, we would reach the terminal 1 and its value would be assigned 1. The operation of weighted model counting (WMC) would calculate the probability of b_1 to be 1 as $6.14e^{-6}$ as node f_1 has probability $6.14e^{-6}$ to be true. Similarly WMC can be used for other roots of this BDD. Since each bit needs one BDD node, the overall BDD size grows linearly with the number of bits. Since WMC runs in time linear in the BDD size, probabilistic inference for an exponential distribution would run linear in the number of bits $O(b)$. Another example of OBDD for a uniform distribution can be found in the appendix.
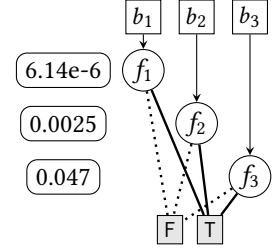

Figure 9. Compiled BDD for exponential (-3) e^{-3x}.

For all programs p obtained through the judgement $\leadsto_b$, if p $\leadsto (\varphi, \gamma, w)$, then φ is the Boolean formula that represents the return value of the program. We argue that the return value of p is always a mixture of exponential distributions making its OBDD size linear in the number of bits.

3.4.2 Conditioning on inequality between an exponential and a uniform distribution. The rules for judgment $\leadsto_b$ use the helper judgment unifObs(y, b) = p to condition on an inequality between binary representations of a uniform distribution and an exponential distribution.

DEFINITION 13 (INEQUALITY FUNCTION). *A b-bit inequality function,* $LT_b : \{0,1\}^b \times \{0,1\}^b \to \{0,1\}$ *takes as input two b-bit numbers* x, y *and outputs* 1 *if* $x < y$ *and* 0 *otherwise. Thus,*

$$LT_b((x_1, \ldots x_b), (y_1, \ldots y_b)) = \begin{cases} \neg x_1 y_1 & b = 1 \\ \neg x_1 y_1 + (\neg x_1 \neg y_1 + x_1 y_1) LT_{b-1}((x_2, \ldots, x_b), (y_2, \ldots, y_b)) & b > 1 \end{cases}$$

We prove the following lemma which states that the OBDD size for the inequality function grows linearly with the number of bits.

LEMMA 11. $\exists k, \forall b$, *for the variable order* $x_1, y_1, x_2, y_2, \ldots, x_b, y_b$, *the size of the OBDD, that is* $OBDD(LT((x_1, x_2, \ldots, x_b), (y_1, y_2, \ldots, y_b))) \leq kb$.

Since the only constructs that depend on the number of bits (exponential distributions and inequalities) grow linearly with the number of bits, Theorem 10 holds intuitively. We provide a formal proof in the appendix.

4 HYBIT: A PROBABILISTIC PROGRAMMING SYSTEM

The previous section described how to bit blast mixed-gamma distributions. We further use it to build a probabilistic program system HyBit for hybrid probabilistic programs. This section describes its implementation and elaborates on two important aspects: piece-wise approximations of continuous distributions and advantages of a binary representation.

4.1 HyBit — Implementation Details

We build a probabilistic programming system HyBit around sound bit blasting of mixed-gamma densities and approximate bit blasting of other continuous distributions. To do so, we first build a shallow embedding of Dice in Julia using its meta-programming tools [Bezanson et al. 2017; Holtzen et al. 2020] and extend it with necessary features to support hybrid probabilistic programs.

```
DistFixPt{bits} general_gamma(int bits, int alpha, real beta, float ll, float ul)
```
Parameters:

- `bits`: number of bits for bit blasting
- `alpha, beta`: parameters of the density $\pi_{\alpha,\beta}$
- `ll, ul`: range of the continuous density

Returns: Sound bit blasted distribution of type `DistFixPt{bits}`

```
DistFixPt{bits} bitblast(int bits, function density, int numPieces, bool dist,
 float ll, float ul)
```
Parameters:

- `bits`: number of bits for bit blasting
- `density`: continuous density function
- `numPieces`: number of pieces
- `dist`: Boolean indicating whether to use linear or exponential pieces
- `ll, ul`: range of the continuous density

Returns: Bit blasted distribution of type `DistFixPt{bits}`

```
Dict{float, float} pr(DistFixPt{bits} var)
float expectation(DistFixPt{bits} var)
float variance(DistFixPt{bits} var)
```
Parameters: random variable
Returns: Probability distribution / expectation / variance of `var`.

Figure 10. API for `HyBit`.

`HyBit` provides support for random variables over unsigned and signed fixed point numbers using the type `DistFixPt{bits}`, representing distributions over fixed point numbers with bitwidth `bits`. This is used as the representation for bit blasted distributions.

Figure 10 contains the API description. The function `general-gamma` is used for sound bit blasting of generalized gamma densities using the bits specified using the parameter `bits`. Sound bit blasting of mixed-gamma densities is achieved using `if-then-else` construct over generalized gamma densities. The function `bitblast` is used for bit blasting any arbitrary continuous distribution using piece-wise approximation employing the bits and pieces specified using the parameters `bits` and `pieces`. The API also allows the user to choose the type of discrete distribution – linear or exponential – for the piece-wise approximation. The parameters of linear (slope) and exponential (β) pieces are automatically chosen such that the ratio of probabilities of the first and last interval is the same as that for the naïve discretization. With these functions, users can write their hybrid probabilistic program as Julia code with each continuous distribution replaced with its bit blasted discrete distribution. The next subsection describes piece-wise approximations in more detail. The API also provides functions for querying the probability distribution, expectation and the variance of a random variable. The computation of expectation and variance benefit from the binary representation, which we also elaborate further below.

4.2 Piece-wise Approximations

Even though mixed-gamma distributions capture many natural distributions, there are other commonly occurring ones, such as the Gaussian. It is an open problem as to whether Gaussians admit a sound bit blasting function, let alone one that compiles to a compact OBDD. For such distributions, one can instead use a piece-wise approximation.

Let C be an arbitrary continuous probability distribution over the interval $[l, u]$. To bit blast C using a piece-wise distribution with t pieces, C is approximated using a mixture of t discrete probability distributions over disjoint intervals. For every piece, one creates a shifted and scaled instance of a bit blasted mixed-gamma density and then creates a mixture of them. Note that since each piece uses $O(b)$ coin flips, a piece-wise distribution with t pieces uses $O(tb)$ coin flips. Section 5 shows empirical advantages of this approach.

Figure 11. Bit blasted Gaussian distribution using 5 bits in the range $[-8, 8]$ using exponential pieces p — for 2, 4, 8 and 16 pieces.

This piece-wise approximation using linear or exponential pieces can be easily built using the `bitblast` API available in HyBit (Figure 10). For other piece-wise approximations using gamma pieces, one can use the construct `if-then-else` along with `general_gamma`. Figure 11 shows bit blasting of a Gaussian distribution using 2, 4, 8 and 16 pieces, where each piece is a bit blasted exponential. This allows the user to have the conventional trade off between accuracy and performance. We elaborate more on this trade off in Section 5.

4.3 Advantages of the Binary Representation

The binary representation has important advantages for probabilistic reasoning beyond the succinctness that bit blasting provides. First, many hybrid probabilistic models involve arithmetic operation on continuous random variables — for example, to express constraints or dependencies among variables. The binary representation of discretized distributions allows probabilistic inference (specifically the knowledge compilation approach that we employ) to identify and exploit the structure that exists in arithmetic, such as conditional independences among the resulting bits in a computation. Recent work [Cao et al. 2023] showed this advantage empirically for integers; HyBit leverages these advantages for computations over fixed-point numbers.

(a) Expectation

(b) Variance

Figure 12. Speedup in computing expectation and variance

The binary representation also enables an optimized computation of expectation and variance. Naïve computation of expectation and variance for a distribution over 2^b values requires one to compute probability of 2^b values. Bitwise representation and linearity of expectation allows one to only compute probability of b bits which gives an exponential improvement. We formalize the approach in following two propositions.

PROPOSITION 12. *Let D be a discrete probability distribution over the interval $[0, 2^n)$. Then D can be represented as a distribution over n bits as $(b_n, b_{n-1}, \ldots, b_1)$ and the expectation of D can be*
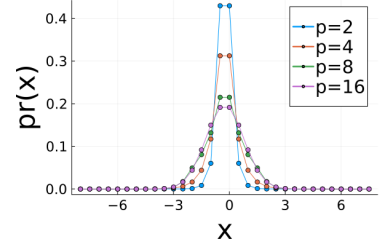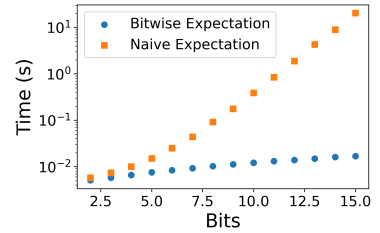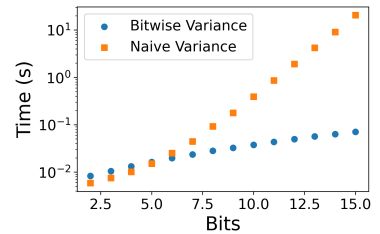
computed using linearity of expectation as follows:

$$\mathbb{E}[D] = \sum_{i=0}^{2^n-1} i \cdot pr(i) = \mathbb{E}(\sum_{j=1}^{n} 2^{j-1} b_j) = \sum_{j=1}^{n} 2^{j-1} \cdot pr(b_j)$$

PROPOSITION 13. *Let D be a discrete probability distribution over the interval $[0, 2^n)$. Then D can be represented as a distribution over n bits as $(b_n, b_{n-1}, \ldots, b_1)$ and the variance of D can be computed as follows:*

$$Var[D] = \sum_{i=0}^{2^n-1} i^2 pr(i) - (\mathbb{E}(D))^2 = Var(\sum_{j=1}^{n} 2^{j-1} b_j) = \sum_{k=1}^{n} \sum_{l=1}^{n} 2^{l+k-2}[pr(b_l \wedge b_k) - pr(b_l)pr(b_k)]$$

Example. Consider a discrete uniform distribution U_4 over the integers $\{0, 1, 2, 3\}$ represented using two bits, (X_2, X_1). The direct way of calculating the expectation and variance of this uniform distribution requires inferring the probability of all the integers in the domain as follows:

$$\mathbb{E}[U_4] = \sum_{i=0}^{i \leq 3} i \cdot pr(i) = \sum_{i=0}^{i \leq 3} i \cdot \frac{1}{4} = 1.5 \quad Var[U_4] = \sum_{i=0}^{i \leq 3} i^2 \cdot pr(i) - (\mathbb{E}(U_4))^2 = \sum_{i=0}^{i \leq 3} i \cdot \frac{1}{4} = 1.25$$

But using Propositions 12 and 13, the expectation and variance can instead be calculated from the probabilities of the individual bits.

$$\mathbb{E}[U_4] = \sum_{j=1}^{2} 2^{j-1} \cdot pr(b_j) = 1.5 \quad Var[U_4] = \sum_{k=1}^{2} \sum_{l=1}^{2} 2^{l+k-2}[pr(b_l \wedge b_k) - pr(b_l)pr(b_k)] = 1.25$$

Figure 12 empirically shows the performance benefits in computing expectation and variance of a distribution as we increase the number of bits in bit blasting a standard normal distribution.

5 EMPIRICAL EVALUATION

We evaluate the practicality of bit blasting on real-life probabilistic programs[3]. We have carried out relevant experiments to investigate the following questions:

Q1: How does HyBit perform in comparison to existing inference algorithms? Section 5.1
Q2: How effective is the piece-wise approximation? Section 5.2

5.1 Comparison with existing inference algorithms

5.1.1 Approximate Inference Algorithms. We evaluate HyBit against two classes of approximate inference algorithms.

Sampling Methods We compare against WebPPL rejection sampling, MCMC sampling (with Metropolis Hastings kernel), SMC sampling and Stan HMC as representatives of this class.

Discretization Methods The second class of inference algorithms are those that discretize the continuous probability density functions. We compare against AQUA in this class of inference algorithms [Huang et al. 2021].

Comparing performance of different probabilistic programming systems is a challenging task since performance is directly affected by the structure of the program. We write equivalent programs for these benchmarks in each system and put in our best effort to optimize them. The tables in this section and subsequent sections report the mean value of absolute error over 10 runs for stochastic

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[3]HyBit's implementation and code for all experiments are available at https://github.com/Juice-jl/Dice.jl/tree/hybit

algorithms. For other inference algorithms, we report output of a single run. All experiments were single-threaded and were carried out on a server with 2.4 GHz CPU and 512 GB RAM.

Table 2 reports the results of performance evaluation of HyBit against other existing approximate inference algorithms. We take all the hybrid and continuous benchmarks on which *Psi* [Gehr et al. 2016] was evaluated and a few more relevant benchmarks from existing work [Huang et al. 2021]. We put in our best effort to compute ground truth for these benchmarks either analytically or using computer algebra systems. We include only those benchmarks in our evaluation for which we were able to compute the ground truth reliably. We report the absolute error with respect to the ground truth for all the benchmarks. For benchmarks that returned a non-boolean value, we compute the absolute error of expectation for each of the approaches. We report the minimum error achieved by an inference algorithm within a timeout of 20 minutes.

For all the benchmarks, HyBit replaced mixed-gamma distributions with their sound bit blasted distribution and all other distributions with their linear piece-wise approximation $\pi_{1,0}$. The employed bits and pieces for each benchmark are reported in Table 2. To run Stan on these benchmarks, we make use of SlicStan [Gorinova et al. 2020] to get the Stan program with marginalized discrete random variables. For all WebPPL baselines, default settings were used for all the sampling algorithms with maximum number of samples within 20 minutes.

Table 3. Comparison of HyBit with exact inference PPLs: Psi

Benchmarks	HyBit	Psi
Pi	✓	✗
weekend	✓	✗
spacex	✓	✗
GPA	✓	✓
Tug of war	✓	✗
altermu2	✓	✗
conjugate gaussians	✓	✗
normal_mixture (θ)	✓	✗
normal_mixture (μ_1)	✓	✗
normal_mixture (μ_2)	✓	✗
zeroone (w1)	✓	✗
zeroone (w2)	✓	✗
coinBias	✓	✓
Addfun/sum	✓	✓
ClickGraph	✓	✓
trueskill	✓	✗
clinicaltrial1	✓	✓
clinicaltrial2	✓	✓
addfun/max	✓	✗

As Table 2 shows, HyBit with its efficient bit blasting is comparable with the existing approaches on all the benchmarks, even better on 11/19 of them. For other 8 benchmarks, HyBit achieves

Table 2. *Comparison of HyBit against other approximate inference algorithms.* Each row consists of one entry in bold indicating the lowest absolute error achieved among all inference algorithms. A '✗' denotes that the baseline does not support inference for the benchmark. A 'ϕ' denotes timeout

| Benchmarks	HyBit		AQUA	WebPPL			
	Bit	Pieces		rejection	MCMC	SMC	Stan
Pi [@10kdiver 2022]	1.73E-03	14	–	✗	9.12E-05	9.74E-05	**1.29E-03**	4.84E-05
weekend [Gehr et al. 2016]	**2.52E-08**	24	4096	✗	1.51E-02	1.04E-02	1.10E-02	✗
spacex [canyon289 2022]	6.94E-04	19	32	✗	8.84E-04	2.98E-03	**1.90E-02**	1.15E-04
GPA [Wu et al. 2018]	**2.22E-16**	25	4096	3.62E-01	1.70E-02	9.29E-03	1.38E-02	✗
Tug of war [Huang et al. 2021]	**2.87E-07**	23	16	✗	6.54E-04	6.94E-04	2.39E-03	4.51E-05
altermu2 [Nishihara et al. 2013]	1.33E-05	16	256	**3.41E-07**	ϕ	4.14E-01	4.48E-01	1.68E-03
conjugate gaussians [Jordan 2010]	**1.23E-06**	23	16	0.99	1.77E-04	3.24E-04	2.95E-03	1.77E-05
normal_mix (θ) [Huang et al. 2021]	5.49E-05	9	64	**4.13E-07**	ϕ	3.78E-04	5.09E-03	4.29E-01
normal_mix (μ_1) [Huang et al. 2021]	5.20E-03	9	16	**7.55E-06**	ϕ	1.36E-03	2.00E-02	1.87E+01
normal_mix (μ_2) [Huang et al. 2021]	3.92E-03	9	32	**8.65E-06**	ϕ	7.11E-04	1.15E-02	1.77E+01
zeroone (w1) [Bissiri et al. 2016]	**9.40E-05**	16	–	5.66E-02	ϕ	ϕ	ϕ	1.73E-01
zeroone (w2) [Bissiri et al. 2016]	**4.51E-04**	19	–	3.69E+00	1.40E+00	1.43E+00	1.03E+00	2.38E-01
coinBias [Gehr et al. 2016]	**2.02E-07**	22	4096	2.47E-02	9.88E-06	7.73E-05	1.16E-03	1.18E-05
Addfun/sum (cont.) [Gehr et al. 2016]	**3.81E-06**	24	16	✗	4.50E-04	1.63E-03	5.11E-03	8.45E-05
ClickGraph [Gehr et al. 2016]	1.75E-03	10	–	✗	7.14E-04	1.22E-03	**3.07E-03**	2.80E-05
trueskill [Gehr et al. 2016]	6.40E-04	10	16	✗	2.01E-04	4.22E-04	1.35E-03	**6.88E-05**
clinicaltrial1 [Gehr et al. 2016]	**5.27E-16**	9	–	✗	4.54E-07	1.41E-01	1.23E-01	4.53E-01
clinicaltrial2 [Gehr et al. 2016]	**6.81E-07**	13	–	✗	1.14E-01	1.32E-01	6.39E-02	4.54E-05
addfun/max [Gehr et al. 2016]	**2.20E-06**	23	128	✗	3.49E-04	4.42E-04	2.90E-03	1.19E-04
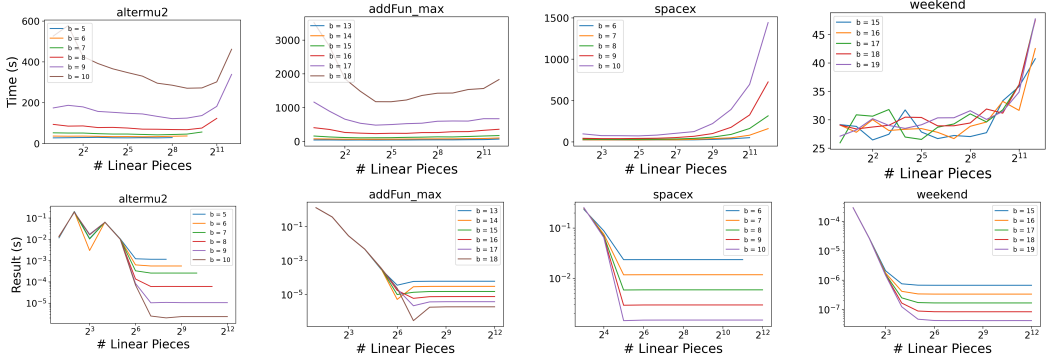
Figure 13. Runtime and Accuracy trends with respect to linear pieces for different bitwidths

a very close accuracy. AQUA performs better on only four of the benchmarks. This is primarily because its enumerative discretization does not scale well for higher precision. WebPPL and Stan (equipped with automated marginalization through SlicStan) support most of the benchmarks but do not achieve good accuracy within the threshold time. This is because sampling based algorithms are stochastic and cannot obtain sufficiently many samples from the true posterior in limited time.

5.1.2 Exact Inference Algorithms. Table 3 compares HyBit against a probabilistic programming systems that perform exact inference using algebraic methods i.e. Psi [Gehr et al. 2016]. Since *Psi* performs exact inference, it gives the exact correct answer for the programs that it is able to handle but is limited in its expressivity. It fails to handle 13/19 benchmarks. HyBit works for all 19 benchmarks as it reduces the computation to discrete inference on Boolean random variables and approximates the inference query.

5.2 How effective is piece-wise approximation?

We analyze the tradeoff between performance and accuracy when using different numbers of pieces to approximate the continuous distribution. Figure 13 demonstrates the trends of runtime and accuracy with the increase in pieces for different bitwidths for four benchmarks. As the number of linear pieces increases, runtime tends to first decrease and then increase. As the number of pieces increases, the accuracy tends to improve as shown by the lower four plots. This is due to the fact that as we increase the number of pieces, continuous distributions are replaced with more accurate bit blasted distributions. That accuracy improvement comes at the cost of increased runtime after a certain sweet spot. The appendix provides additional experiments that also justify the usage of piece-wise approximations over other approximations based on the central limit theorem.

6 RELATED WORK

Probabilistic programming has been an an active area of research both from the perspective of semantics and inference [Dahlqvist et al. 2023; Milch et al. 2005]. This section describes some closely related work and positions HyBit with respect to them. At a high level, the key distinction in HyBit is the development of bit blasting for succinct discretization of hybrid probabilistic programs.

Discretization approaches. Prior approaches that discretize continuous or hybrid probabilistic programs estimate the posterior by exhaustively enumerating all of the discretized values [Huang et al. 2021], which does not scale to provide sufficient accuracy in many cases. One prior discretization technique also employs a bit representation [Claret et al. 2013]. However, their approach is not

a form of bit blasting, since it is not succinct but rather still in general produces a representation that is proportional to the number of discretized points. Finally, a recent approach uses discretization to produce upper and lower bounds on the posterior of a probabilistic program [Beutner et al. 2022].

Inference algorithms for hybrid probabilistic programs. Other research specifically targets hybrid probabilistic programs. Leios [Laurel and Misailovic 2020] *continualizes* the hybrid probabilistic program in order to harness the power of existing continuous inference algorithms. HyBit, on the other hand discretizes the hybrid programs which helps in scaling inference for hybrid programs specifically with respect to the discrete structure. SPPL support hybrid programs by translating them to specific representations for that purpose [Saad et al. 2021]. However, these representations place constraints on the hybrid programs that can be supported, while HyBit can support arbitrary many more hybrid programs. Probabilistic logic programming languages have also been extended to support hybrid models through interval traces [Gutmann et al. 2011]. Further, there have been inference algorithms for hybrid domains in the context of Bayesian deep learning as well [Zeng and Van den Broeck 2023].

Algebraic approaches. Some PPL inference algorithms produce closed form algebraic expressions to encode probability distributions and then use symbolic techniques to perform exact inference [Gehr et al. 2016; Hur et al. 2014; Narayanan et al. 2016]. However, these systems are necessarily limited in their expressivity and the programs that they can handle, as shown in Table 2.

Path based inference algorithms. A common class of inference algorithms for PPLs are *operational*: they record traces on the program by using concrete values of the random variables. This includes sampling algorithms and variational approximations [Bingham et al. 2019; Carpenter et al. 2017; Chaganty et al. 2013; Dillon et al. 2017; Goodman et al. 2008; Hur et al. 2015; Kucukelbir et al. 2015; Mansinghka et al. 2013, 2018; Minka et al. 2014; Pfeffer 2007; Saad and Mansinghka 2016; Tristan et al. 2014; van de Meent et al. 2015; Wingate and Weber 2013; Wood et al. 2014]. Sampling algorithms like rejection sampling and MCMC methods are universal but have known limitations such as difficulty in handling multi-modality and low-probability evidence, as described in Section 2. More sophisticated techniques like Hamiltonian Monte Carlo and variational approximation address these limitations but impose constraints of continuity and almost-everywhere differentiability, so they must resort to marginalizing out all discrete structure.

Use of a binary representation bit blasting has been a widespread technique in software verification, used in constraint solvers to reason about arithmetic using a bit representation [Bruttomesso and Sharygina 2009]. Recent work in scaling inference for probabilistic programs over integers also employs a binary representation for numbers [Cao et al. 2023], in order to exploit conditional independences in that representation. The bit blasting in HyBit is inspired by these techniques but has a different purpose and hence a very different technical approach: to develop succinct, and in many cases provably sound, approximations of continuous probability distributions.

7 CONCLUSION AND FUTURE WORK

In this work, we motivated the need for new inference methods for hybrid probabilistic programs. We described *bit blasting*, whereby hybrid probabilistic programs are succinctly discretized and then analyzed using algorithms for discrete inference. We characterized a class of continuous densities — mixed-gamma densities — for which bit blasting is not only succinct but also sound relative to an explicit discretization approach as well as provably efficient to analyze. We then presented a new PPL HyBit that employs a novel inference algorithm for hybrid programs based on bit blasting. We demonstrated the performance benefits of HyBit over existing approximate inference algorithms.

In future work, we hope to expand the class of distributions that can be bit blasted soundly. We are also interested to explore the integration of HyBit with other inference approaches, to leverage their relative strengths for support of a wider range of hybrid probabilistic programs.

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