A GENTLE TUTORIAL ON GRAPH NEURAL NETWORKS AND ITS APPLICATION TO PROGRAMMING LANGUAGE

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Outline

Introduction



Graph Neural Networks

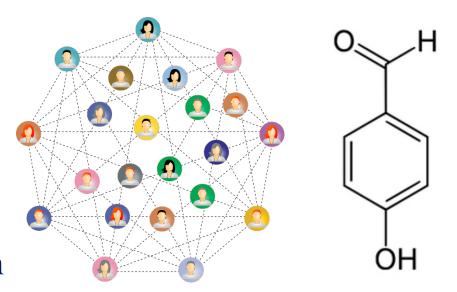
Downstream Tasks for Graphs

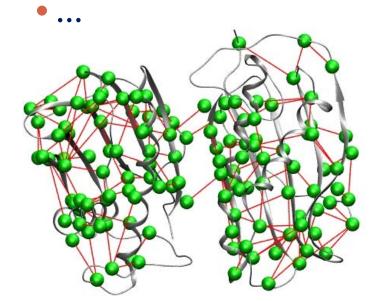
Applications in PL

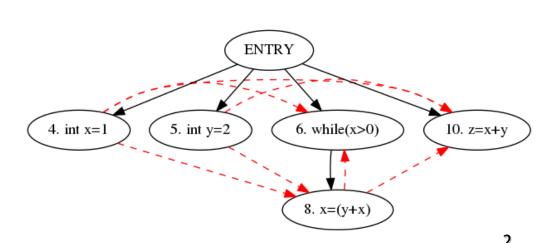
Discussions

Graph Analysis

- Graphs are ubiquitous
 - Social networks
 - Proteins
 - Chemical compounds
 - Program dependence graph

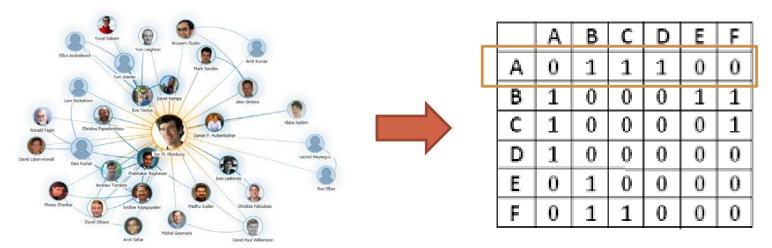






Representing Nodes and Graphs

- Important for many graph related tasks
- Discrete nature makes it very challenging
- Naïve solutions

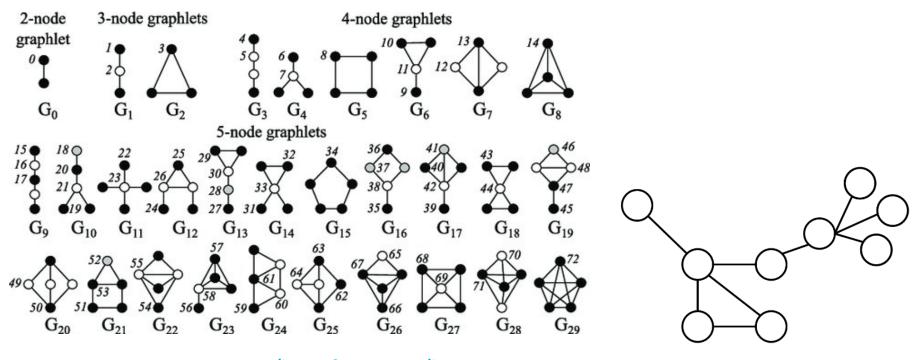


Limitations:

Extremely High-dimensional
No global structure information integrated
Permutation-variant

Even more challenging for graph representation

Ex. Graphlet-based feature vector



Source: DOI: <u>10.1093/bioinformatics/btv130</u>

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12	1	4	1	6	0	

Requires subgraph isomorphism test: NP-hard

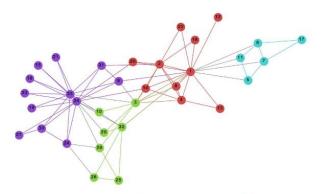
Source:

https://haotang1995.github.io/projects/robust _graph_level_representation_learning_using_g raph_based_structural_attentional_learning4

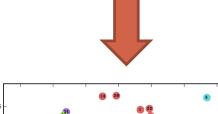
Automatic representation Learning

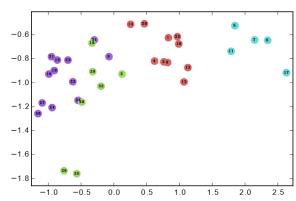
- Map each node/graph into a low dimensional vector
 - $\phi: V \to \mathbb{R}^d \text{ or } \phi: \mathcal{G} \to \mathbb{R}^d$
- Earlier methods
 - Shallow node embedding methods inspired by word2vec
 - DeepWalk [Perozzi, KDD'14]
 - LINE [Tang, WWW'15]
 - Node2Vec [Grover, KDD'16]

 $\phi(v) = U^T x_v$, where U is the embedding matrix and x_v is the one-hot encoding vector









(b) Output: representations

Source: DeepWalk

Limitation of shallow embedding techniques

- Too many parameters
 - Each node is associated with an embedding vector, which are parameters
- Not inductive
 - Cannot handle new nodes
- Cannot handle node attributes

From shallow embedding to Graph Neural Networks

- The embedding function (encoder) is more complicated
 - Shallow embedding
 - $\phi(v) = U^T x_v$, where U is the embedding matrix and x_v is the one-hot encoding vector
 - Graph neural networks
 - $ullet \phi(v)$ is a neural network depending on the graph structure

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Notations

- •An attributed graph G = (V, E)
 - V: vertex set
 - *E*: edge set
 - A: adjacency matrix
 - $X \in \mathbb{R}^{d_0 \times |V|}$: feature matrix for all the nodes
 - N(v): neighbors of node v
 - h_{v}^{l} : Representation vector of node v at Layer l
 - Note $h_v^0 = x_v$
 - $H^l \in R^{d_l \times |V|}$: representation matrix

The General Architecture of GNNs

For a node v at layer t

$$h_v^{(t)} = f\left(\underline{h_v^{(t-1)}}, \left\{\underline{h_u^{(t-1)}} | u \in \mathcal{N}(v)\right\}\right)$$

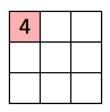
representation vector from previous layer for node v

representation vectors from previous layer for node v's neighbors

- A function of representations of neighbors and itself from previous layers
 - Aggregation of neighbors
 - Transformation to a different space
 - Combination of neighbors and the node itself

Compare with CNN

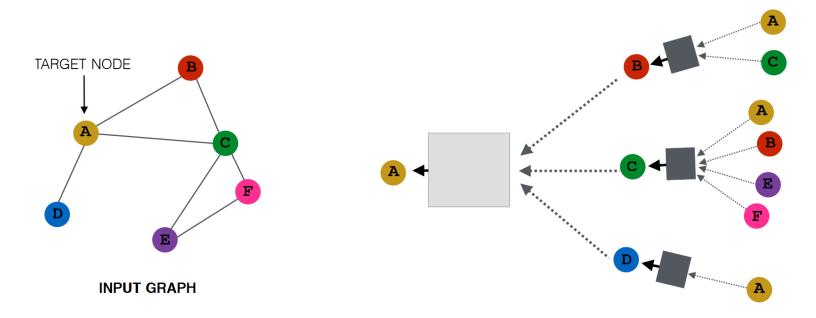
- Recall CNN
 - Regular graph
- GNN



Image

Convolved Feature

Extend to irregular graph structure



Graph Convolutional Network (GCN)

Kipf and Welling, ICLR'17

$$ullet f(H^{(l)},A) = \sigma\left(\hat{D}^{-rac{1}{2}}\hat{A}\hat{D}^{-rac{1}{2}}H^{(l)}W^{(l)}
ight), \widehat{A} = A + I$$

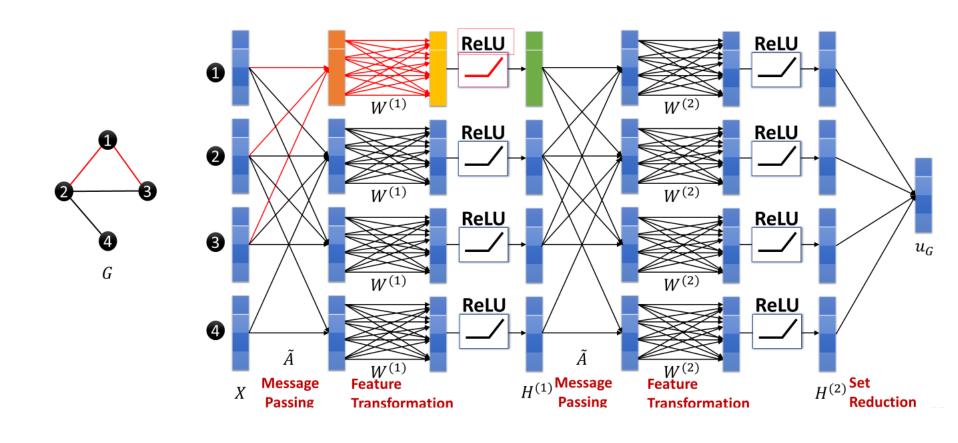
- f: graph filter
- From a node v's perspective

$$\mathbf{h}_{v}^{k} = \sigma \left(\mathbf{W}_{k} \sum_{u \in N(v) \cup v} \frac{\mathbf{h}_{u}^{k-1}}{\sqrt{|N(u)||N(v)|}} \right)$$

 W_k : weight matrix at Layer k, shared across different nodes

A toy example of 2-layer GCN on a 4-node graph

Computation graph



GraphSAGE

Inductive Representation Learning on Large Graphs

William L. Hamilton*, Rex Ying*, Jure Leskovec, NeurIPS'17

$$\mathbf{h}_{\mathcal{N}(v)}^{k} \leftarrow \text{AGGREGATE}_{k}(\{\mathbf{h}_{u}^{k-1}, \forall u \in \mathcal{N}(v)\})$$

$$\mathbf{h}_{v}^{k} \leftarrow \sigma\left(\mathbf{W}^{k} \cdot \text{CONCAT}(\mathbf{h}_{v}^{k-1}, \mathbf{h}_{\mathcal{N}(v)}^{k})\right)$$

A more general form

$$\mathbf{h}_{v}^{k} = \sigma\left(\left[\mathbf{W}_{k} \cdot \overline{\mathbf{AGG}\left(\left\{\mathbf{h}_{u}^{k-1}, \forall u \in N(v)\right\}\right)}, \mathbf{B}_{k}^{k} \mathbf{h}_{v}^{k-1}\right]\right)$$

More about AGG

Mean

$$AGG = \sum_{u \in N(v)} \frac{\mathbf{h}_u^{\kappa - 1}}{|N(v)|}$$

- LSTM $\left(\left[\mathbf{h}_{u}^{k-1}, \forall u \in \pi(N(v))\right]\right)$
 - • $\pi(\cdot)$: a random permutation

Pool

$$AGG = \gamma \left\{ \mathbf{Qh}_u^{k-1}, \forall u \in N(v) \right\}$$

• $\gamma(\cdot)$: Element-wise mean/max pooling of neighbor set

Message-Passing Neural Network

- Gilmer et al., 2017. Neural Message Passing for Quantum Chemistry. ICML.
- A general framework that subsumes most GNNs
 - Can also include edge information
- Two steps
 - Get messages from neighbors at step k

$$\mathbf{m}_v^k = \sum_{u \in N(v)} M(\mathbf{h}_u^{k-1}, \mathbf{h}_v^{k-1}, \mathbf{e}_{u,v})$$
 e.g., Sum or MLP

• Update the node latent represent based on the msg

$$\mathbf{h}_v^k = U(\mathbf{h}_v^{k-1}, \mathbf{m}_v^k)$$
 e.g., LSTM, GRU

Graph Attention Network (GAN)

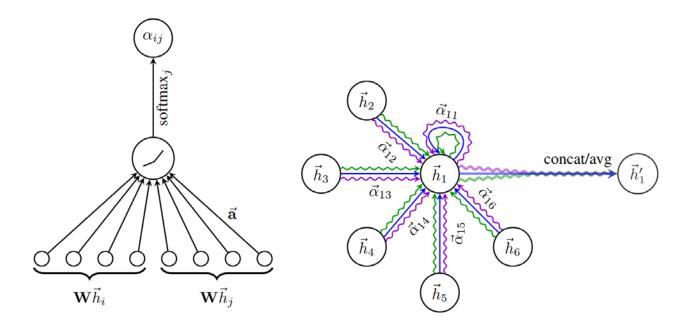
- How to decide the importance of neighbors?
 - GCN: a predefined weight
 - Others: no differentiation
- GAN: decide the weights using learnable attention
 - Velickovic et al., 2018. Graph Attention Networks. *ICLR*.

$$\vec{h}_i' = \sigma \left(\sum_{j \in \mathcal{N}_i} \alpha_{ij} \mathbf{W} \vec{h}_j \right)$$

The attention mechanism

Potentially many possible designs

$$\alpha_{ij} = \frac{\exp\left(\text{LeakyReLU}\left(\vec{\mathbf{a}}^T[\mathbf{W}\vec{h}_i \| \mathbf{W}\vec{h}_j]\right)\right)}{\sum_{k \in \mathcal{N}_i} \exp\left(\text{LeakyReLU}\left(\vec{\mathbf{a}}^T[\mathbf{W}\vec{h}_i \| \mathbf{W}\vec{h}_i]\right)\right)}$$

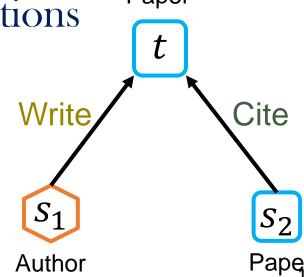


Heterogeneous Graph Transformer (HGT)

- How to handle heterogeneous types of nodes and relations?
 - Introduce different weight matrices for different types of nodes and relations

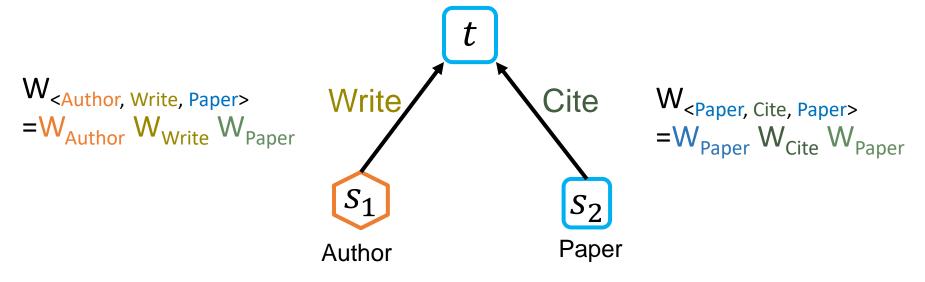
• Introduce different attention weight matrices for different types of nodes and relations

Hu et al., Heterogeneous Graph Transformer, WWW'20



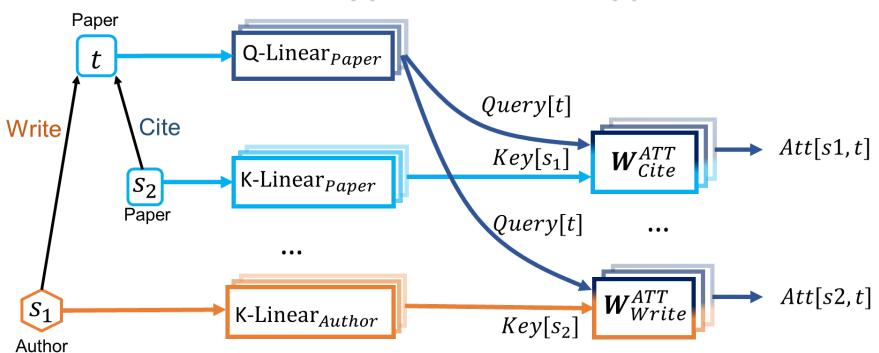
Meta-Relation-based Parametrization

- Introduce node- and edge- dependent parameterization
 - Leverage meta relation < source node type, edge type, target node type> to parameterize attention and message passing weight.



Meta-Relation-based Attention

 Attention learning is also parameterized based on node type and link type



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Typical Graph Functions

- Node level
 - Similarity search
 - Link prediction
 - Classification
 - Community detection
 - Ranking

- Graph level
 - Similarity search
 - Frequent pattern mining
 - Graph isomorphism test
 - Graph matching
 - Classification
 - Clustering
 - Graph generation

1. Semi-supervised Node Classification

- Decoder using $z_v = h_v^L$
 - Feed into another fully connected layer
 - $\bullet \, \hat{y}_v = \sigma(\theta^T z_v)$
- Loss function
 - Cross entropy loss
 - In a binary classification case
 - $l_v = y_v \log \hat{y}_v + (1 y_v) \log(1 \hat{y}_v)$

Applications of Node Classification

- Social network
 - An account is bot or not
- Citation network
 - A paper's research field
- A program-derived graph
 - The type of a variable

2. Link Prediction

- Decoder using $z_v = h_v^L$
 - Given a node pair (u, v)
 - Determine its probability $p_{uv} = z_u^T R z_v$
 - R could be different for different relation type
- Loss function
 - Cross entropy loss
 - $l_{uv} = y_{uv} log p_{uv} + (1 y_{uv}) log (1 p_{uv})$

Link Prediction Applications

- Social network
 - Friend recommendation
- Citation network
 - Citation recommendation
- Medical network
 - Drug and target binding or not
- A program-derived graph
 - Code autocomplete

3. Graph Classification

- Decoder using $h_G = g(\{z_v\}_{v \in V})$
 - $g(\cdot)$: a read out function, e.g., sum
 - Feed h_G into another fully connected layer
 - $\bullet \, \hat{y}_G = \sigma(\theta^T h_G)$
- Loss function
 - Cross entropy loss
 - In a binary classification case
 - $l_G = y_G \log \hat{y}_G + (1 y_G) \log(1 \hat{y}_G)$

Graph Classification Applications

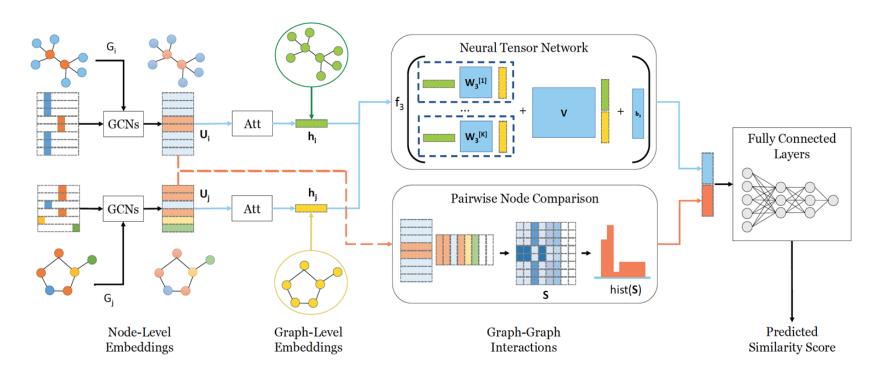
- Chemical compounds
 - Toxic or not.
- Proteins
 - Has certain function or not
- Program-derived graphs
 - Contains bugs or not

4. Graph Similarity Computation

- Decoder using $h_G = g(\{z_v\}_{v \in V})$
 - Given a graph pair (G_1, G_2)
 - Determine its score $s_{G_1G_2} = h_{G_1}^T R h_{G_2}$
- Loss function
 - E.g., Square loss
 - $l_{G_1G_2} = (y_{G_1G_2} s_{G_1G_2})^2$

A Concrete solution by SimGNN [Bai et al., AAAI 2019]

• Goal: learn a GNN ϕ : $G \times G \to R^+$ to approximate Graph Edit Distance between two graphs



- Attention-based graph-level embedding
- **2. Histogram** features from pairwise node similarities

Graph Similarity Computation Applications

- Drug database
 - Drug similarity search
- Program database
 - Code recommendation
 - Search ninja code for novice code
 - Search java code for COBOL code



Wanted urgently: People who know a half century-old computer language so states can process unemployment claims

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Deep Learning in PL

Programs as sequences

```
public class FooBar {
    int BAZ_CONST = 42;
}
```



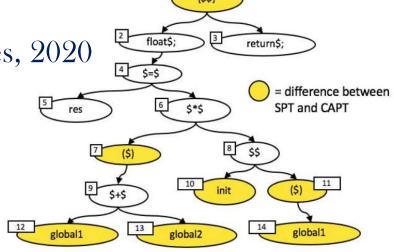
```
"public", "class", "CLASSO", "{", "int", "VARO", "=", "42", ";", "}"
```

Follow NLP techniques

```
float func()
{
    float res = (global1 + global2) * init(global1);
    return res;
}
```

Programs as trees

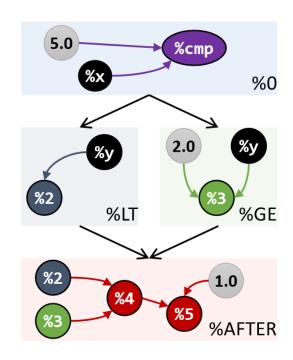
• Ye et al., Context-Aware ParseTrees, 2020

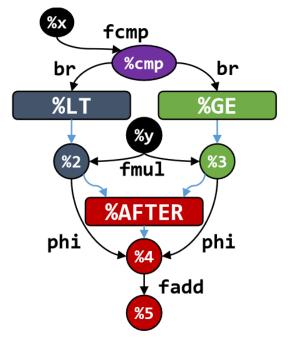


Programs as graphs

 Ben-Nun et al., Neural Code Comprehension: A Learnable Representation of Code Semantics, NeurIPS 2018

```
double thres = 5.0;
if (x < thres)</pre>
    x = y * y;
else
    x = 2.0 * y;
x += 1.0:
           (a) Source code
%cmp = fcmp olt double %x, 5.0
br i1 %cmp, label %LT, label %GE
LT:
  %2 = fmul double %v, %v
GE:
  %3 = fmul double 2.0, %y
AFTER:
  %4 = phi double [%2,%LT], [%3,%GE]
  %5 = fadd double %4, 1.0
             (b) LLVM IR
```





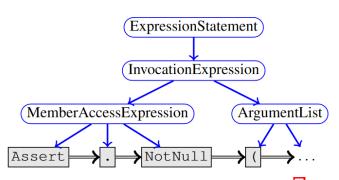
(c) Dataflow basic blocks

(d) Contextual Flow Graph

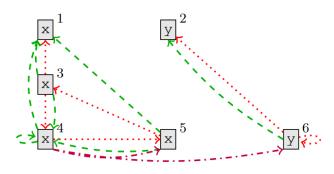
• Then shallow embedding: inst2vec

GNNs in PL

- Allamanis et al., Learning to represent programs with graphs, ICLR 2018
 - Tasks: (1) predict the name of a variable; (2) predict the right variable for a given location
 - Methodology: Gated GNN



(a) Simplified syntax graph for line 2 of Fig. 1, where blue rounded boxes are syntax nodes, black rectangular boxes syntax tokens, blue edges Child edges and double black edges NextToken edges.



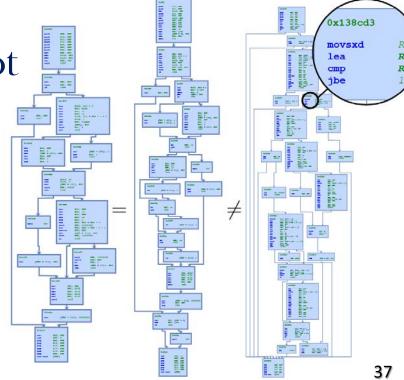
(b) Data flow edges for $(x^1, y^2) = Foo()$; while $(x^3 > 0) (x^4 = x^5 + y^6)$ (indices added for clarity), with red dotted LastUse edges, green dashed LastWrite edges and dashdotted purple ComputedFrom edges.

GNNs in PL (Cont.)

 Li et al., Graph Matching Networks for Learning the Similarity of Graph Structured Objects, ICML 2019

• Tasks: decide whether two functions are the same or not

 Methodology: extend message passing across different graphs Control flow graph for functions



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Open Questions

- How to represent programs into graphs?
 - Iyer, Sun, Wang, Gottschlich, Software Language Comprehension using a Program-Derived Semantic Graph, arXiv:2004.00768
 - Capture program semantics at many levels of granularity
 - A hierarchical graph

Open Questions

• Why GNNs work?

- Is the nonlinear transformation necessary?
- Chen et al., Are Powerful Graph Neural Nets Necessary? A Dissection on Graph Classification, arXiv:1905.04579
- A concatenate feature vector from graph propagation, followed by a MLP works equally well, and much faster!

$$X^G = \gamma(G, X) = \left[\boldsymbol{d}, X, \tilde{A}^1 X, \tilde{A}^2 X, \cdots, \tilde{A}^K X \right],$$

Q&A

- Thanks to my collaborators:
 - Yunsheng Bai, Wei Wang, Derek Xu, Hao Ding, Ting Chen, Ziniu Hu, etc...



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